

A
CORRELATION OF
REPEATED TENSION IMPACT TESTS
WITH
OTHER TENSION TESTS OF
OF
17ST DURALUMIN

Thesis

by

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SUMMARY

The strain distribution after repeated tension impacts along the length of several differently dimensioned specimens of 17ST Duralumin is determined for various energies per blow.

An attempt is made to determine a relationship between the energy available per blow, the dimensions of the specimen, and the number of blows required to cause failure of the specimen by repeated tension impacts.

A relationship is determined between the percent total elongation and the length-to-diameter ratio.

A relationship is determined between the energy per unit volume required to cause failure and the length-to-diameter ratio under static tension, dynamic tension, and repeated tension impact conditions.

A "Modulus of Destructiveness" is proposed for 17ST duralumin.

A method is presented for predicting the number of repeated tension impact blows necessary to cause failure of a part.

INTRODUCTION

Previous repeated tension impact investigations at the Guggenheim Aeronautical Laboratory, California Institute of Technology, have been made with three types of testing machine, namely Tinius Olsen-Izod, Matsumura, and falling carriage.

The falling carriage machine, designed by Coates and Beardsley (see ref. b) at the GALCIT, has been least used in these investigations. Olsen and Brown (see ref. d), the only investigators previously using it, reported the machine unsuitable for impact test velocities above six feet per second due to bending of the specimens.

The present authors modified the falling carriage machine to overcome the difficulty of specimen bending, and used this machine exclusively for tension impact tests.

Basically the machine (see figs. 1-a and 1-b) consists of a carriage which slides on vertical guides, its fall being stopped by a heavy anvil. Rebound of the carriage is prevented by two catches on the anvil. One end of a test specimen is screwed into the bottom of the carriage, and to the other end of the specimen is screwed a weight. The carriage is raised to a set height and let fall. It is stopped by the anvil which has a central hole through it. The weight on the specimen continues to fall through this hole after the carriage is stopped, exerting a tension impact blow on the specimen.

The height of fall of the carriage and the magnitude of the weight attached to the specimen determine the energy of the blow. Thus velocity of impact and available energy of impact may be varied independently of each other.

The carriage is raised by a trip hook attached to a motor driven endless chain. The hook is tripped by a cam, allowing the carriage to fall. Three such hooks are mounted on the chain, giving a rate of about five blows per minute when operated continuously. To prevent shock on pick up of the carriage, coil springs are inserted in the lifting element on the carriage.

Bending of the specimen was encountered in preliminary tests conducted by the authors, due to horizontal vibration of the weight after the carriage struck the anvil. To prevent this bending a ball and socket fixture was designed to mount on the bottom of the carriage (see fig. 1-c). The specimen is screwed into the ball element. To absorb rebound motion of the specimen and attached weight after fall, a rubber damping pad is mounted above the ball element which is flat on top.

The velocity of impact for all tests was maintained at 13.32 feet per second. Equipment was mounted on the testing machine for determining the acceleration of fall of the carriage. This equipment, employing an interrupted spark coil, provided a record of the position of the carriage at every thirtieth of a second of time during its fall. The result of repeated measurements by this means showed the acceleration of the carriage to be no measureable amount different from the acceleration of gravity. Hence the energy per blow was taken as the weight times the height of fall.

Load weights used in the tests included the following:

17.922 lbs.

11.923 "

7.923 lbs.

3.930 "

2.430 "

0.629 "

Any weight contributed to the impact energy by the specimen itself has been neglected in this investigation. The weight of the specimens used ranged from one-half to one and one-half ounces for the different sizes. The proportion of the specimen weight actually contributing to the tension impact blow is a questionable matter; even if all the specimen weight is considered as so acting, the quantity is negligible for the load weights used.

Six types of specimens (see Fig. 2) were used. These types are as follows:

<u>Type designation</u>	<u>Test section length</u>	<u>Test section diameter</u>
A	1.00 in.	0.300 in.
B	4.00 "	0.300 in.
C	8.00 "	0.300 in.
D	2.83 "	0.300 in.
E	2.83 "	0.178 in.
F	4.00 "	0.253 in.

The material of all specimens was 17 ST duralumin. After machining, specimens were polished to remove machining marks.

Fine scribe lines were placed at every tenth of an inch of length on the surface of the specimen by means of a razor blade. For placing the scribe lines a machine known as a comparator was used, having a screw driven head which moved the razor blade mount. The comparator

was also used to measure the elongations of the specimens, with a microscope mounted on the comparator head. Readings were taken from a micrometer connected to the screw shaft. Accuracy of results is believed to be within one-thousandth of an inch.

Two types of test other than repeated tension impact test were made for purposes of comparison. These were dynamic tension and static tension tests. The dynamic tension tests were carried out by the Impact Laboratory, California Institute of Technology, and consisted of breaking a specimen in tension by a single blow at a specified velocity of impact and recording the stress values versus time. From these data, a stress-strain curve for the specimen was obtained.

STRAIN DISTRIBUTION

The strain distribution on each of the specimens tested is shown graphically in Figs. 3 to 37 inclusive. The "a" curve of each figure shows the actual strain distribution or the unit elongation in each tenth of an inch. The "b" curve of each figure shows the total elongation up to each point in question and is really an integral curve of the corresponding "a" curve.

For plotting the total elongation curves, data were obtained by taking the accrued elongations at each scribe line. To obtain the unit elongation data at any point, the total elongation at that point was diminished by the total elongation at the previous point.

It may be noted that the unit elongation of the first tenth of an inch of each specimen appears on the graph sheet as negative in value. This elongation is actually positive; it is merely plotted below the horizontal axis due to the manner of measuring it. Rather than use the shoulder at one end of the specimen test length as a reference mark for all measurements, the first tenth of an inch scribe line from the shoulder was used as the reference mark. This afforded more consistent accuracy of measurement as the shoulder point was difficult to determine with accuracy, due to the fact that this point was badly out of focus in the microscope which was focused on the test section of the specimen. The elongation of the first tenth of an inch then appears negative only in direction from the reference line.

The elongation shown for the tenth of an inch increment at each end of a specimen is not considered to be as accurate as for the rest of the specimen owing to focus difficulties and to inexactness of machining.

The shapes of the strain distribution curves show considerable similarity. There are in general three different phases of strain distribution resulting on each specimen from repeated tension impacts. These can perhaps best be seen in Fig. 21-a wherein the distribution after each blow has been plotted. After blows 1, 2, and 3 the distribution remains quite uniform, with regular displacement upward, the amount of displacement decreasing only slightly with increasing number of blows. This phase of uniform distribution holds for 25% of the total number of blows to break in this particular case, but the average of all specimens tested shows this phase to hold for about 35% of the total number of blows to break.

After the fourth blow (Fig. 21-a) we find that the ends of the specimen did not elongate at all but that the central portion suffered elongation much more severe than previously, with the result that the increase in total elongation as shown in Fig. 21-b remains nearly the same as before. The next, or fifth, blow shows similar results except that the distribution is reversed, the central portion holding steady while the ends elongate excessively. The portions which previously elongated had increased yield strength due to the cold working and hence did not elongate. The sixth blow shows the same effect except that here the elongation occurs in four regions, one at each end and one about one-third of the length from each end. Subsequent blows show the same tendencies with the regions where elongation occurs moving back and forth along the length of the specimen but always quite symmetrical about the center of the specimen. The average unit and the total elongations show a fairly uniform increase in magnitude until necking begins.

The third or necking phase begins just before the specimen breaks and is characterized by excessively high unit elongation over a short length of the specimen. This necking and subsequent break usually occur near one end of the specimen but in a few cases occur in the central region. There seems to be no way of predicting at which end of the specimen the break will occur since there is almost invariably a similar necking of only slightly lesser magnitude occurring at the opposite end. Fig. 20-a perhaps shows this property best. In this instance there was an actual crack part way through the specimen at the end opposite to the break. For an average of all specimens tested the necking phase occurs during the last 20% of the blows.

To summarize, the strain distribution falls into the following three phases:

1. Uniform distribution for first 35% of the blows.
2. Symmetrical variably located local elongation for the next 45% of the blows.
3. Extremely localized necking for the last 20% of the blows.

Energy wave propagation theory (see ref. n) would indicate a marked increase in stress as evidenced by higher unit elongation near each end of the specimen due to the reflection and consequent reinforcement of the energy waves in the specimen at these points. In most of the specimens this tendency is not evidenced to any considerable extent in the first few blows, a fairly uniform distribution being obtained for the first 35% of the blows as mentioned above. However, in the second and third phases the higher end elongations usually become evident. For specimens D and E this phenomenon appears even in the first phase.

The strain distributions on the specimens subjected to static tests and to dynamic tests were observed. These distributions, shown in graphical form in Figs. 38 to 49 inclusive, are all seen to be of the same general order as for the final blow of the repeated impact specimens. The unit strain level is approximately constant along the length except in the region where necking occurs. This leads to the conclusion that the general strain distribution is not materially altered by the method of testing, except for the energy wave reflection effects in the repeated impact cases.

The maximum unit elongations in the necking region vary somewhat with the three methods of testing. In general, comparing particular groups of specimens, we find the static tests to give the lowest, and the repeated impact tests to give the highest maximum unit elongations, with the value for the dynamic tests falling roughly midway between the other two methods. The average maximum unit elongations are as follows:

By static tests 45.5%

By dynamic tests 54.0%

By repeated tension impact tests. 52.0%

Only slight variation in total elongation after failure with method of testing is evidenced. The average values (see Table III) show repeated impact tests to give an elongation of 15.9%, static tests 15.0%, and dynamic tests 16.8%. However, these results vary so widely between types of specimen that they are not at all conclusive.

Examination of the necking length shown in figures 3-a to 37-a inclusive indicated that in all cases the average length of specimen affected by necking was approximately 1.67 d. On this premise we are led directly to the conclusion that there is a relationship between the

length-to-diameter (l/d) ratio and the total elongation. As the total length of the specimen is decreased and approaches 1.67 d, the necking length becomes a greater portion of the whole length, and consequently the average percent total elongation should increase. As the length of the specimen increases and approaches infinity, the necking length should have less and less effect, so that the average total elongation should reach some practically constant value for large l/d ratios. This effect is experimentally verified by comparison of the average total elongations of the various specimens which are plotted against l/d ratio in Fig. 63. These experiments, however, do not extend to high enough l/d ratios to indicate precisely the asymptotic value reached by the total elongation but it will probably be in the neighborhood of 11%. Neither do they extend low enough to indicate what variation may be expected at or below a length of 1.67 d.

It may be of interest to point out what effect the scribe marks had on determining the location of the final fracture. In all cases for the static and the dynamic tests except one the fracture occurred at a scribe mark; i.e., the edge of the fracture contained the scribe mark. In the repeated impact tests there were many instances where the break occurred between scribe marks. This would tend to indicate that the specimens are generally less sensitive to surface irregularities or notch effects under repeated tension impact tests than under either static or dynamic tests.

Variation of Number of Blows to Break with Dimensions
of Specimen and with Energy Available per blow.

Previous investigations, Ref. b, c, and d, have shown that the number of blows required to break a given specimen, N , varies inversely as the energy available per blow, E_A . Theoretical considerations indicate that the number of blows at a given energy per blow would vary directly with the volume of the specimen. To investigate the effect of volume change and of relative dimension changes a series of tests was conducted for which the specimens were chosen as follows:

(a) Specimens A, B, C, and D to have the same diameter and cross sectional area but to have lengths of 1, 4, 8 and 2.83 inches respectively. Hence, the volumes and the length-to-diameter ratios (l/d) vary directly as the lengths.

(b) Specimen E to have the same volume as Specimen A but to have the same length as Specimen D.

(c) Specimen F to have the same volume as Specimen D but to have the same length as Specimen A.

The following table gives the most important dimensional properties of the series of specimens.

<u>Specimen letter</u>	<u>Diameter, d, in.</u>	<u>Area, A, sq. in.</u>	<u>Length, l, in.</u>	<u>l/d</u>	<u>Volume in.³</u>
A	0.300	0.0707	1.00	3.33	0.0707
B	0.300	0.0707	4.00	13.33	0.2828
C	0.300	0.0707	8.00	26.67	0.5656
D	0.300	0.0707	2.83	9.42	0.2000
E	0.178	0.0249	2.83	15.90	0.0707
F	0.252	0.0409	4.00	15.87	0.2000

Table I gives comparisons showing the effect of the variations of the above dimensions on the number of blows required to break. The following effects are apparent:

(a) With the diameter and cross sectional area constant, the number of blows increases with the length of the specimen.

(b) With length constant, the number of blows varies directly with the cross-sectional area.

(c) With the volume constant, the number of blows remains constant. One group of specimens does not agree with this statement; however, the other group does, and this, together with the comparisons of (a) and (b) above, indicates this statement to be true. It should be noted that between the A and the E specimens there is a radical change in l/d ratio. This would seem to indicate that the l/d ratio might have some influence on the result.

From this comparison we may derive the general conclusion that the number of blows to break varies almost directly with the volume of the specimen, but that there is some indication that the number of blows may also vary inversely as the l/d ratio.

Following the lines of attack of previous investigators at the GALCIT the values of N , E , and N/E were calculated in Table II. Curves of E vs. N and of N/E vs. N were plotted as shown on Fig. 59. These curves showed the same general forms as indicated in reference (b).

The values of E vs. N , E vs. N/V and E vs. N/EV were then plotted on log-log coordinate paper as shown in figures 60 to 62 respectively. The first, E vs. N , showed roughly parallel curves. The E vs. N/V plot showed a wide scatter of points through which no definite curves

could be faired. However, the plot of E vs. N/EV showed a linear form with not too great a variation from an average value. The equations for the median line and for the boundary lines indicated by the test points were worked out as shown on the figure. From these, equivalent equations for the relations between E and N/V were derived and plotted on Fig. 61. The lines thus determined include all the test data satisfactorily and it is believed that they might be used in predicting the number of blows to break for a given volume of material. However, it is not felt that such predictions would be sufficiently accurate to justify their use. As a typical example, at energy level of 8 ft.lbs. per blow, the mean line would predict 200 blows per cubic inch, whereas the limits indicate it might break in as few as 80 blows or it might hold through 430 blows.

Such a series of comparisons or predictions then seems to be too far outside the desired limits of accuracy to be worth while. However, to determine approximately the order of magnitude of the number of blows to be expected, the following equation might be used:

$$N = 2630 \frac{V}{E^{1.25}}$$

where N = number of blows to break

V = volume, in cubic inches

E = energy available per blow, in ft. lbs.

However, it should be used only to determine the order of magnitude and even this may not be a close value.

Correlation of Repeated Impact, Static and Dynamic
Stress-Strain Data

Since the above calculations attempting to relate the Volume, Number of blows and the Energy Available per blow do not produce any correlation enabling an accurate prediction of blows to break, an attempt was made to determine such relations by correlation of Repeated Tension Impact data with data from static stress-strain curves of the material.

The area under a force-total elongation diagram represents energy in units of inch pounds for example. Similarly the area under the corresponding stress-strain diagram represents energy per unit volume, or simply energy when multiplied by the volume of the specimen. A typical stress-strain curve, Fig. 50, was obtained for a specimen of 17ST and this curve was used in making all the following calculations.

One assumption is made in the following analysis which the authors have not verified experimentally but which they believe leads to no significant error in the analysis. This assumption is that when the load is completely removed at any time after the yield point has been reached, the specimen will unload along a straight line exactly parallel to the slope in the elastic range; and that when the load is reapplied the specimen will load up again following the exact same line until it intersects the original stress-strain curve, and will then follow the original stress-strain curve. This assumption is more or less justified by references (b) and (p) wherein this effect is shown to be approximately as stated.

One other assumption is made; that the static stress-strain curve we are using is not changed appreciably by the rate of application of load, at least in the low speeds (about 13.3 ft. per. sec.) here en-

countered. This assumption is justified by reference (k) and is further verified by tests to be discussed later.

The first attempt at analysis was made by taking the total kinetic energy available per blow, $1/2 MV^2$, and laying out its equivalent area under the stress-strain curve, determining from this a maximum stress and a maximum strain encountered during the blow. Using the above assumptions, the energy recovered during unloading of the specimen was calculated. The difference between these quantities was considered to be the plastic energy delivered to the specimen per blow. This process was repeated for subsequent blows until the last repetition took the values to the end point of the static stress-strain curve. The number of times this process was repeated was assumed to be the number of blows required to break the specimen. However, comparison with actual tests showed this number to be much less than the number actually required to break.

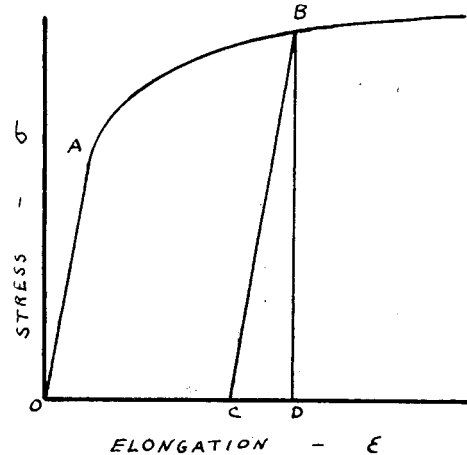
Any practical considerations must lead to the conclusion that not all of the kinetic energy of such a machine could be transferred to a specimen without losses of any kind. The above calculations verified this conclusion. The problem then became one of determining the amount or percentage of the energy of each blow which was transferred to the specimen. The key to finding this percentage of energy transferred to the specimen lies in the above discussion of strain distribution.

In the previous discussion we saw that the unit elongations are quite constant for about the first 35% of the blows. Hence we can pick an average percent elongation from the unit elongation charts or determine an average percent elongation by dividing the total elongation by the gage length. If the values for one blow are not given it will be

sufficiently accurate to take the percent elongation for the least number of blows shown and divide this by the number of blows.

By the above method we locate the specimen on the stress-strain diagram at the zero stress level, point "C" on the accompanying figure.

Then using the above unloading assumptions, draw CB parallel to OA, determining point "B" on the stress strain curve. Drop BD vertically to the strain axis. Then the area OABDO represents the energy



per unit volume transferred to the specimen in the first blow. The ratio of this energy, which we shall call E_1 , to the total kinetic energy per blow per unit volume, $E_A = 1/2 MV^2 \div \text{vol.}$, represents the energy transfer ratio for this particular specimen. Let us call this ratio K_1 .

It is to be expected that K_1 should have a value less than unity. It seems possible that this K_1 might actually be a constant for all weights and all specimens although it might vary with either.

Calculations of K_1 for each specimen tested, Column 11, Table III showed that it varied from 0.614 to 1.865. Only one set of specimens, the L specimens, showed the remarkable property of an energy transfer greater than unity. Eliminating this entire set of specimens we find the average K_1 to be 0.800 with individual values ranging from 0.614 to 0.971. Only 5 of these are below 0.700 and only 6 above 0.900, the remaining 20 being within 12.5% of the mean value. It is believed that this value may be within the limits of accuracy of the experiments

and that this energy transfer constant may be taken as 0.800.

As for the extreme variation of K_1 shown by the E specimens there is no completely satisfactory explanation apparent. Since it occurs generally for all the E specimens, the magnitude reaching a peak at one mass and decreasing with both greater and lesser masses, it seems to indicate a resonant vibrating condition. It is probable that the falling carriage itself tends to vibrate vertically after striking the anvil. We know that the weight on the end of the specimen vibrates vertically after the carriage strikes the anvil. It therefore seems highly possible that with the right combination of masses and with the right "effective spring constant" in the form of a particular specimen, the carriage may be vibrating upward with a very high acceleration while the mass on the end of the specimen is still moving downward, thereby applying momentary high stresses to a properly shaped specimen so as to result in excessive elongations. This suggestion is offered as a possible explanation for the extreme variation of K_1 shown by the E specimens. This resonant property may depend on volume and the l/d ratio, but it does not depend on the l/d ratio alone since the F specimens which have almost the same l/d ratio as the E specimens exhibit none of these peculiarities.

The area CBDC of the above sketch, the elastic energy recovered in unloading, was next calculated for all specimens. This elastic energy per unit volume per blow was subtracted from the total energy per unit volume transferred to the specimen per blow, giving the plastic energy per unit volume transferred to the specimen per blow. For a first approximation it was assumed that this same amount of plastic energy is

absorbed by the specimen on each subsequent blow. This amount of energy was then multiplied by the number of blows to break and the total energy per unit volume required to break the specimen was obtained as shown in Column 14, Table III.

The above assumption of constant plastic energy per blow does not appear to be quite exact because of the fact that as greater elongations are reached, a greater percentage of the total energy transferred is recovered as elastic energy in unloading due to the constantly increasing yield point. This variation should be particularly noticeable on specimens having very short elongations on the first blow, say less than 1%. A more exact method of procedure would be to repeat the above calculations and determine the exact amount of plastic energy transferred in each blow. This might give slightly lower total energies, but it is not felt that such refinement in technique is required at the present stage of the investigations.

For most of the specimens this value of total energy per unit volume to break remained fairly constant for each type of specimen. However, between types of specimens there seemed to be considerable variation. Thus a variation of total energy per unit volume with specimen dimensions was indicated. It was felt that possibly the actual static stress-strain curves of each particular type of specimen might exhibit variations which could explain these irregularities. Also it seemed desirable to make static tension tests of each specimen to see if it had been sufficiently accurate to use this particular curve as an average curve on which all calculations were based.

The results of these static tests are plotted in Figs. 50 to 55 inc. A comparative plot of all the static curves from these figures is shown in Fig. 56. It is evident that for all practical purposes and within the limits of accuracy of these tests these curves can be considered to coincide in the region up to the ultimate stress. After the ultimate stress is reached and the specimens start to neck there is a marked variation in the curves depending primarily on the l/d ratio, the higher l/d ratios generally showing smaller final average elongations as is to be expected. One of the F curves and the B curve do not follow this prediction exactly, possibly due to experimental errors. This particular F specimen, however, was made from a different bar than the other specimens which may account for its irregularity.

To determine exactly the effect of velocity on these specimens a dynamic tensile test of each type of specimen was made at an initial velocity of loading of 15.3 ft. per. sec. Since this is an extremely low velocity for this type of testing the velocity could not be considered as constant during the test. However, any variation would only make the conditions approach more closely those of the repeated impact tests. The dynamic stress-strain curves for these tests are plotted with the corresponding static curves on figures 50 to 55 inclusive. A comparative plot of all these dynamic curves is shown in fig. 57. For individual specimens there is no marked or consistent difference between the static and the dynamic curves. A comparison of the comparative plots of the static and the dynamic curves shows that within the limits of accuracy of these tests the static and the dynamic stress strain curves are identical up to the ultimate stress.

Comparing our typical stress-strain curve, fig. 58, with figures 56 and 57, we see that although it is perhaps not the best average curve of the group it is everywhere within the region covered by the curves of our tests. It is therefore considered that the above calculations based on this typical curve are reasonable and sufficiently accurate.

As a further means of comparison, the energies per unit volume to break were calculated for each type of specimen from the static and the dynamic stress-strain curves. The unit energies thus obtained are compared with the averages of the unit energies calculated by repeated impact tests for each specimen in Table IV. This Table brings out the fact that the unit energy at which failure occurs is roughly constant no matter what type of loading is applied. However, this unit energy to break varies considerably between specimens, indicating a possible variation with the dimensions of the specimen. The variations within each type of loading are of approximately the same magnitude, indicating that the repeated impact calculations approach the same accuracy as the static or dynamic stress-strain measurements. However, the average of these values for the type of testing showed the repeated impact values to be about 15% higher than the average of the other two types of testing.

It was decided to investigate the results of calculations based on the above mentioned assumptions using blows other than the first blow. Accordingly Table III was completed from columns 16 to 34 inclusive. This method is the same as for the calculations based on the first blow.

Mention should here be made of the fact that a maximum tensile stress of 59500 lbs. per square inch was chosen for uniformity, which value was said to occur for all elongations greater than 12.3%. Consequently when the elongation after the blow was shown to be greater than 11.7% the E'_n (column 26 of Table III) was obtained directly as the product of this ultimate stress and the change in percent elongation.

The K'_1 values obtained (Column 30, Table III) are seen to be much more uniform than the K_1 values obtained from the previous calculations (column 11). Furthermore, the average is higher than before. Averaging all values gives K'_1 of 0.861, the average for particular groups ranging from 0.811 to 0.917. The maximum variation for individual tests is from 0.703 to 0.996 with only one exception. This exception is the K'_1 of 0.195 shown for specimen E-2, and this can be explained easily by the fact that practically none of the energy of the second or last blow was used in deforming the specimen. Fig. 29-b shows this fact clearly.

It should be noted that the E specimens which previously gave values of K_1 in excess of unity show normal values for K'_1 . The resonant vibrating effect apparently disappears after the first blow in which the length is changed so that the critical l/d-volume combination no longer exists.

The plastic energy per cubic inch absorbed per blow was calculated in column 31. From this the total energy per unit volume to break was calculated in column 32. Since all of the energy of the last blow was probably not used in deforming the specimen, the total energy for one blow less than failure was also calculated as shown in column 33. In

In the cases marked "*" only two blows were required to break and the total energy to break is obtained directly by adding the plastic energies for each blow. In all other cases the strain distribution curves were examined to estimate how much of the energy of the last blow was used in deforming the specimen. These considerations led to the "Considered Average" of total energies per cubic inch to break as shown in column 34.

Examination of this quantity reveals that there is an even more marked constancy within groups of specimens than was observed by the previous calculations, column 14. The variation between groups was here more clearly evident and seemed to vary with the $1/d$ ratio. The average of this unit energy for each type of specimen was plotted against $1/d$, as shown in Fig. 64. This plot approximates the hyperbolic form expected, but the variations are rather high.

The curves of E vs. $1/d$ and of ϵ vs. $1/d$, Figs. 63 and 64 respectively, were compared. The similarity between the two curves was quite striking and immediately suggested the possibility that the quotient of the two quantities, E and ϵ , might be a constant. The resultant quantity, inch pounds per cubic inch for one percent elongation, is calculated for each specimen as shown in column 37. The constancy of this quantity is here quite evident, both within groups and between groups of specimens. The weighted average value of this quantity is 583 in. lbs./cu.in. for 1% elongation for this type of test.

It was felt desirable to investigate this same quantity for the static and dynamic tests. This was done by dividing the total energy per cubic inch to break by the final percent total elongation for each

specimen so tested. The results are shown in comparative form in Table VI from which it is apparent that this quantity is approximately constant regardless of the size or the shape of the specimen or the type of tension testing to which the specimen is subjected. This quantity appears to be a characteristic property of the material. We give this quantity the name of "Modulus of Destructiveness", with a value of 650 in.lbs./in.³ for one percent elongation for 17ST Duralumin.

Probably the more basic units for this Modulus would be in.lbs./in.³ for 100% elongation, or $\frac{\text{in.lbs./in.}^3}{\text{in./in.}}$ or lbs./in.². This would give the Modulus a numerical value of 55,000 lbs./in.². This brings out the fact that this Modulus is really an average stress on the stress-strain curve, which average holds for all types of tensile tests and for all sizes and shapes of specimens having circular cross sections.

By use of this Modulus of Destructiveness the total energy required to cause failure in tension of a given part of 17ST can be determined as follows:

1. Multiply the Modulus of Destructiveness by the volume of the part, obtaining the inch pounds of energy required to elongate the specimen one percent of its original length.
2. Multiply this energy by the percent total elongation at break determined from Fig. 63, obtaining the total inch pounds of energy required to break the part.

The number of Repeated Tension Impact blows which will cause failure of a given part can be predicted as follows:

1. Determine the inch pounds of energy required to break the part by the method shown above.

2. Subject the part to a few repeated tension impacts, measuring the total elongation suffered after each blow.
3. Determine the plastic energy delivered to the part per blow by use of a typical static stress-strain diagram for 17ST by the method previously described.
4. Divide this plastic energy per blow into the total energy at break, obtaining the number of blows required to cause failure.

It must be emphasized that this method of analysis is known to be valid only for 17ST duralumin, for a number of blows below about 130, and at an impact velocity of about thirteen feet per second. It is believed that variations in impact velocity will not affect the method or the results for 17ST. For a number of blows greater than about 130 the conditions begin to approximate those for no plastic energy per blow, and the failure seems to become of a different nature, resembling a fatigue failure. In specimens C-4 and C-5, Figs. 17 and 18, the only two specimens tested to over 130 blows, the break occurred as a fatigue break at the fillet rather than as a normal tension break in the body of the specimen. For a number of blows greater than 130 this method of analysis may then not be valid. Furthermore it appears doubtful whether this method could be applied to other materials which have marked changes in properties with rate of loading. .

CONCLUSIONS

The following conclusions are determined for 17ST Duralumin with velocity of impact of 13.3 feet per second or less:

1) The strain distribution due to repeated tension impacts assumes the following forms as the number of blows is increased until the specimen breaks:

- a) Nearly uniform unit elongations for about the first 35% of the blows.
- b) Symmetrical variably located local elongations for the next 45% of the blows.
- c) Highly localized necking for the last 20% of the blows.

2) The maximum unit elongation at the break by repeated tension impact is 36% greater than that caused by static tension break, and 15% greater than that caused by dynamic tension break.

3) The total elongation for both static and dynamic tension failure varies less than 6% from that for repeated tension impact failure.

4) An approximately hyperbolic relationship exists between the length-to-diameter ratio and the total elongation suffered by a round specimen at failure in tension for length-to-diameter ratios varying from 3 to 27.

5) No exact relationship was found between the dimensions of a specimen, the energy available per blow, and the number of blows to cause failure by repeated tension impacts.

6) An approximately hyperbolic relationship exists between the length-to-diameter ratio and the total energy per unit volume required to break a round specimen in tension, for length-to-diameter ratios varying from 3 to 27.

7) A "Modulus of Destructiveness", defined as the energy per unit volume per percent elongation at tension failure, is proposed. Its value as determined in this investigation is 550 inch pounds per cubic inch for one percent elongation. This value is nearly the same for tension failures of static, dynamic, or repeated impact types.

8) The number of repeated tension impacts which will cause failure of a given part can be predicted quite closely from the following data:

- a) The percent total elongation at failure in tension as herein determined from specimen dimensions.
- b) A typical static stress-strain curve of the material.
- c) The percent increase in total elongation caused by one impact blow of the type to which the part will be subjected.

The validity of results is not certain if the number of impacts predicted exceeds 130.

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- n. Timoshenko, S.: Strength of Materials, Part II.

TABLE I

Blows Required to Break

Area = constant = .0707 in²

Specimen	Length in.	Energy Available per blow - ft. lbs.					
		49.7	33.05	21.92	10.87	6.74	1.74
C	3	12	13	32	180	--	--
B	4	6	10	15	53	127	--
D	2.83	3	6	8	22	--	--
A	1	2	3	5	10	22	--

Volume = constant = .0707 in³

Specimen	Length in.	Energy Available per blow - ft. lbs.					
		49.7	33.05	21.92	10.87	6.74	1.74
A	1	2	3	5	10	22	--
E	2.83	1	2	2	4	7	71

Volume = constant = .200 in³

Specimen	Length in.	Energy Available per blow - ft. lbs.					
		49.7	33.05	21.92	10.87	6.74	1.74
D	2.83	3	6	8	22	--	--
F	4	4	6	7	24	--	--

Length = constant = 2.83 in

Specimen	Area sq. in.	Energy Available per blow - ft. lbs.					
		49.7	33.05	21.92	10.87	6.74	1.74
D	.0707	3	6	8	22	--	--
E	.0249	1	2	2	4	7	71

Length = constant = 4"

Specimen	Area sq. in.	Energy Available per blow - ft. lbs.					
		49.7	33.05	21.92	10.87	6.74	1.74
B	.0707	6	10	15	53	127	--
F	.0499	4	6	7	24	--	--

TABLE II

1	2	3	4	5	6	7	8	9
Specimen Number	Weight	N Blows to Break	E Energy available Per Blow ft. lbs.	E _T Total Energy to Break E x N ft. lbs.	N/E	V Volume in. ³	N/V	$\frac{N}{E \cdot V}$
A-1	17.922	2	49.70	99.4	.0403	.0707	28.3	.560
A-2	11.923	3	33.05	99.1	.0907	.0707	42.4	1.283
A-3	7.923	5	21.92	109.7	.228	.0707	70.7	3.225
A-4	3.930	10	10.87	108.7	.920	.0707	141.3	13.02
A-5	2.430	22	6.74	148.2	3.265	.0707	311.0	46.20
A-6	0.629	-	1.74	-	-	.0707	-	-
B-1	17.922	6	49.70	298.0	.121	.2828	21.2	.428
B-2	11.923	6	33.05	198.2	.182	.2828	21.2	.642
B-5	11.923	11	33.05	353.5	.333	.2828	38.8	1.178
B-8	11.923	11	33.05	353.5	.333	.2828	38.8	1.178
B-9	11.923	9	33.05	297.5	.273	.2828	31.8	.962
B-3	7.923	15	21.92	329.0	.684	.2828	53.0	2.415
B-4	3.930	20	10.87	217.2	1.84	.2828	70.7	6.50
B-6	3.930	86	10.87	935.0	7.91	.2828	303.5	27.95
B-7	2.430	127	6.74	856.0	18.87	.2828	449.0	66.70
C-1	17.922	12	49.70	596.0	.242	.5656	21.2	.427
13	17.922	12	49.70	596.0	.242	.5656	21.2	.427
C-2	11.923	18	33.05	595.0	.545	.5656	31.8	.960
11	11.923	22	33.05	707.0	.666	.5656	38.9	1.178
C-3	7.923	32	21.92	702.0	1.46	.5656	56.5	2.575
12	7.923	44	21.92	964.5	2.01	.5656	77.8	3.55
C-4	3.930	182	10.87	1978.0	16.75	.5656	321.0	29.55
C-5	3.930	178	10.87	1934.0	16.38	.5656	314.0	28.90
D-1	17.922	3	49.70	149.0	.0605	.2000	15.0	.303
D-5	17.922	3	49.70	149.0	.0605	.2000	15.0	.303
D-2	11.923	6	33.05	198.2	.1814	.2000	30.0	.907
D-3	7.923	8	21.92	175.6	.365	.2000	40.0	1.825
D-4	3.930	24	10.87	261.0	2.21	.2000	120.0	11.05
D-6	3.930	20	10.87	217.0	1.84	.2000	100.0	9.20
E-1	17.922	1	49.70	49.7	.0202	.0707	14.1	.286
E-2	11.923	2	33.05	66.1	.0605	.0707	28.3	.856
E-3	7.923	2	21.92	43.8	.0912	.0707	28.3	1.29
E-4	3.930	4	10.87	43.5	.368	.0707	56.6	5.20
E-5	2.430	7	6.74	47.1	1.039	.0707	99.0	14.70
E-6	0.629	71	1.74	123.5	40.8	.0707	1003.0	578.0
F-1	17.922	4	49.70	198.8	.0807	.2000	20.0	.403
F-2	11.923	6	33.05	198.2	.1814	.2000	30.0	.907
F-3	7.923	7	21.92	153.6	.319	.2000	35.0	1.595
F-4	3.930	24	10.87	261.0	2.21	.2000	120.0	11.05

TABLE IV

Energy Per Unit Volume to Break
inch pounds per cubic inch

Specimen	l/d	Static Test	Dynamic Test	Repeated First Calculation	Impact Test Considered Average	Weighted Average
A	3.33	11204	13970	13076	13440	12872
D	9.42	--	10098	7535	7688	8390
B	15.33	6716	8780	10598	8678	8058
F	15.87	7345	5088	9212	9150	7194
E	15.90	8640	9628	10158	6278	8132
C	26.67	9070	6062	10882	7300	7144
Average	--	8596	8938	10210	8632	8665

TABLE V

Total Elongation After Failure - Percent

Specimen	l/d	Static Test	Dynamic Test	Repeated Impact Test	Weighted Average
A	3.33	20.0	21.5	24.9	23.7
D	9.42	-	17.7	14.3	14.7
B	13.33	15.5	17.0	17.6	16.4
F	15.87	14.0	11.1	16.1	14.8
E	15.90	16.2	17.0	12.5	13.5
C	26.67	14.6	11.9	12.2	12.5

TABLE VI

Modulus of Destructiveness
inch pounds per cubic inch for one percent elongation

Specimen	Static Test	Dynamic Test	Repeated Impact Test	Weighted Average
A	530	649	540	558
B	434	516	522	521
C	621	510	554	629
D	--	620	542	553
E	533	568	508	519
F	487	458	570	534
Weighted Average	526	554	553	549



Fig. 1-a
GALCIT Falling Carriage Type
Repeated Tension Impact

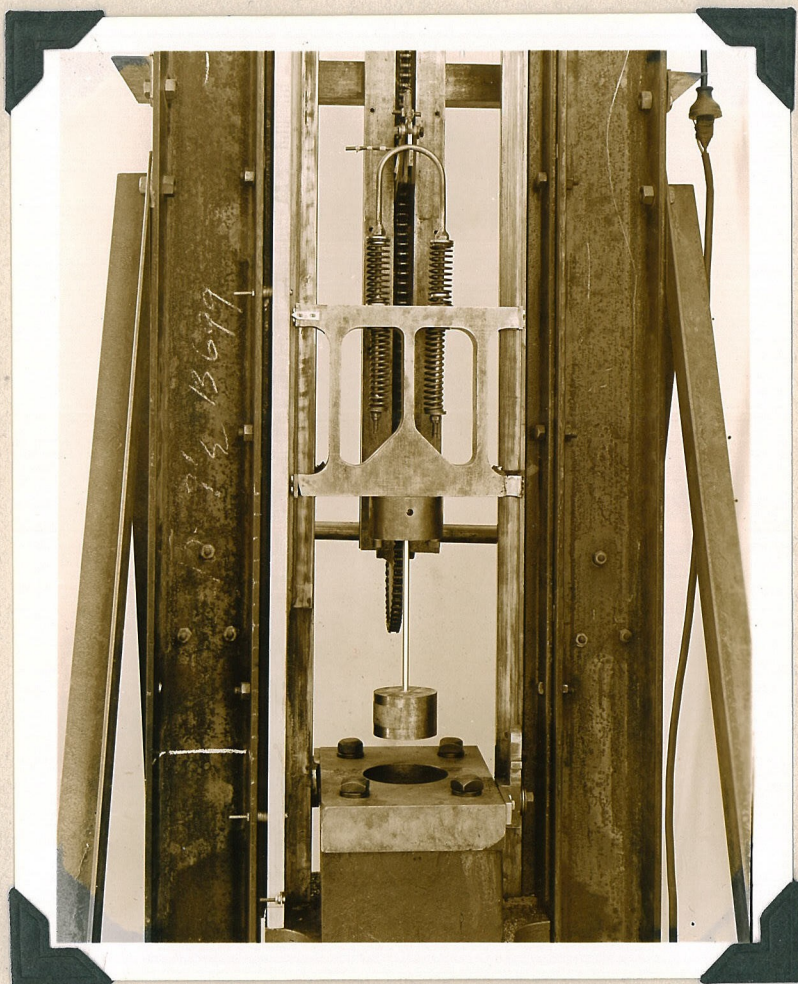
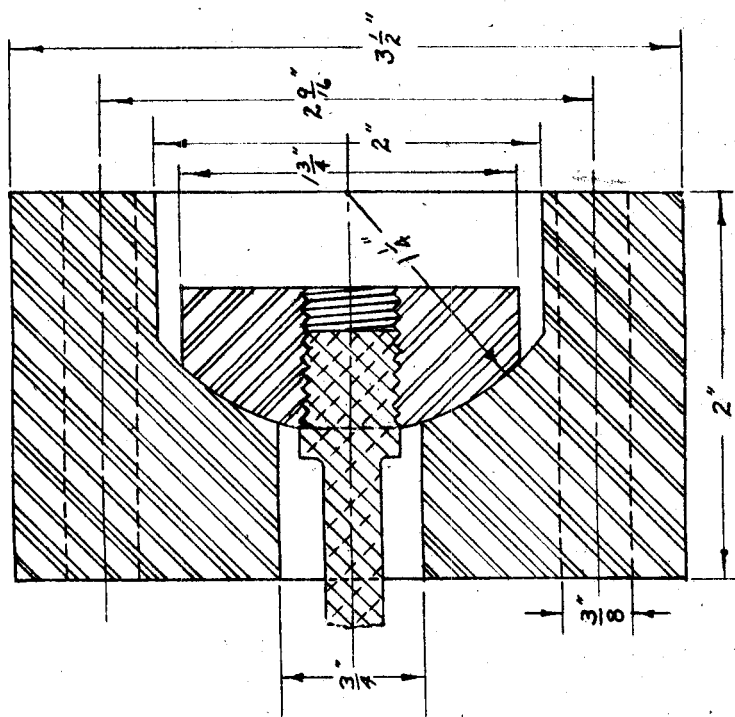


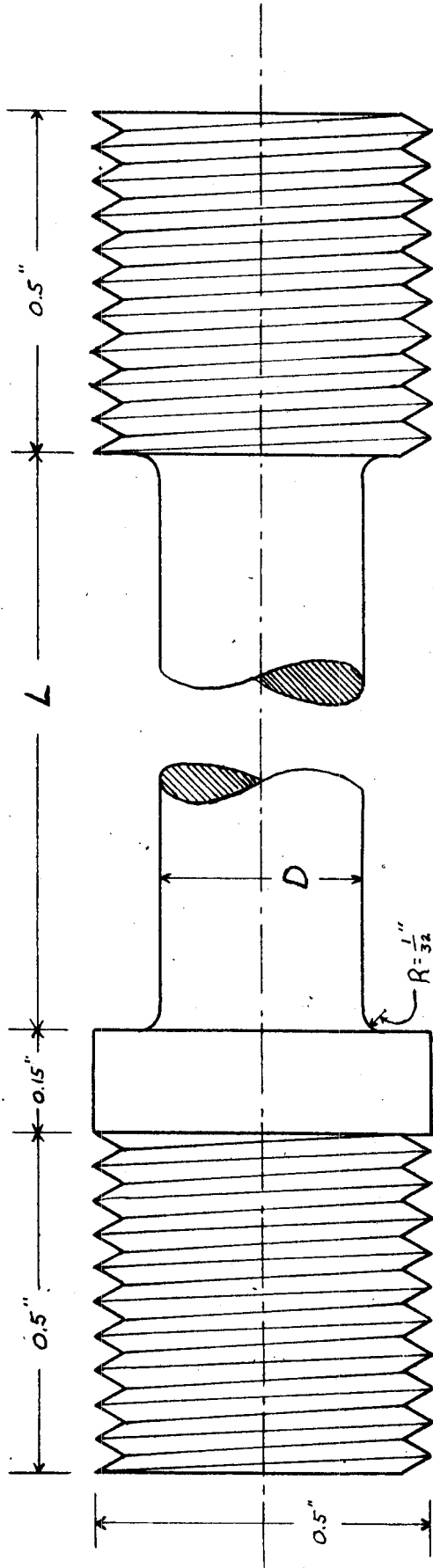
Fig. 1-b

Close up view of testing machine.



SECTION VIEW AT A-A

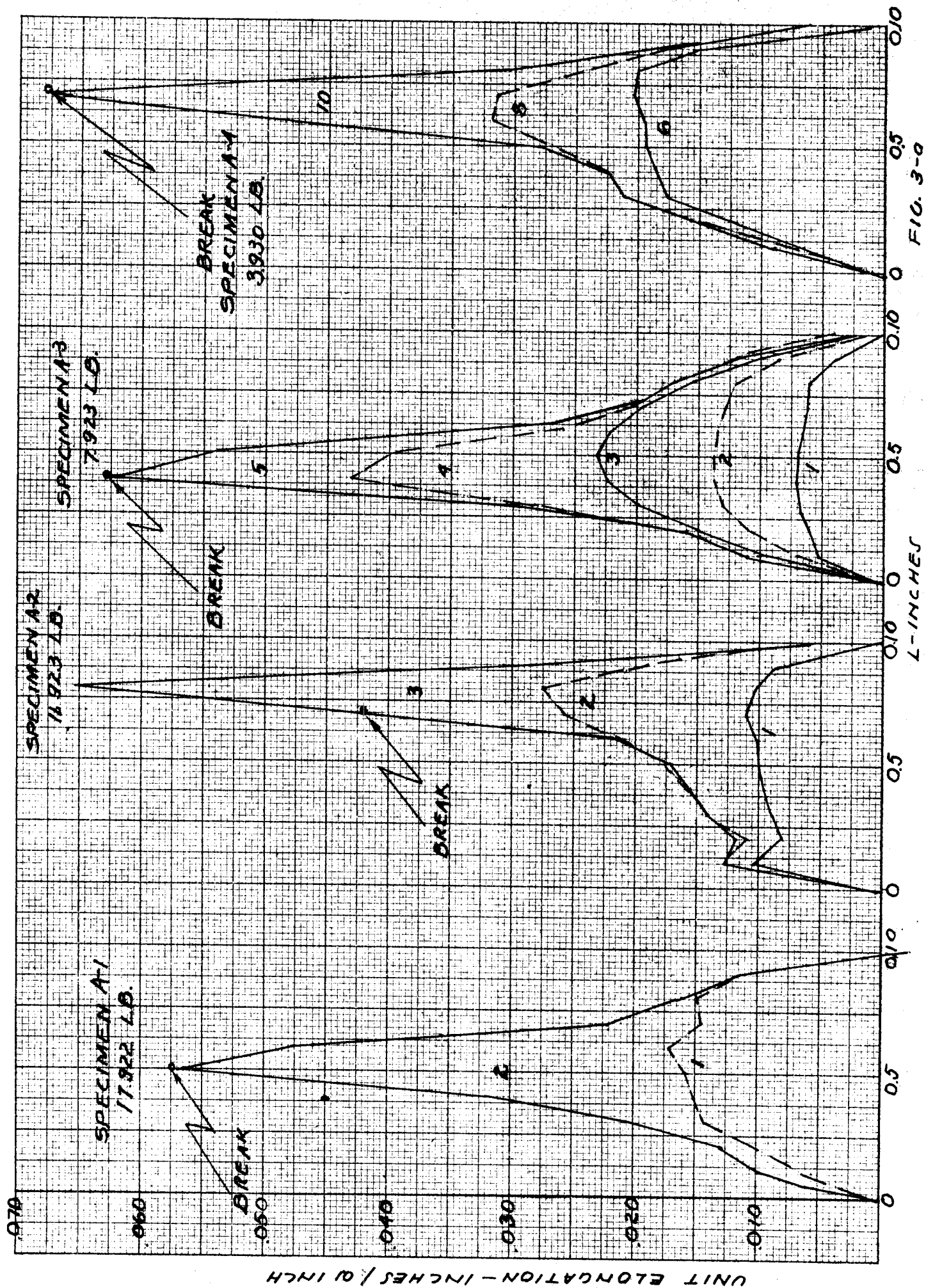
FIG. 1-C



SPECIMEN LETTER	L inches	D inches
A	1	0.300
B	4	0.300
C	8	0.300
D	2.83	0.300
E	2.83	0.178
F	4	0.252

17 ST										TOLERANCES $\pm .010$ OR $\frac{1}{32}$ UNLESS OTHERWISE NOTED	
				E.S. LEE, Jr.		C.W. STIRLING					
MATERIAL		FINISH		HEAT TREAT		DRAFTSMAN		CHECKED		ENGINEER	
GUGGENHEIM AERONAUTICAL LABORATORY											
CALIFORNIA INSTITUTE OF TECHNOLOGY											
TEST SPECIMEN										DRAWING NO.	

FIG. 2



TOTAL ELONGATION - INCHES

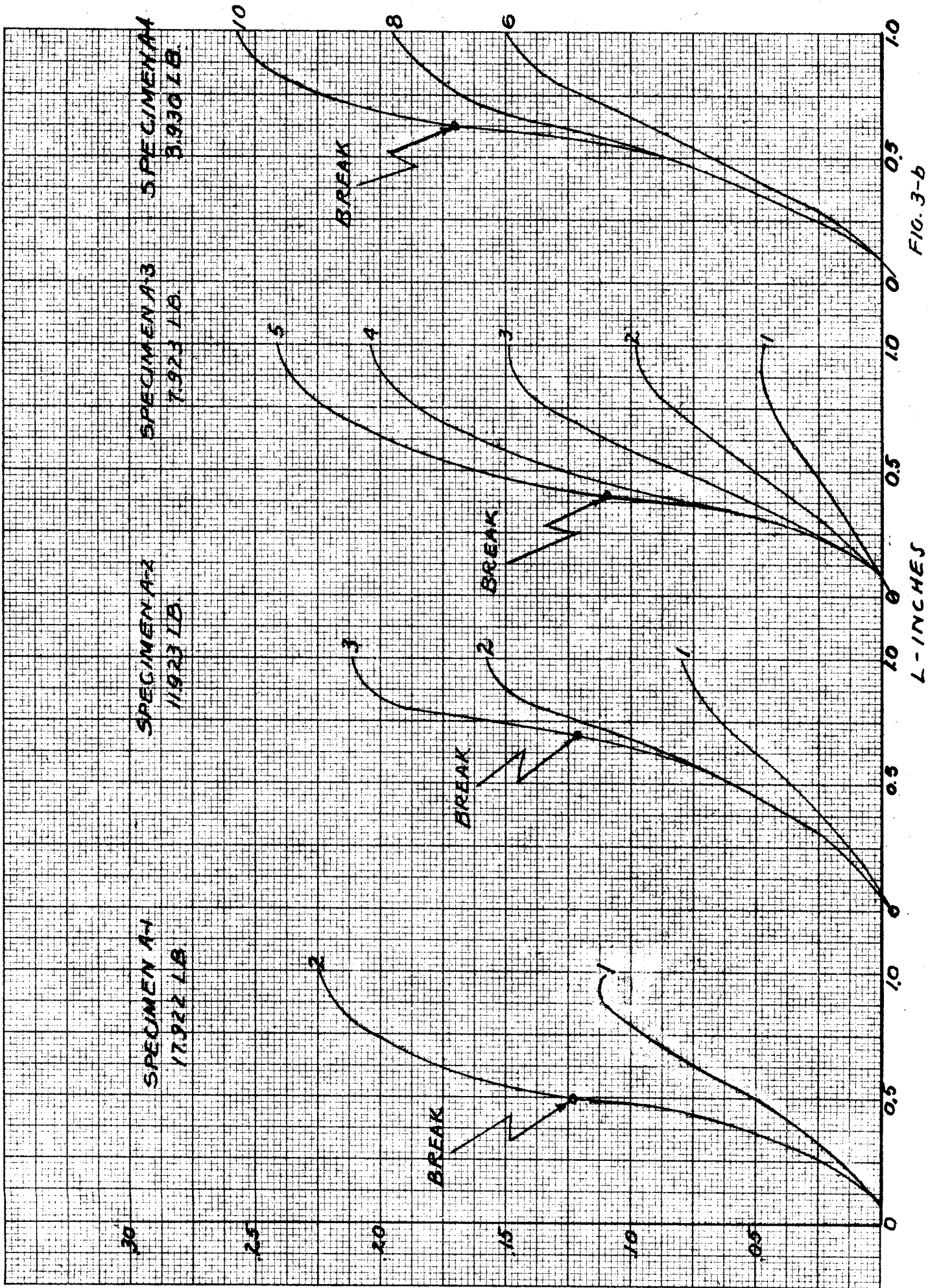


FIG. 3-b

SPECIMEN A5
2.430 LB.

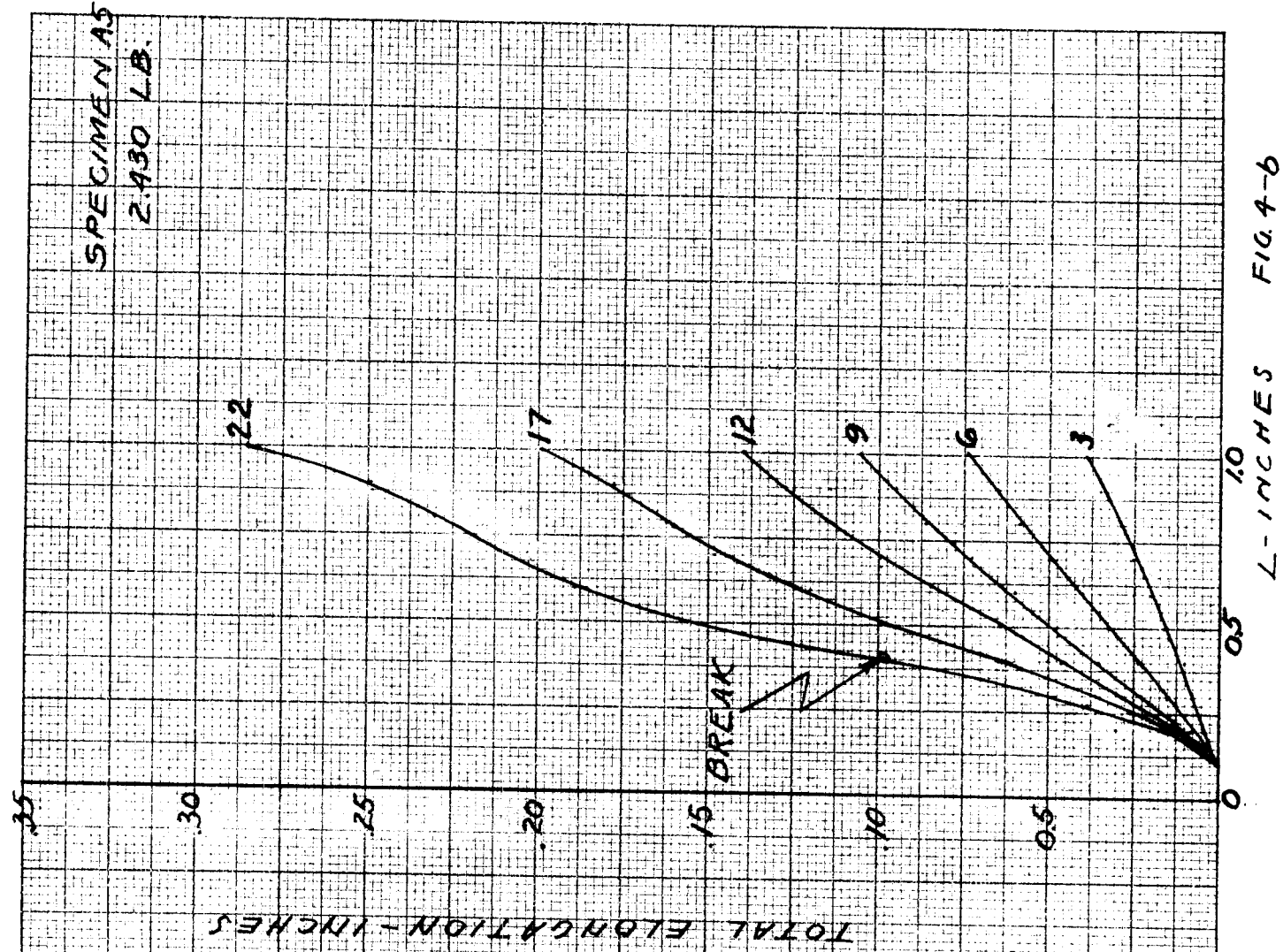


FIG. 4-6

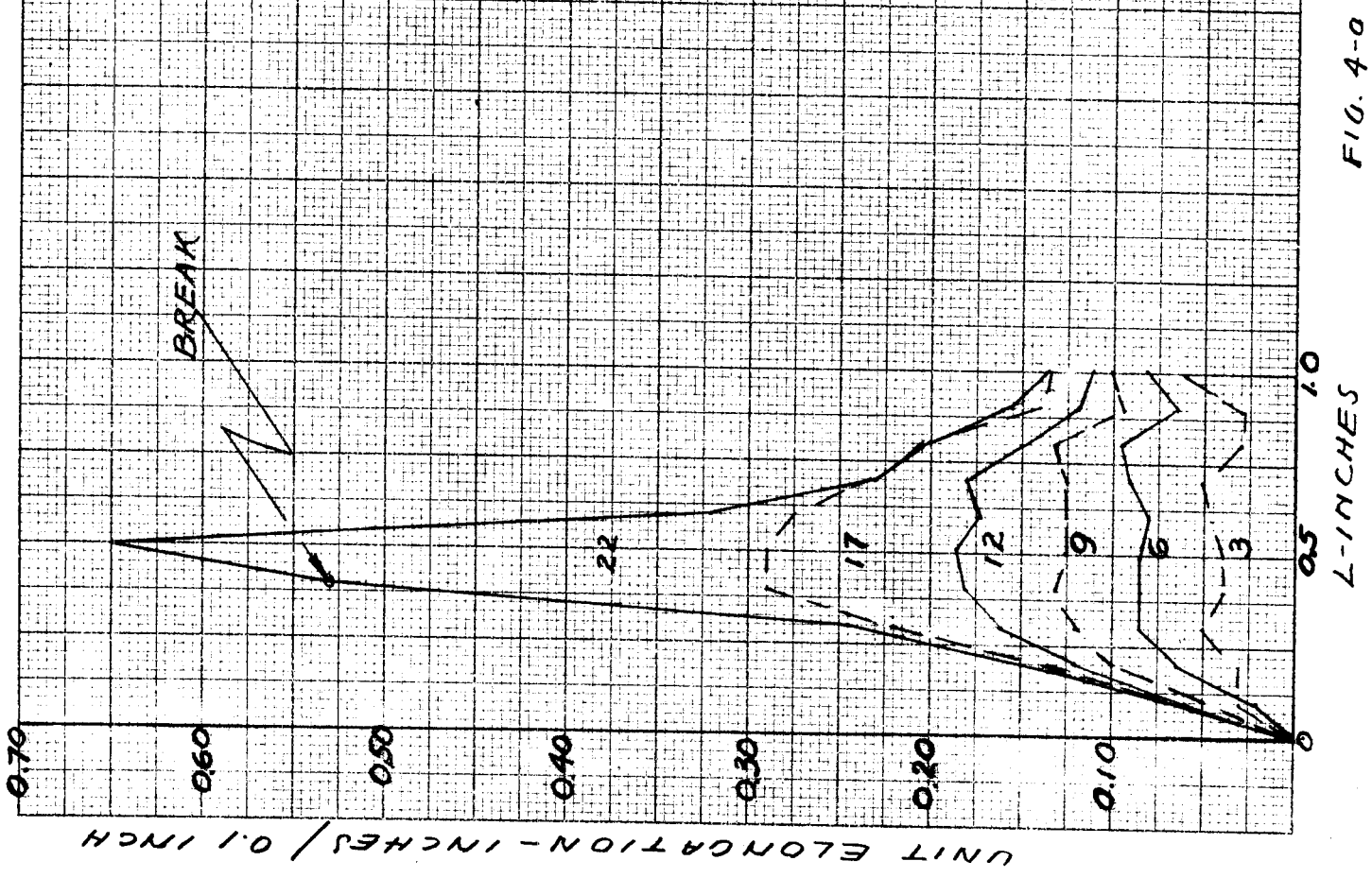


FIG. 4-5

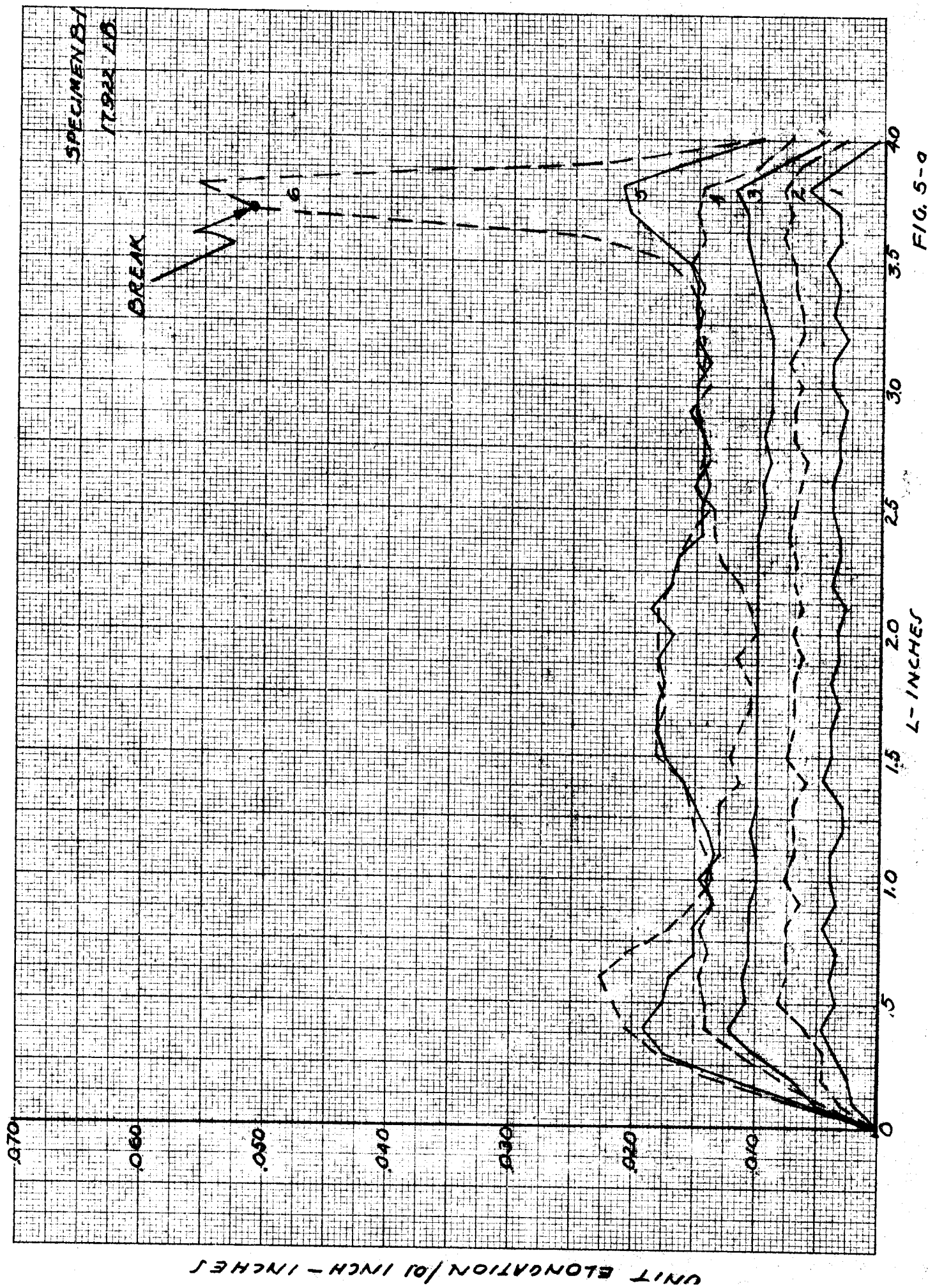
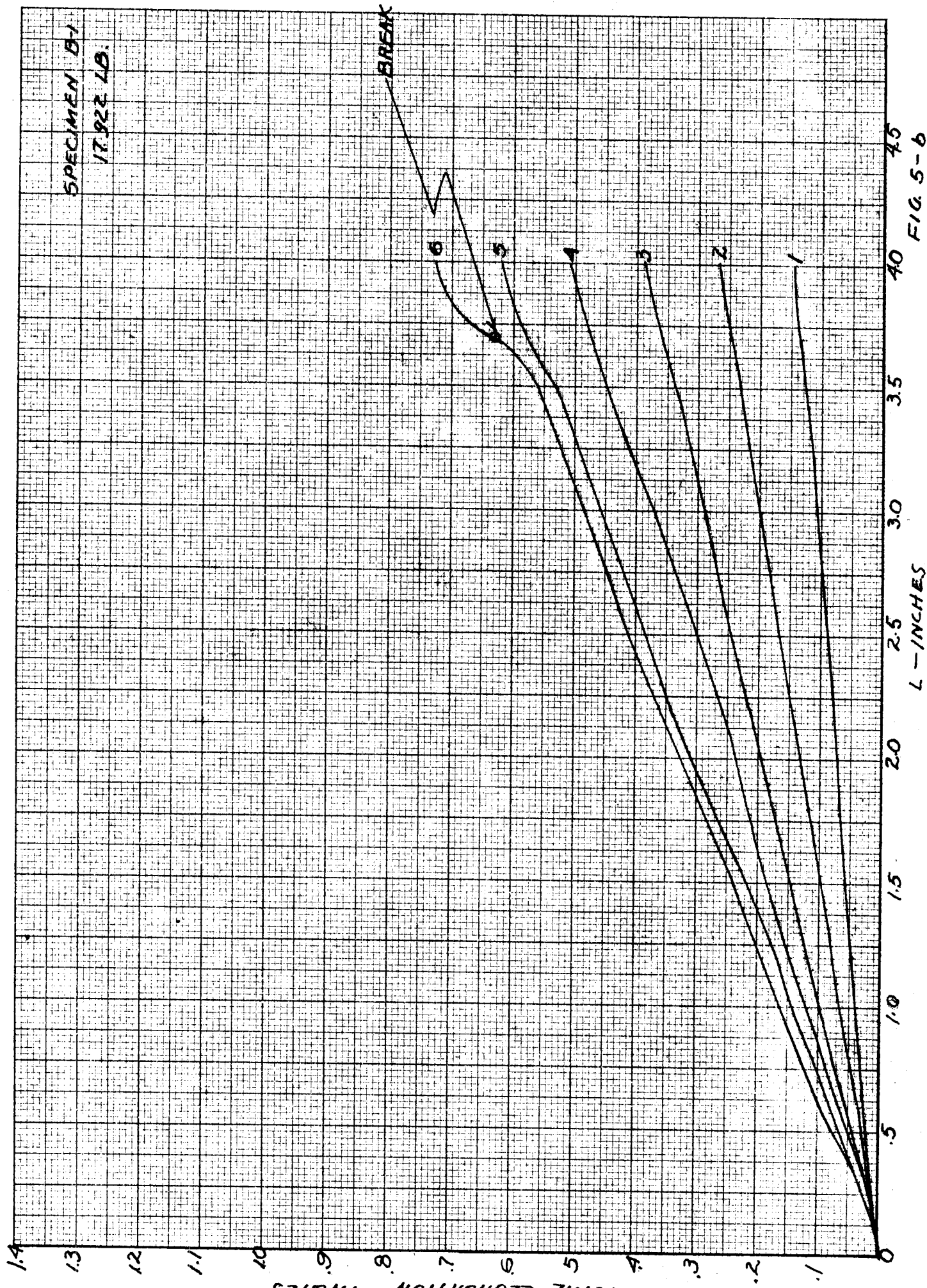


FIG. 5-0

SPECIMEN BY
17.922 LB.



L - INCHES

FIG. 5-6

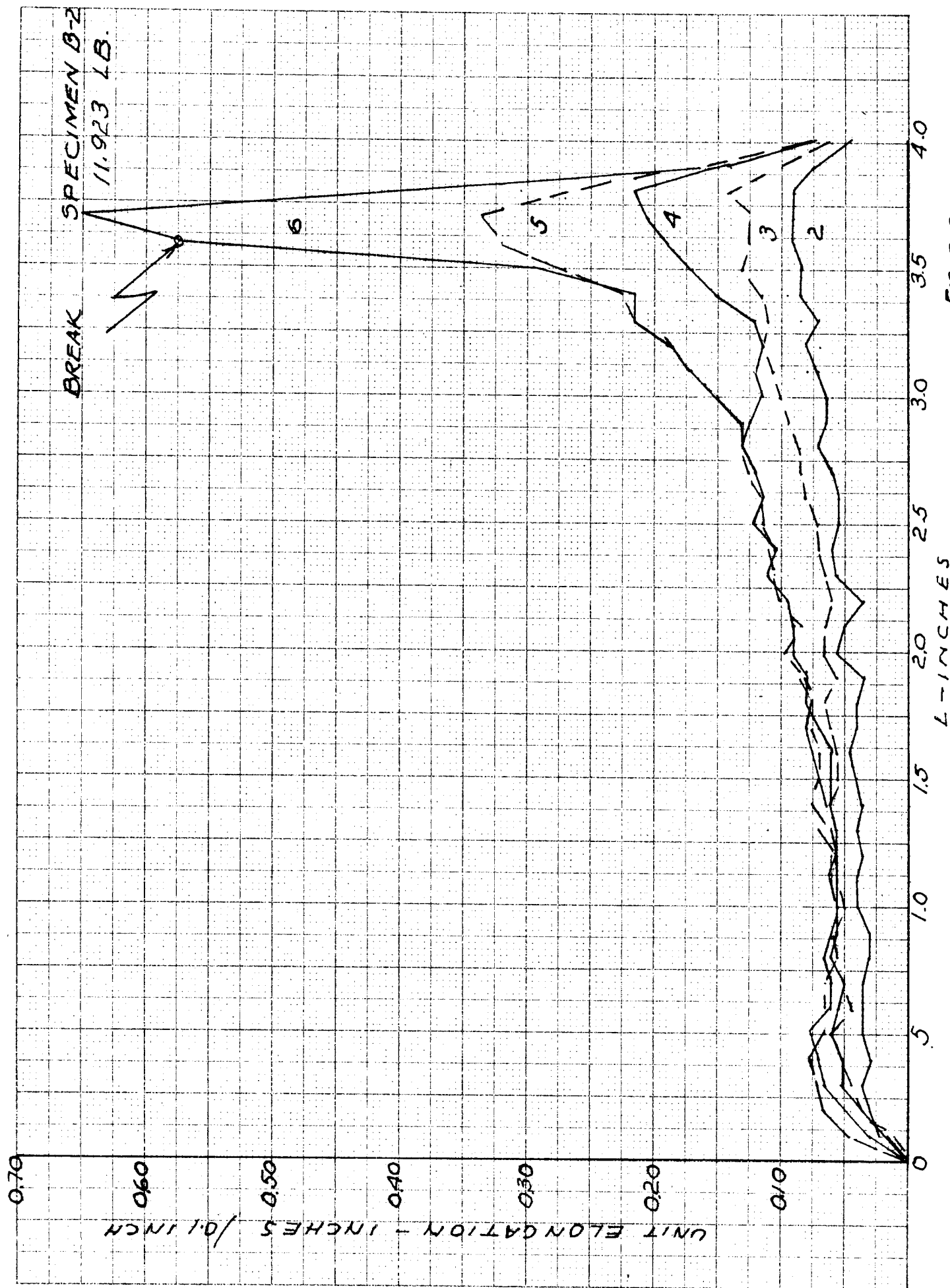


FIG. 6-a

SPECIMEN 0-2

11.923 LB.

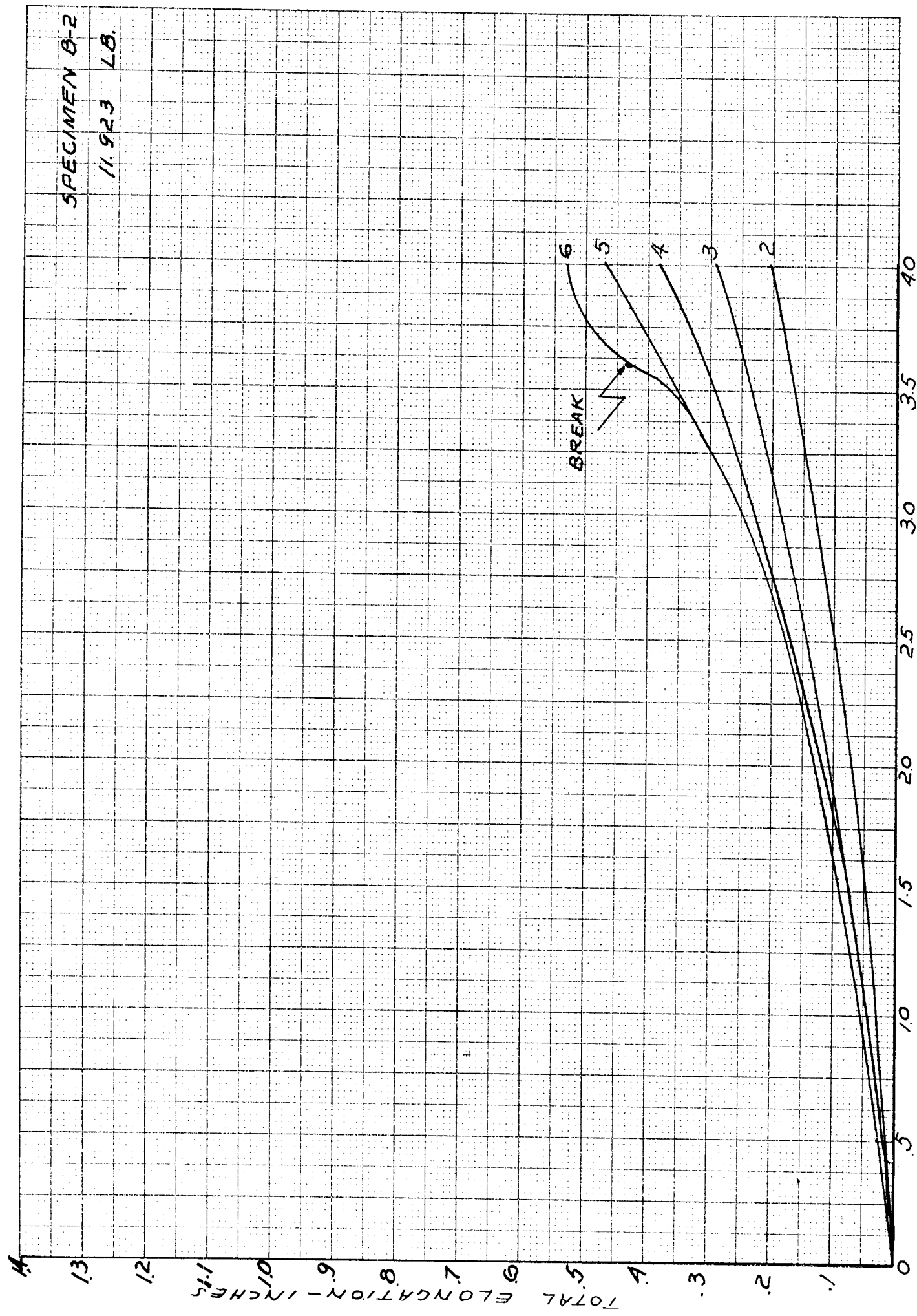
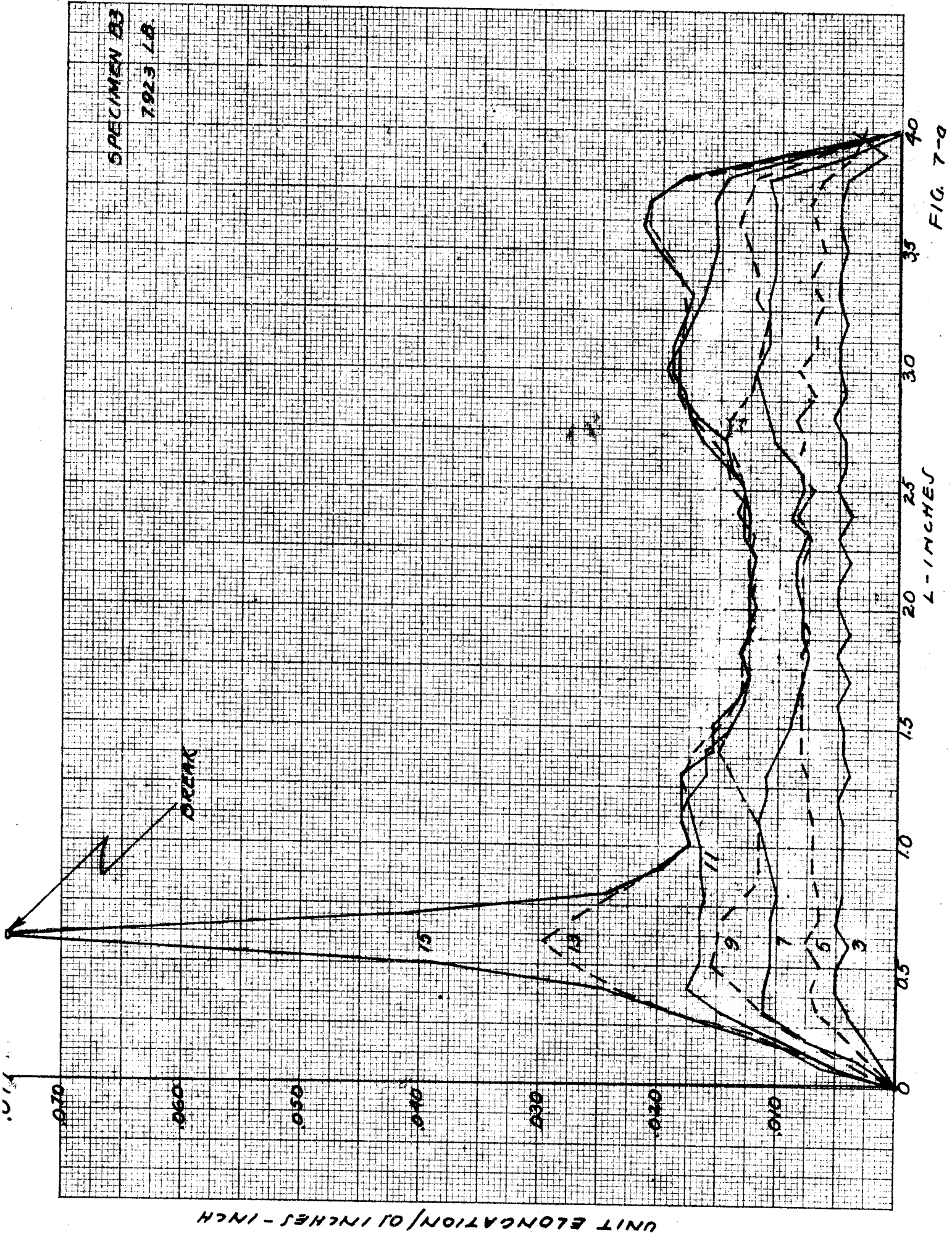
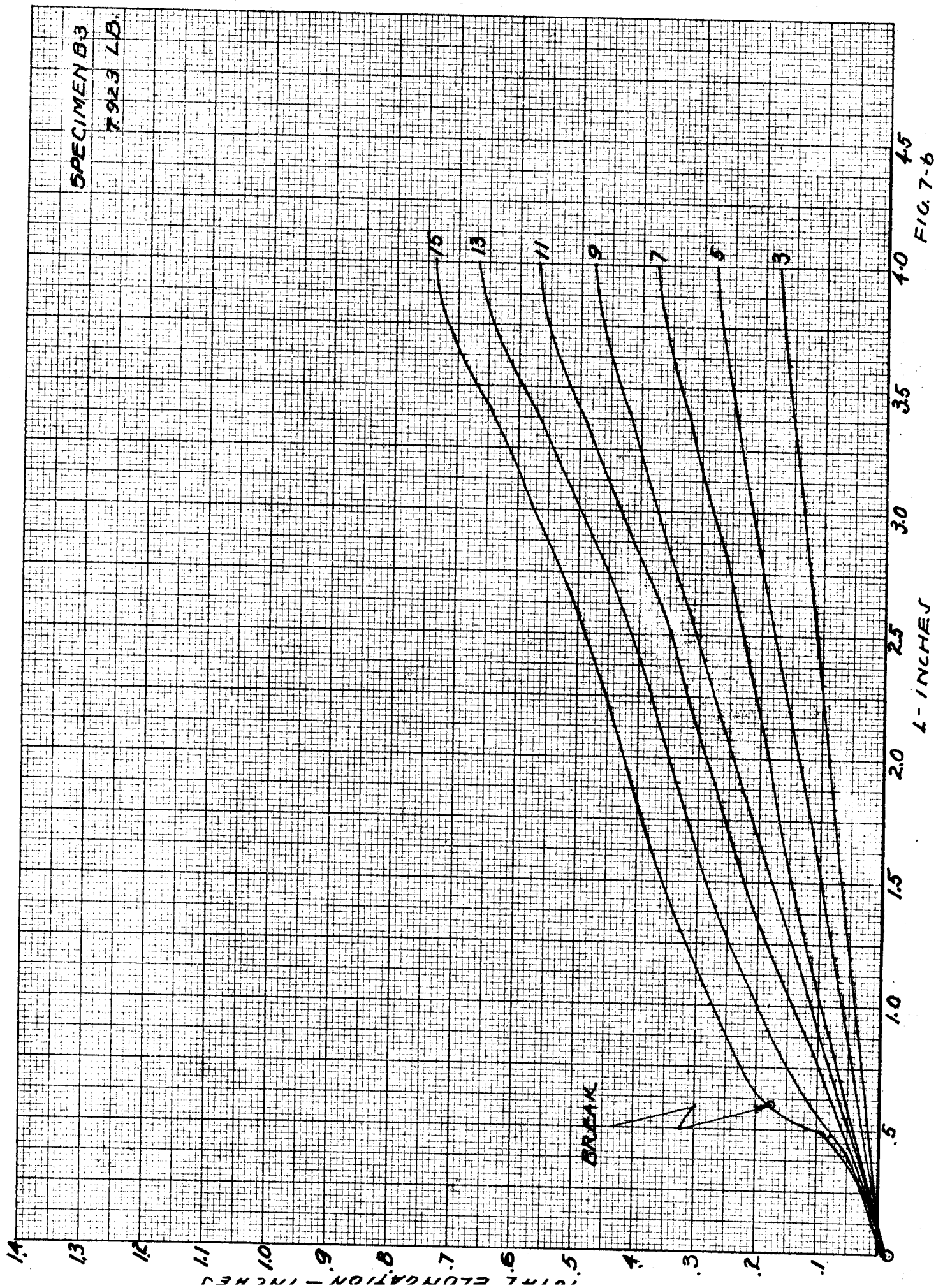


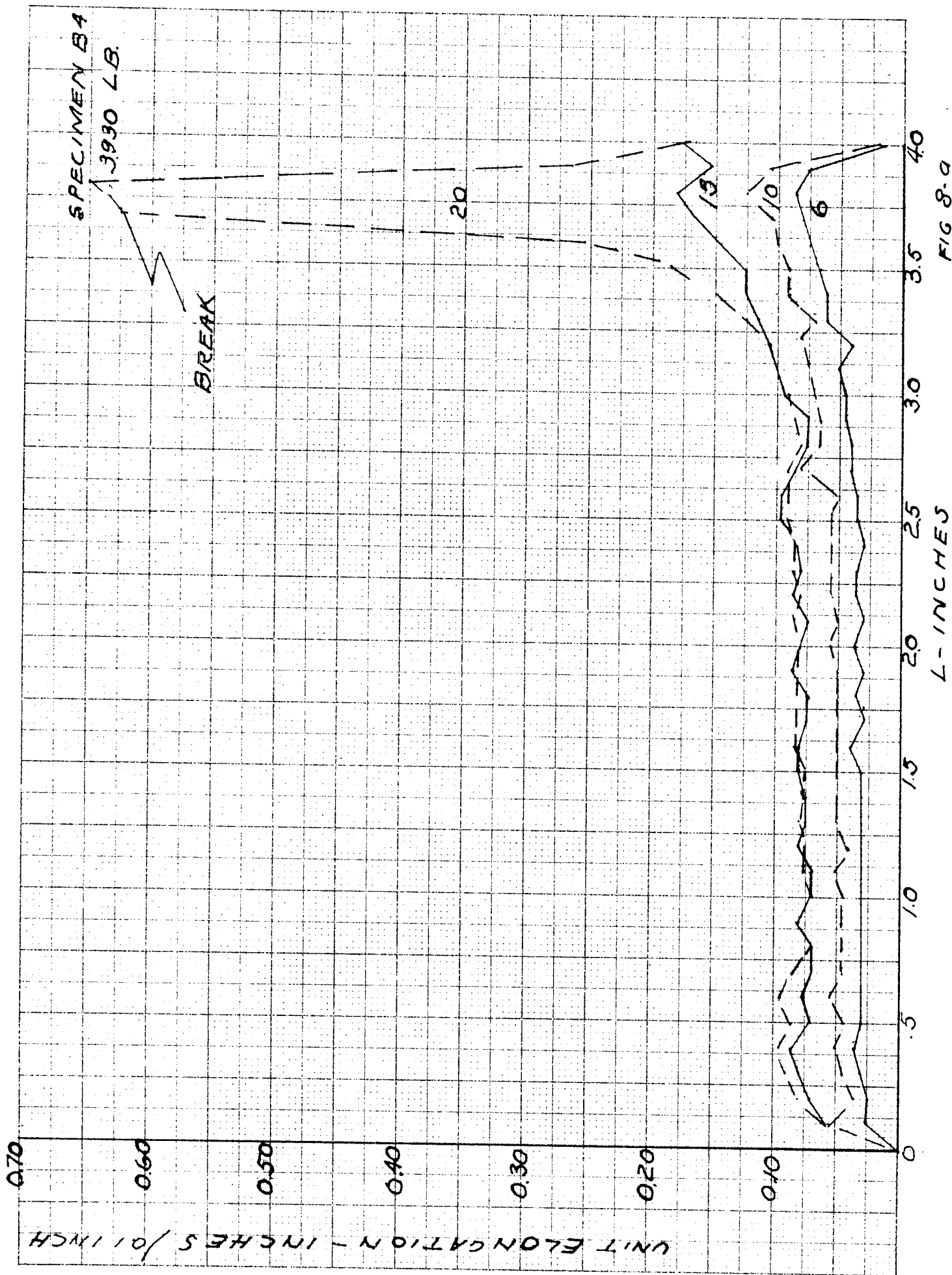
FIG. 6-b

SPECIMEN B3

7923 LB.







SPECIMEN B-4
3930 LB.

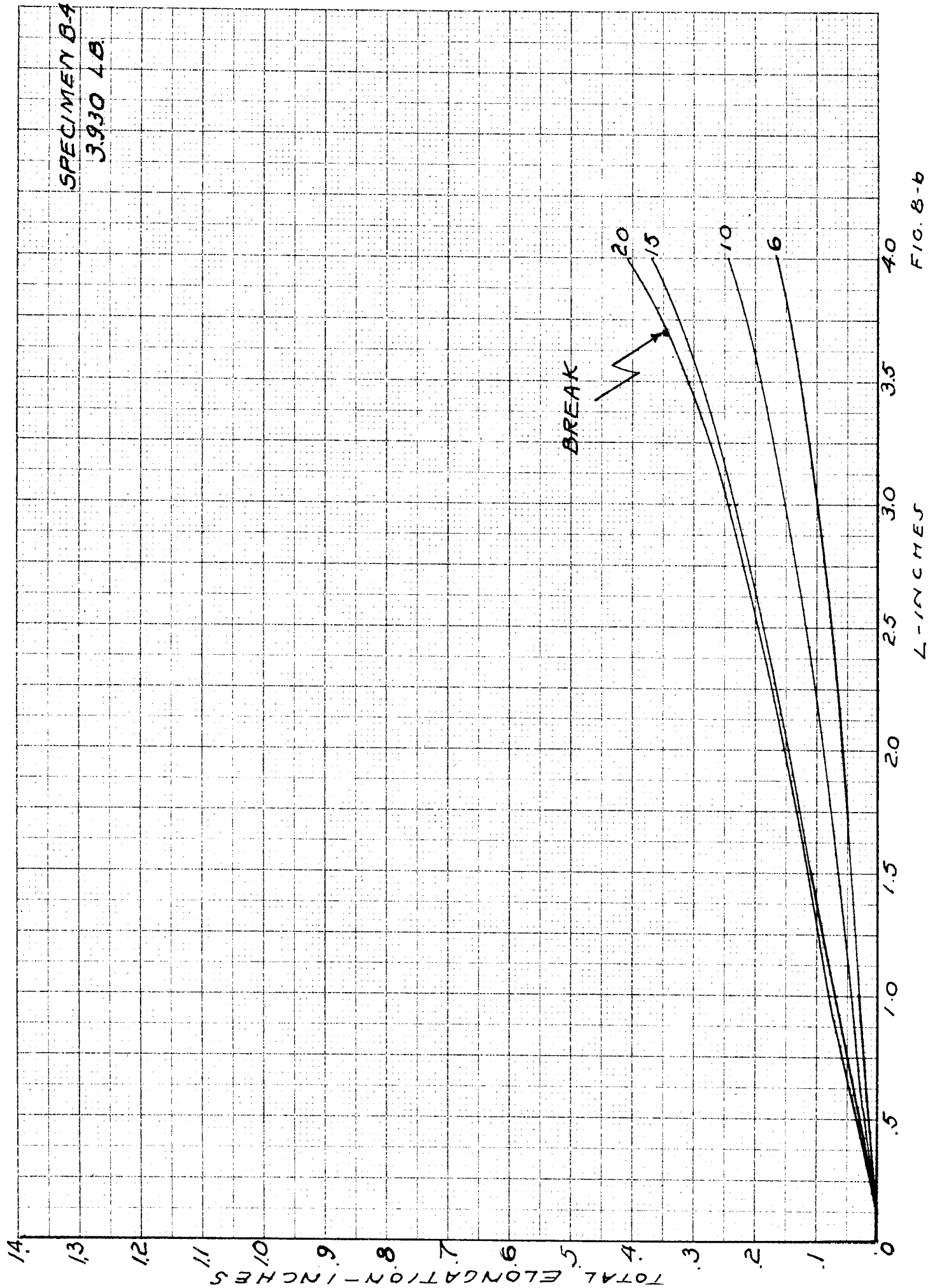
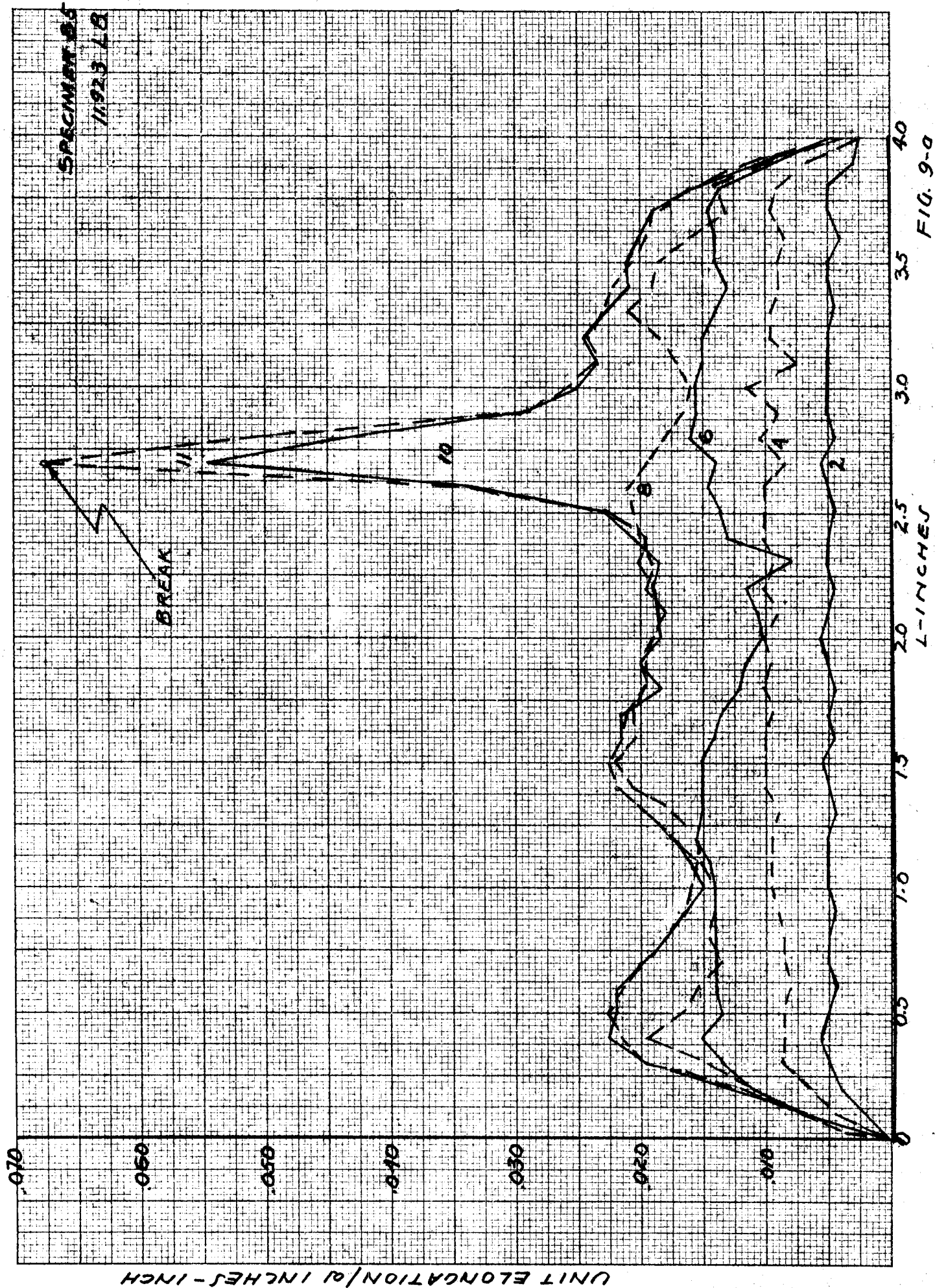


FIG. 8-b



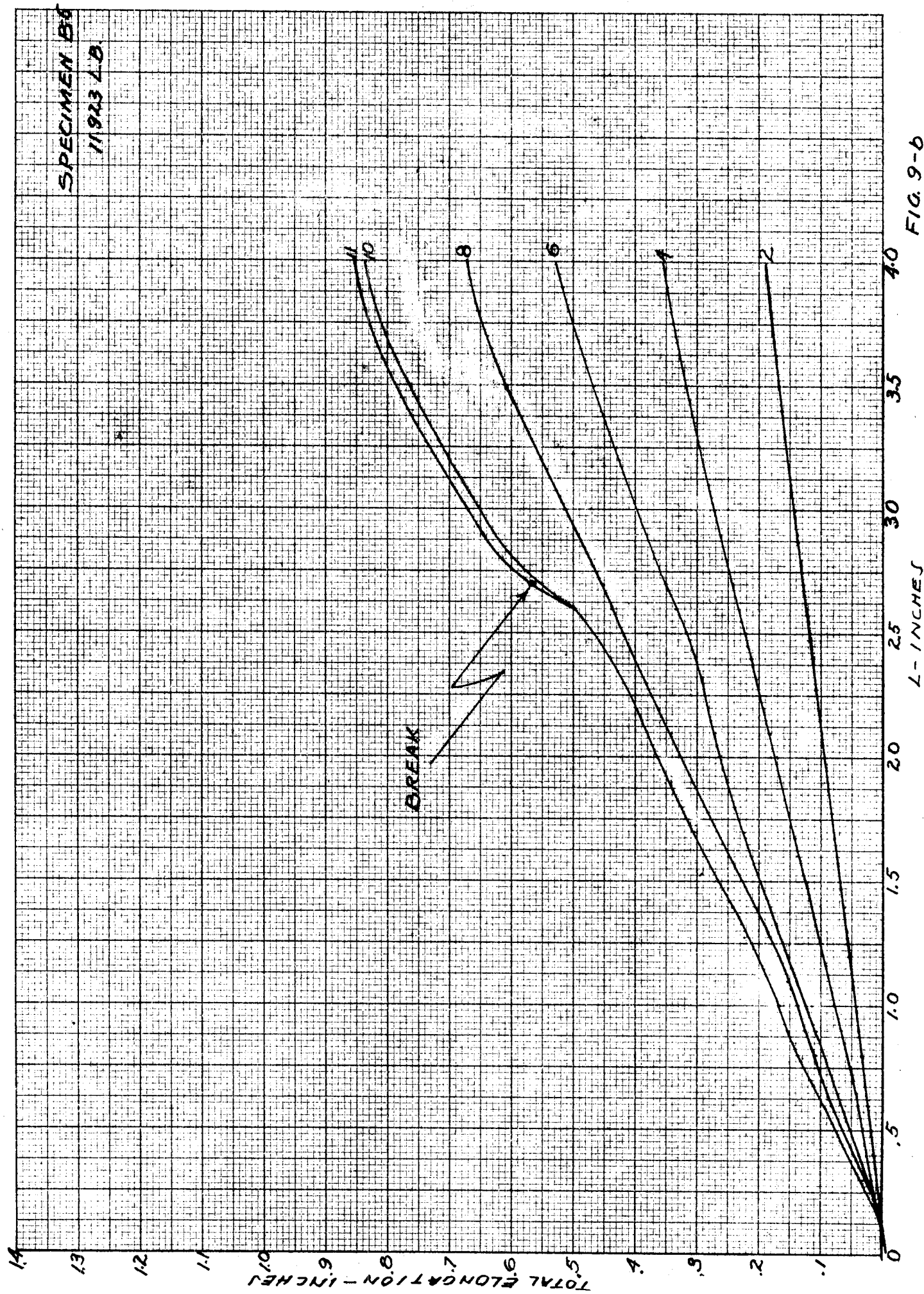


FIG. 9-6

SPECIMEN BG
3930 LB

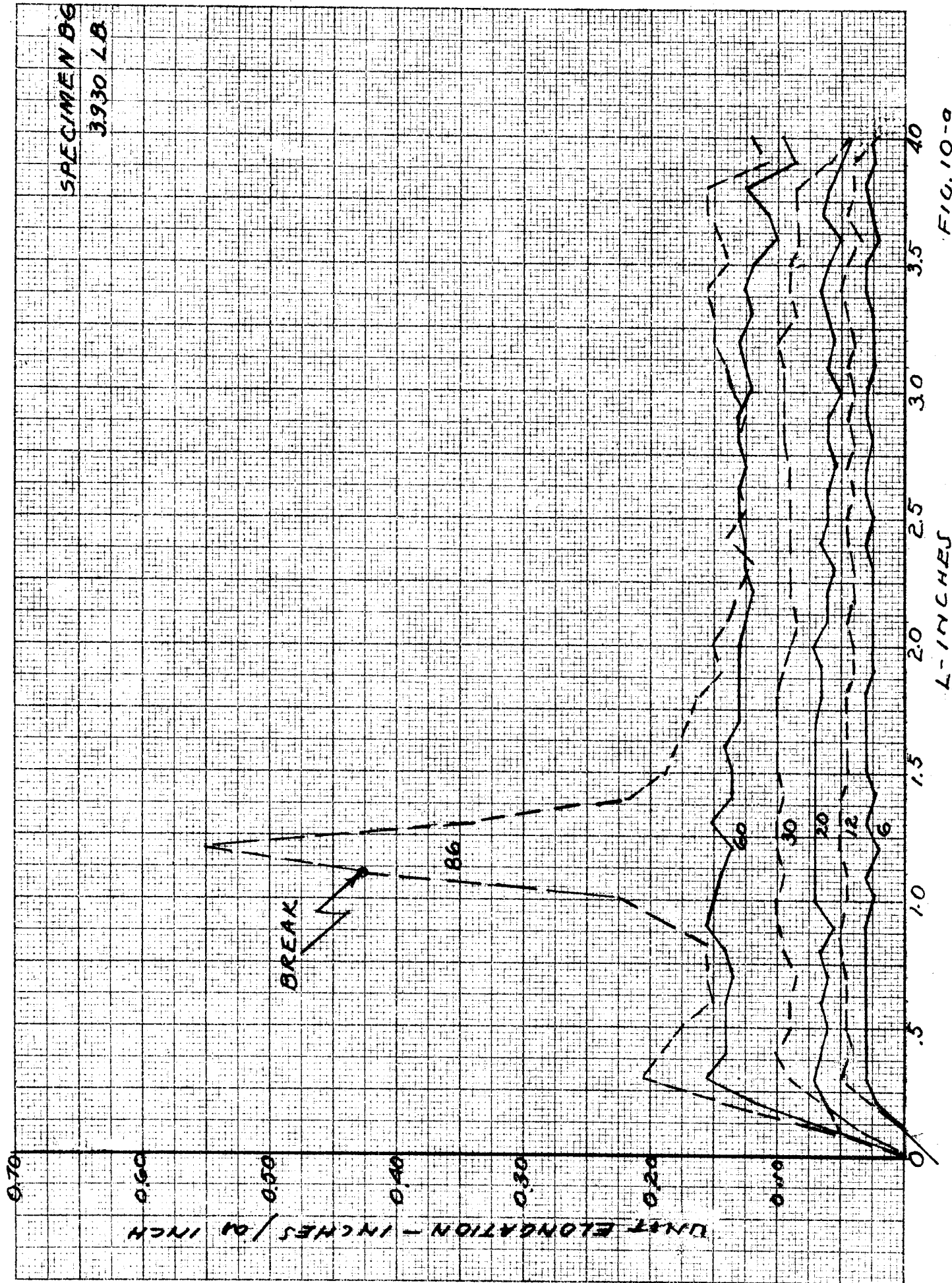
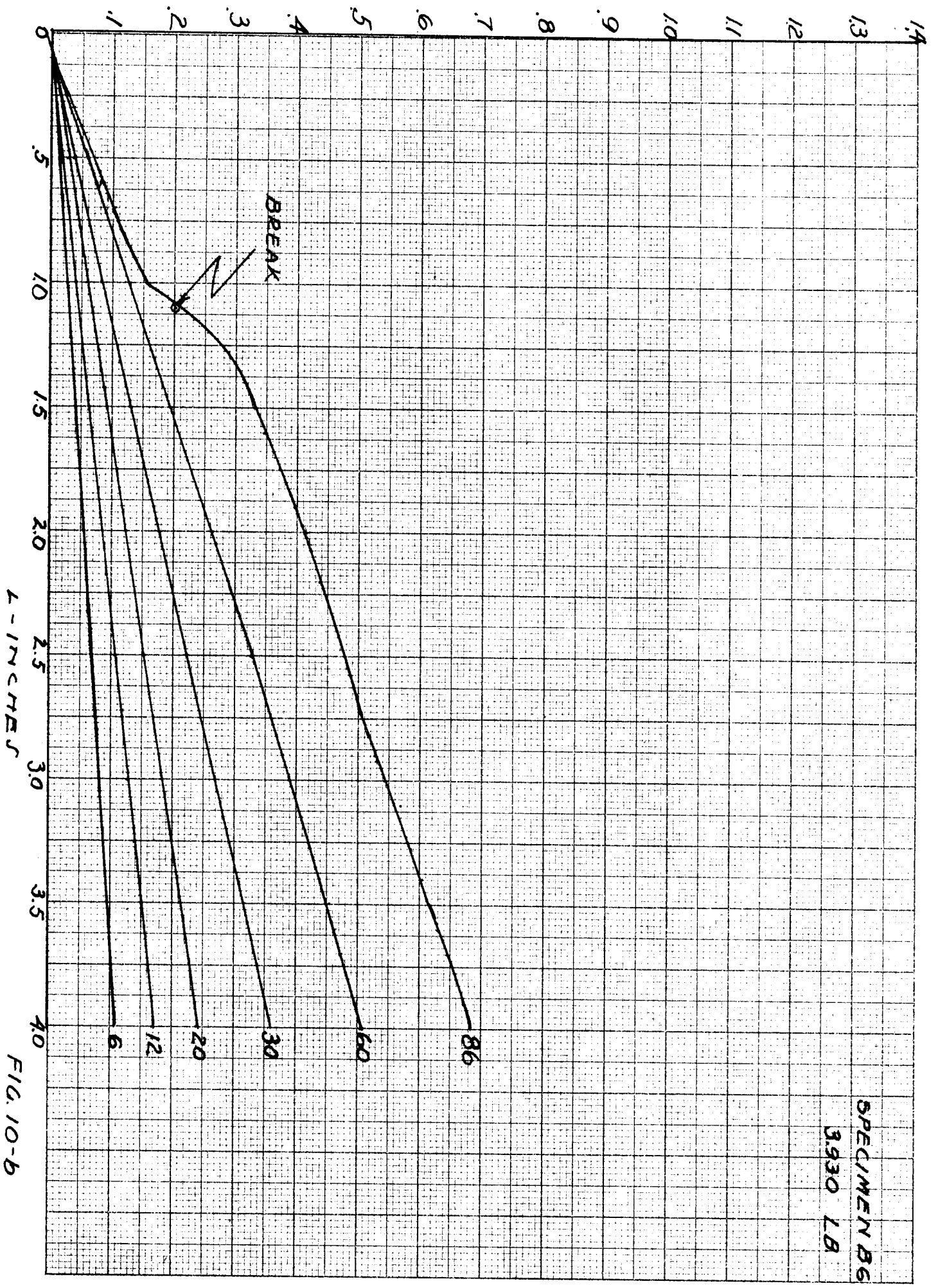


FIG. 10-a

L - INCHES



SPECIMEN B6
3.930 LB

FIG. 10-b

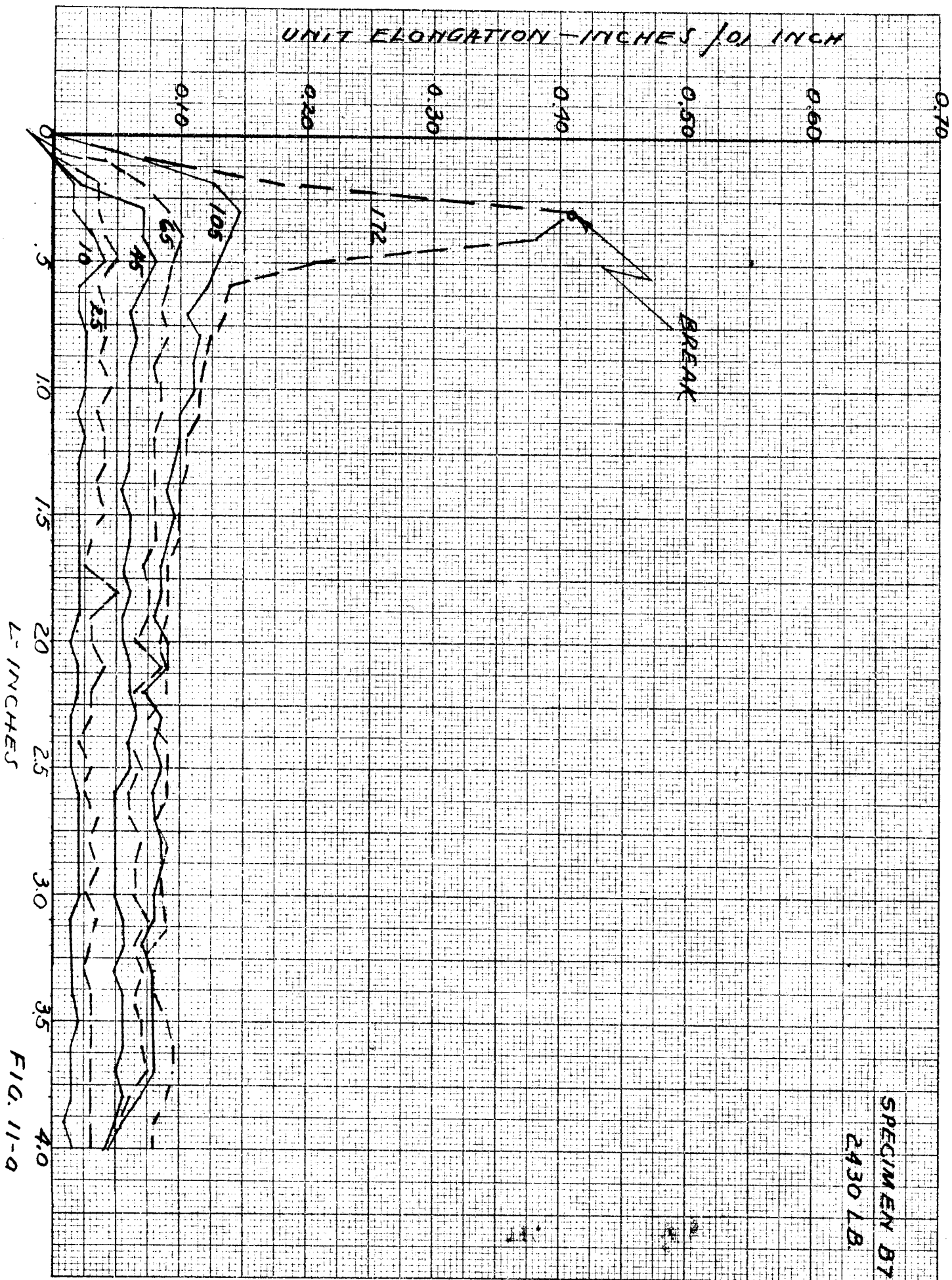


FIG. 11-0

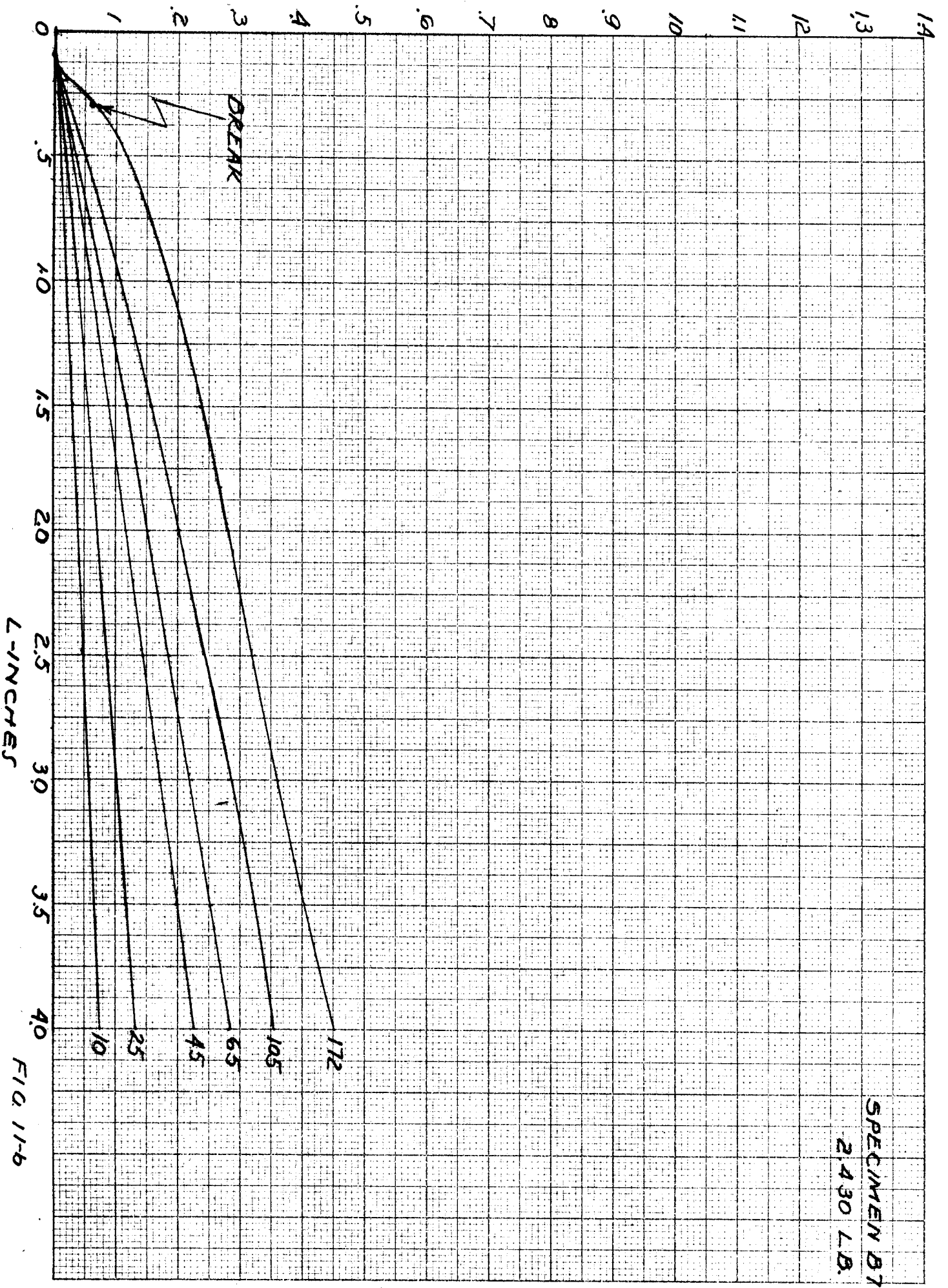
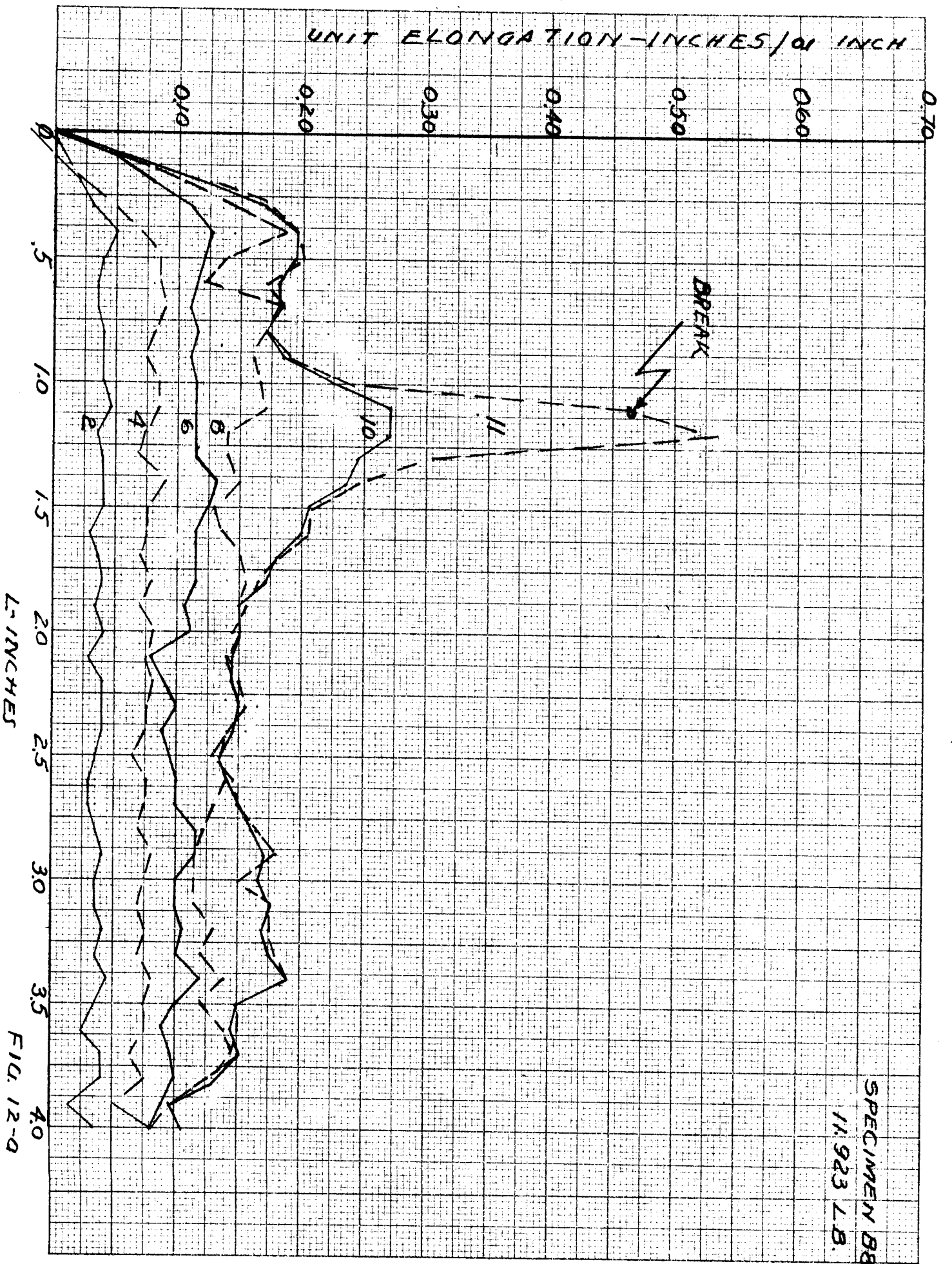


FIG. 11-6



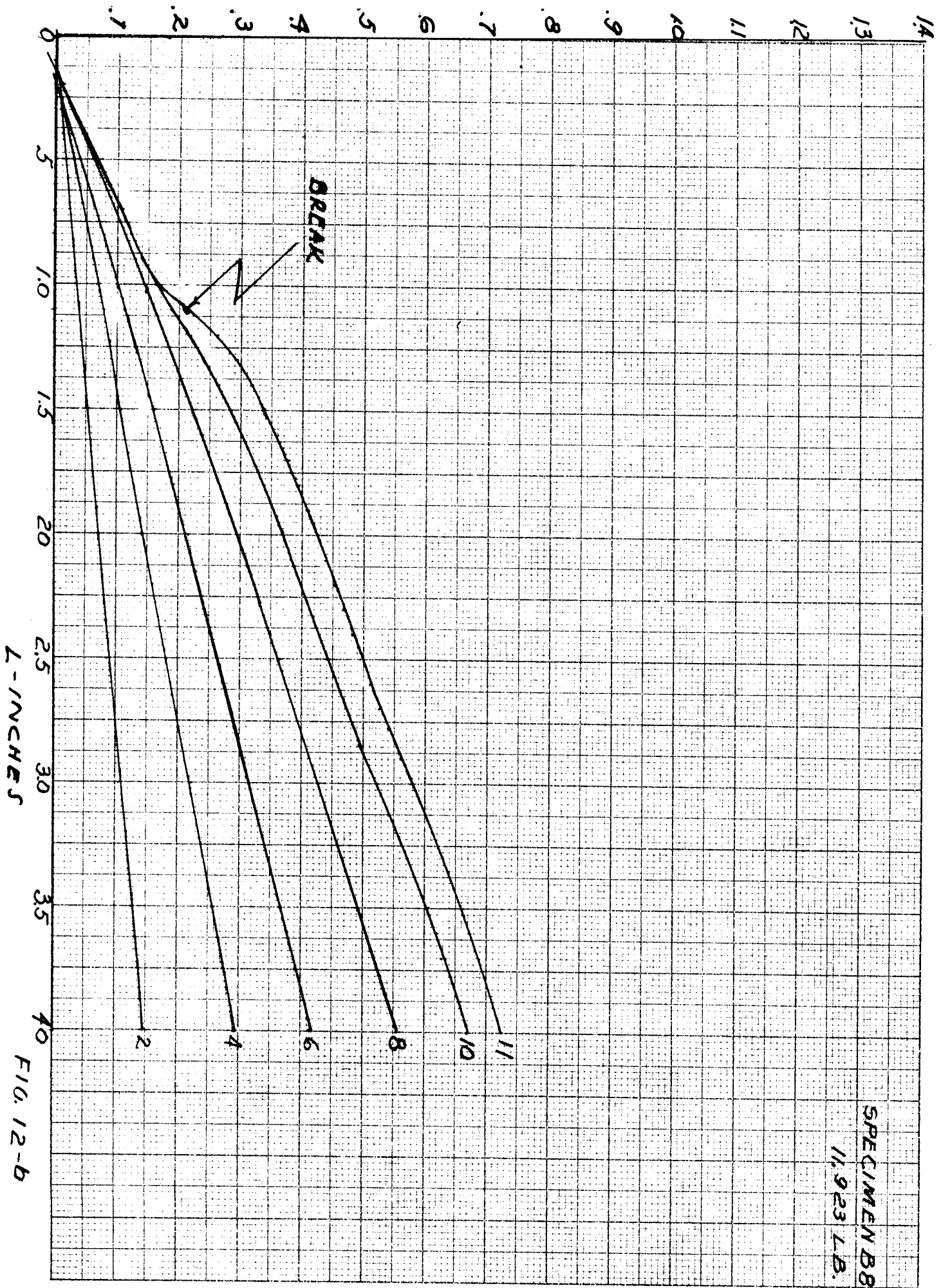


FIG. 12-b

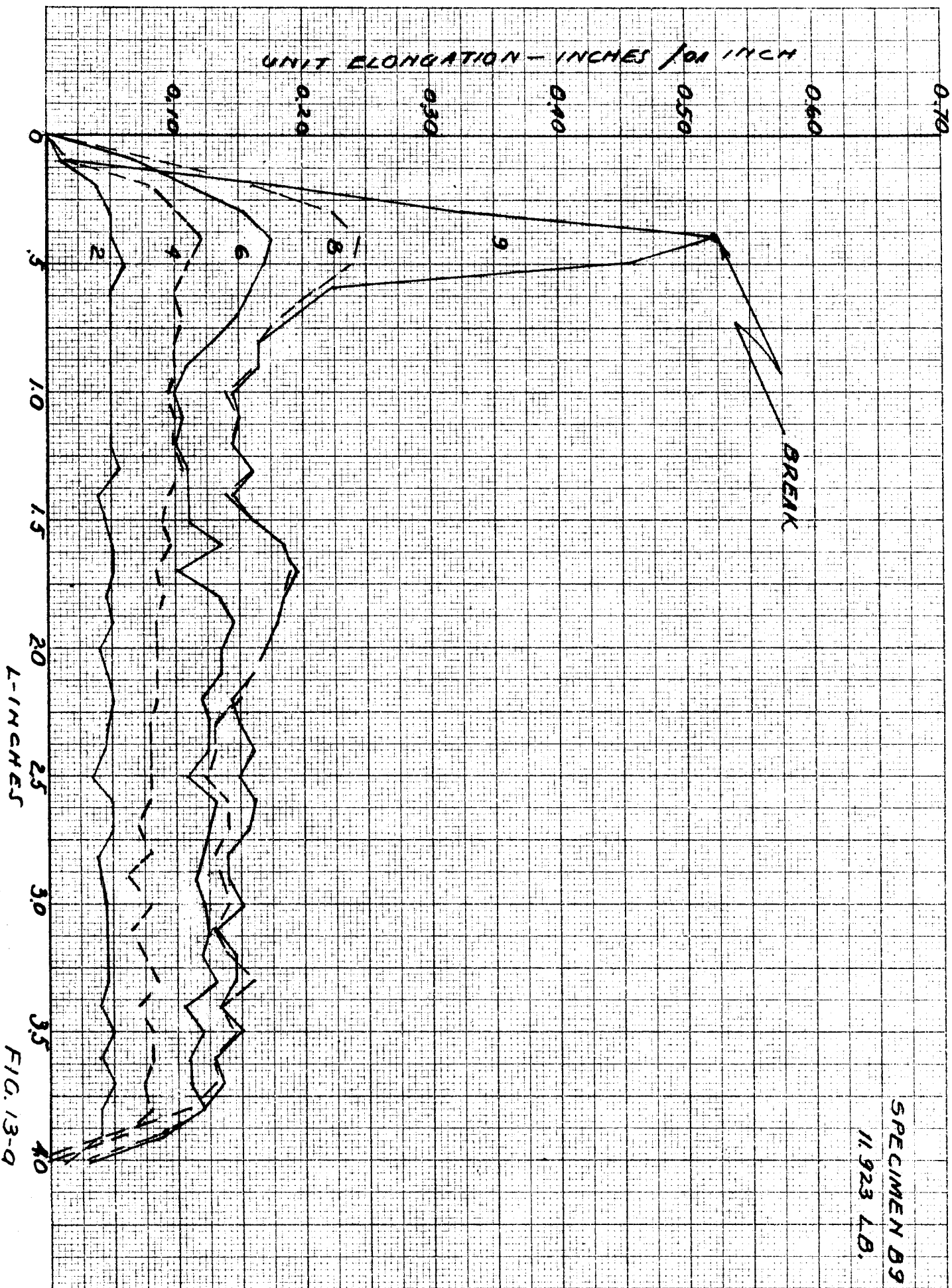


FIG. 13-9

SPECIMEN B9
11.923 L.B.

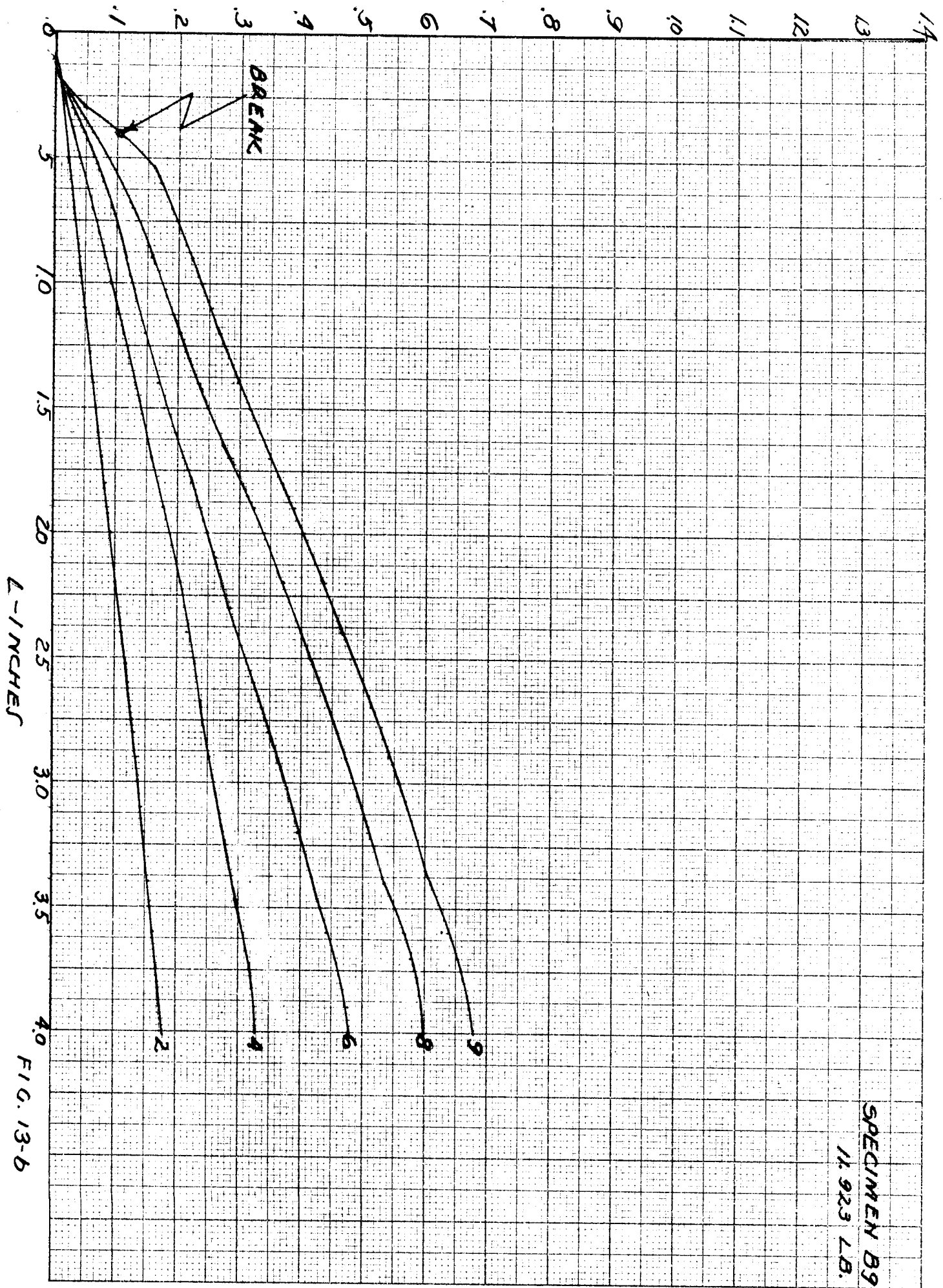
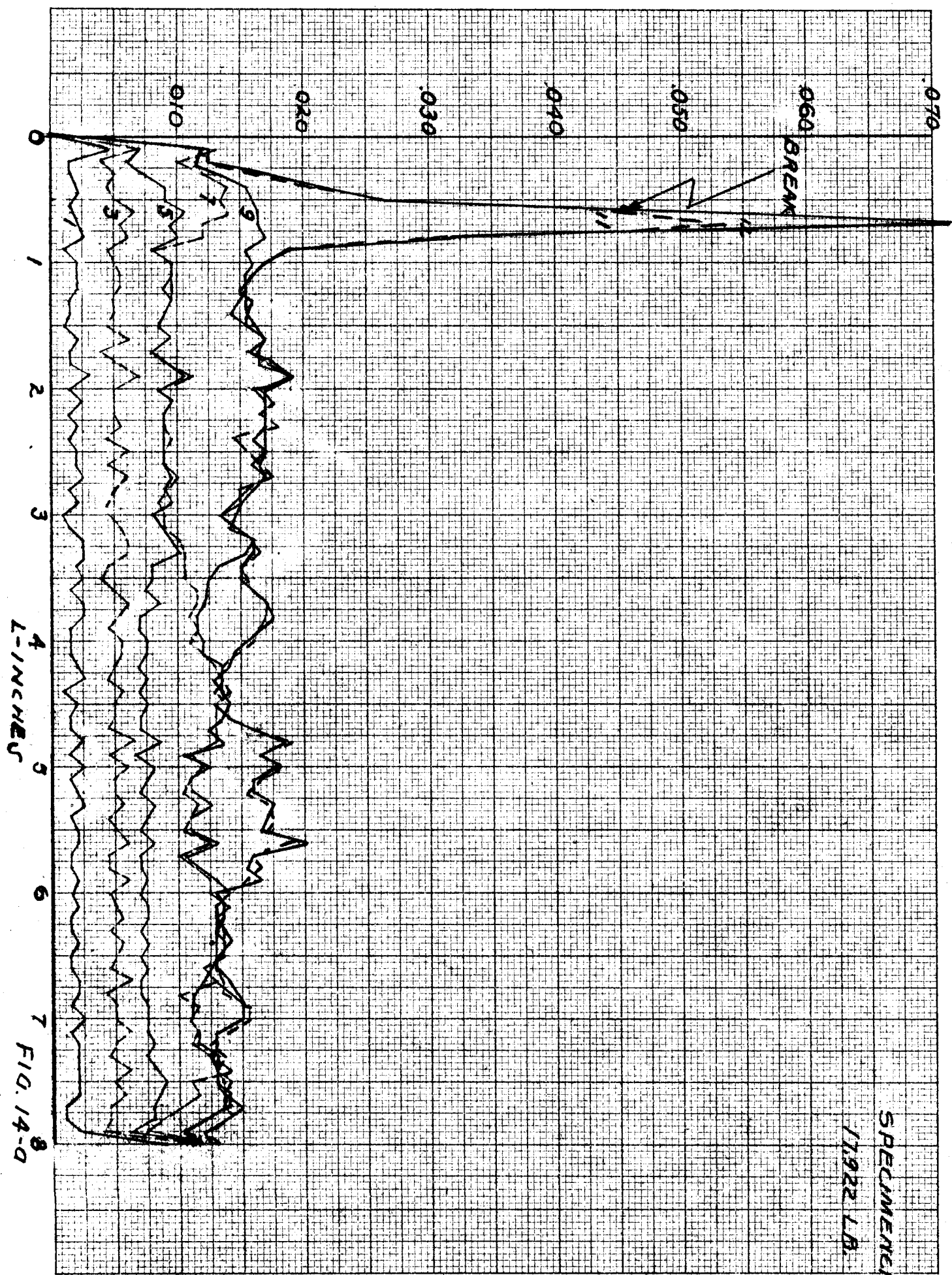


FIG. 13-6



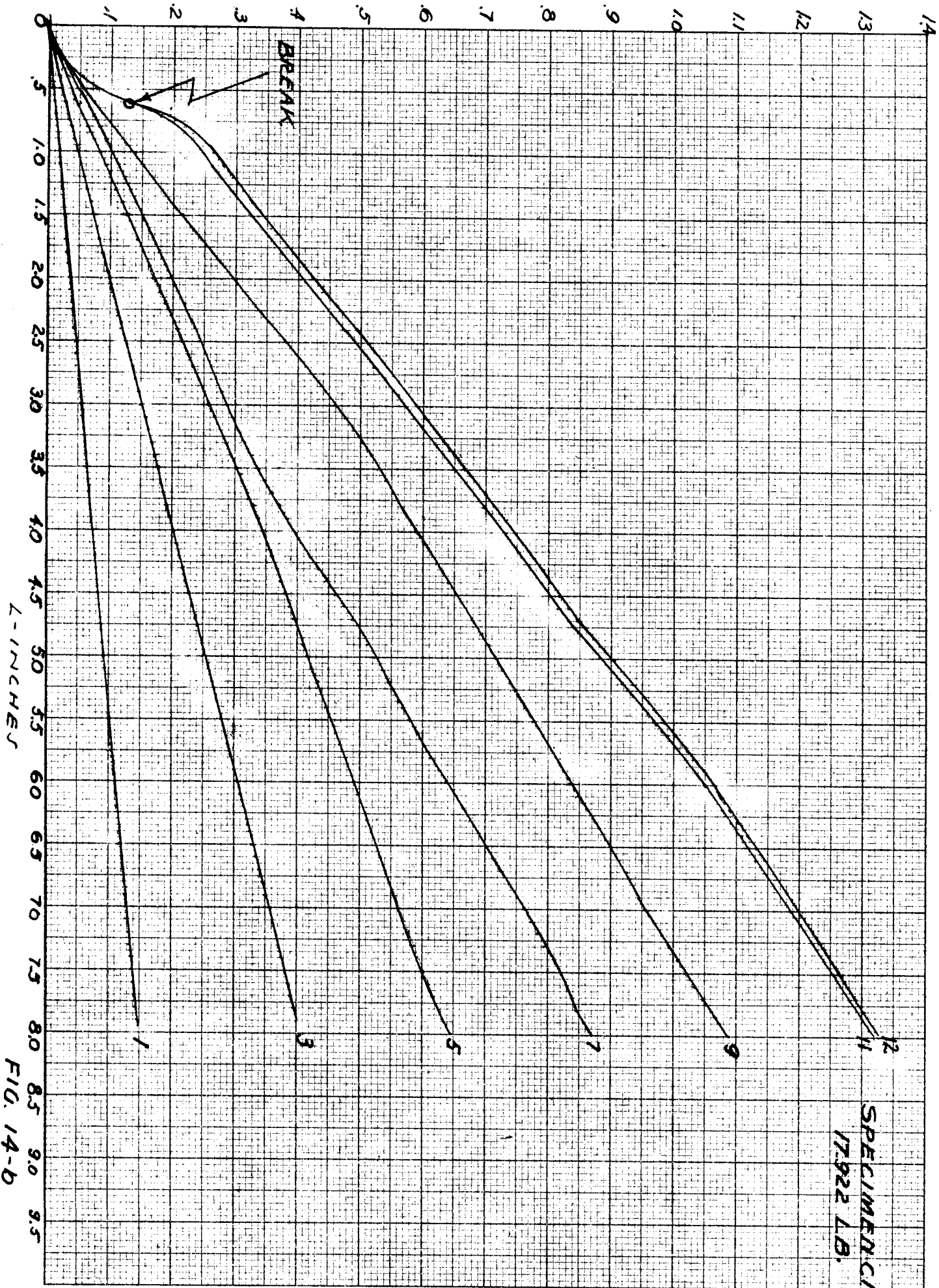
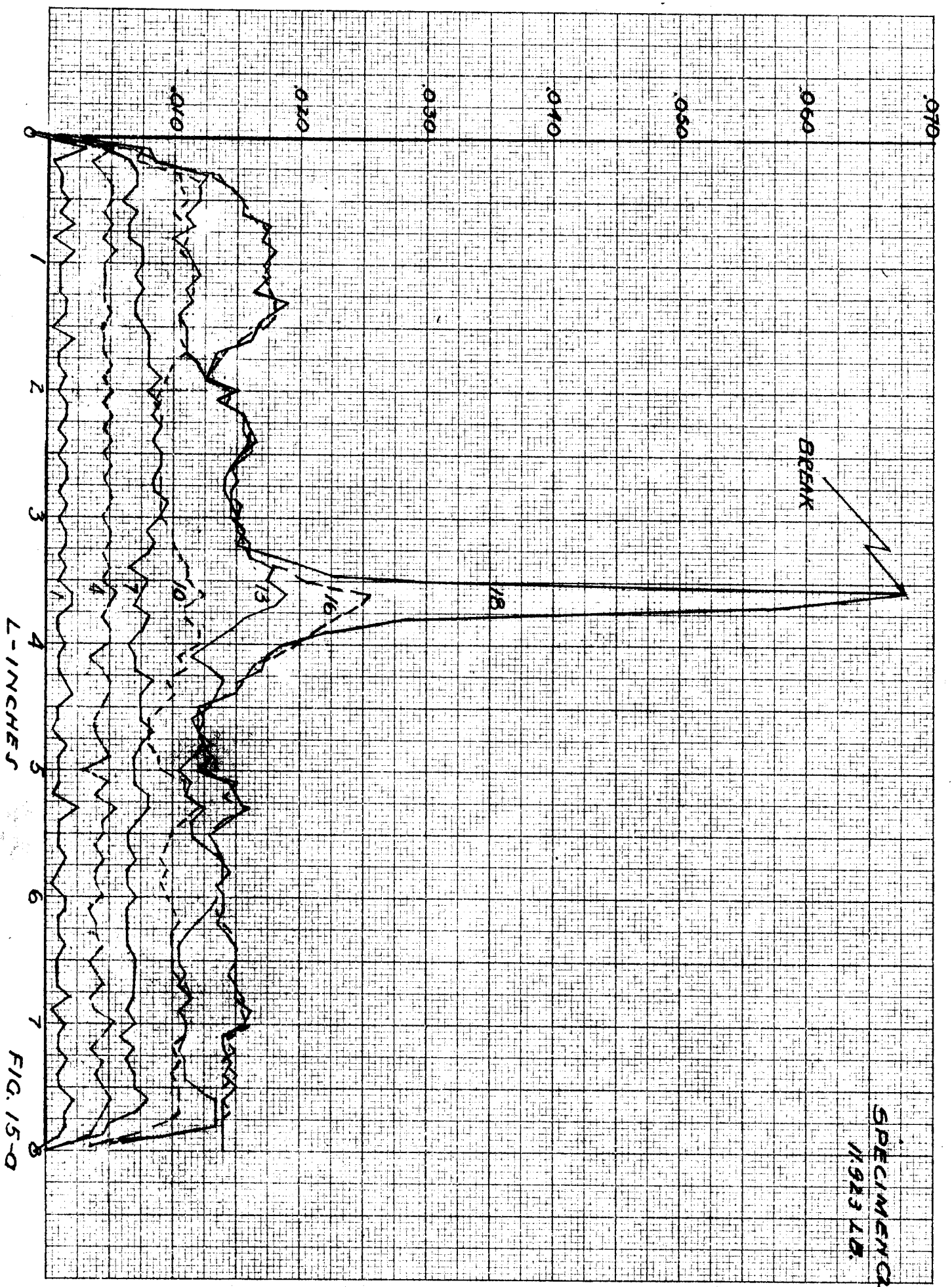
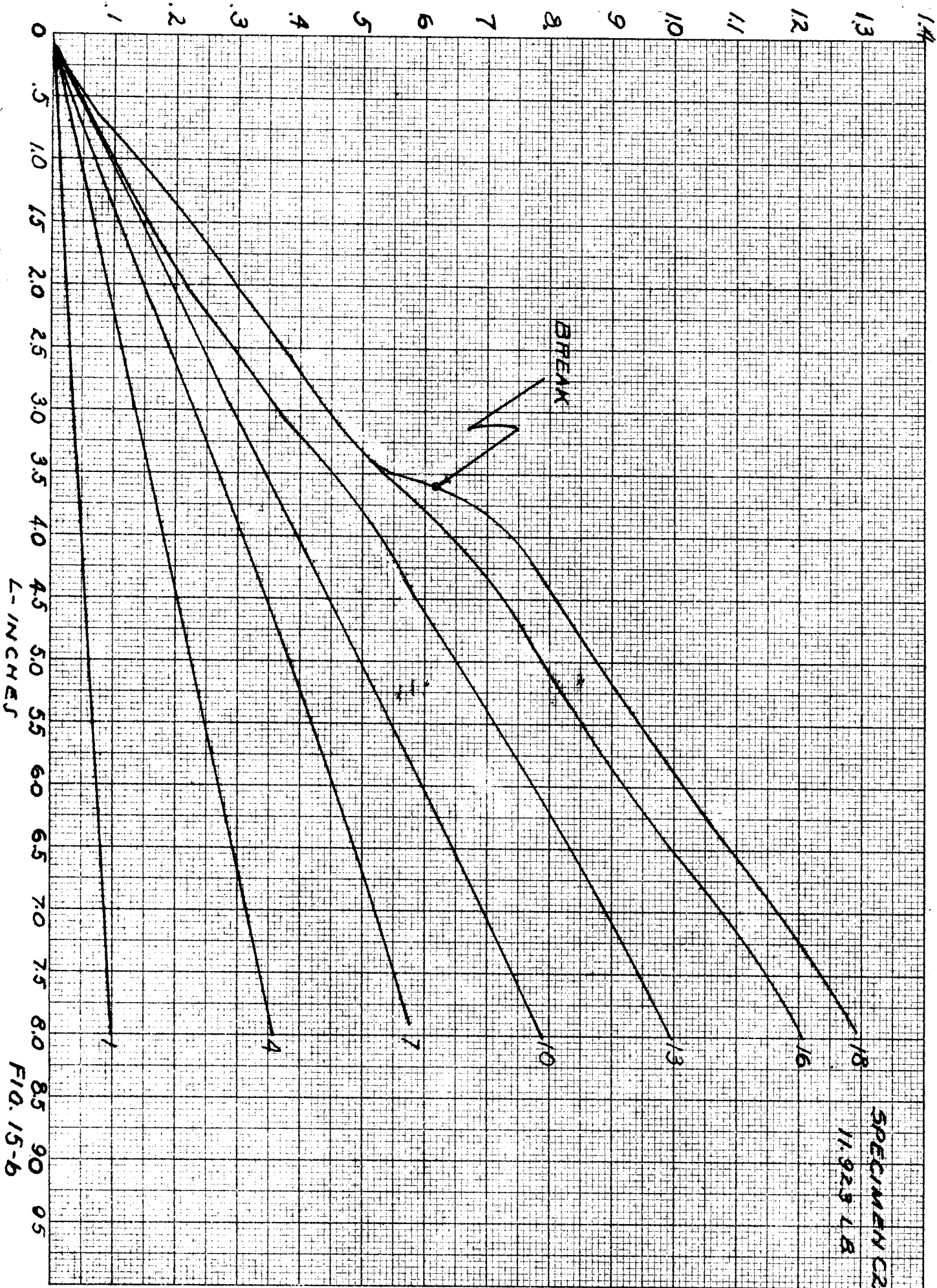
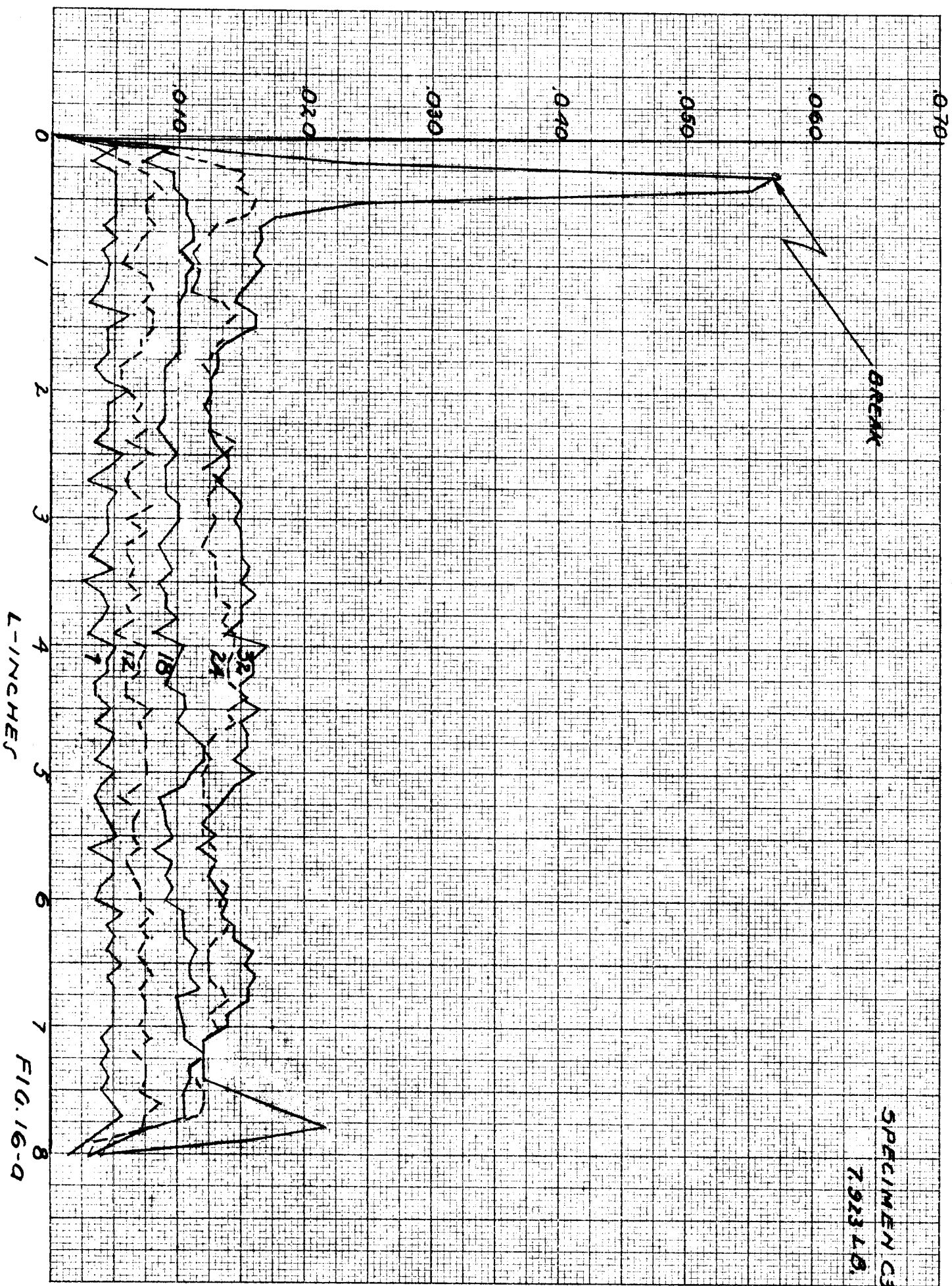


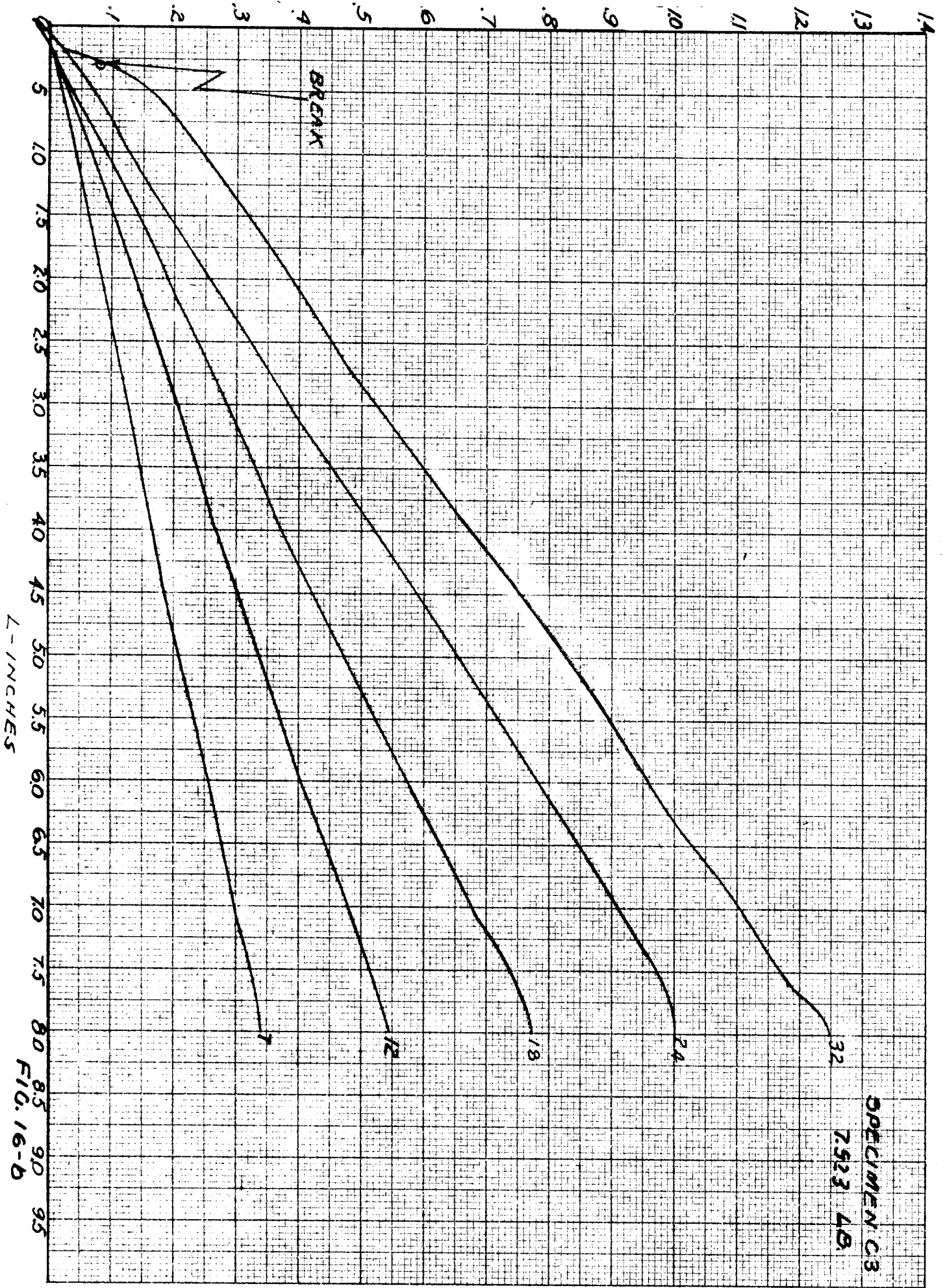
FIG. 14-b





SPECIMEN C2
11.925 LB



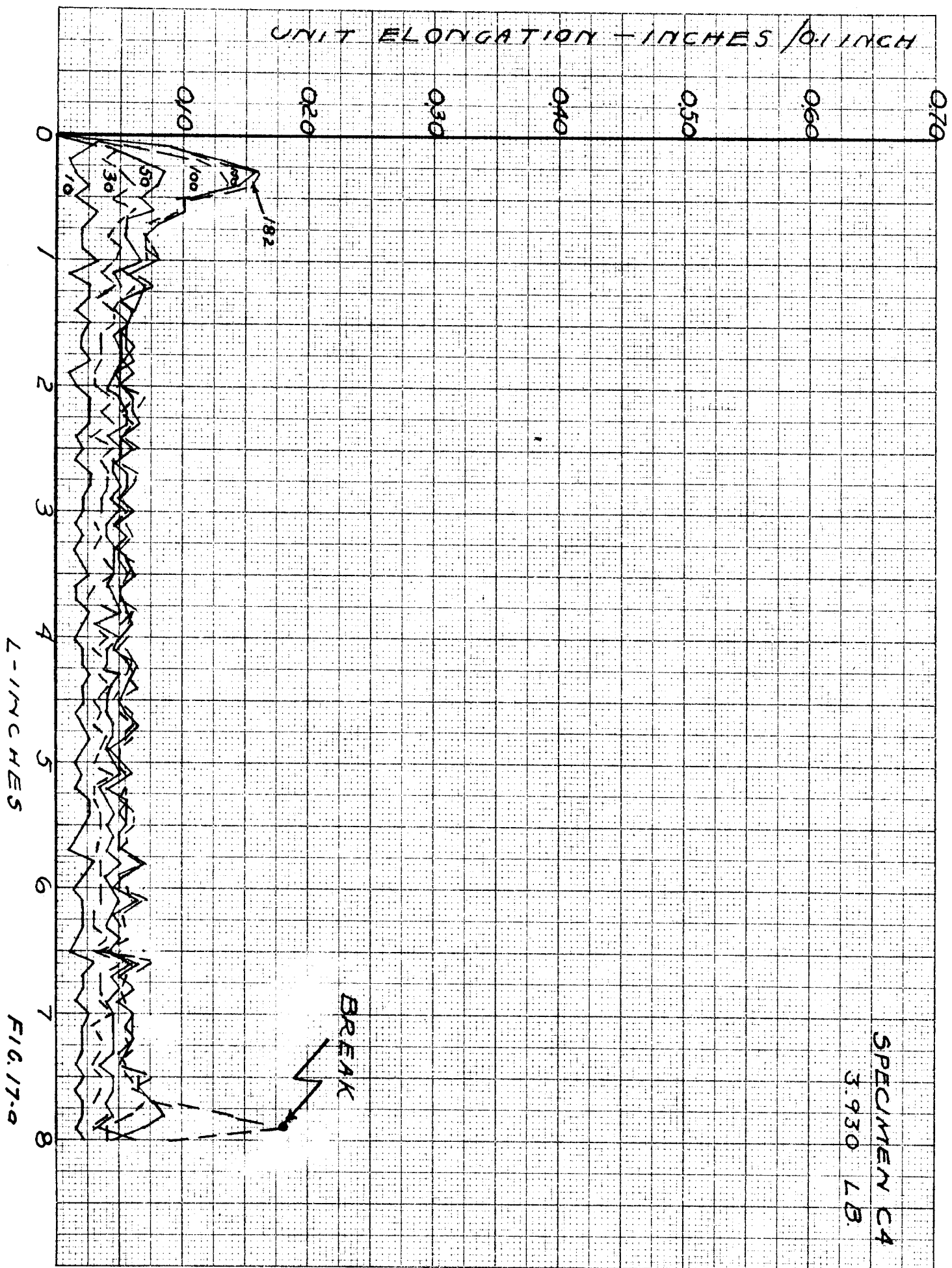


SPECIMEN C3

7523 LB.

F10.16-b

L - INCHES



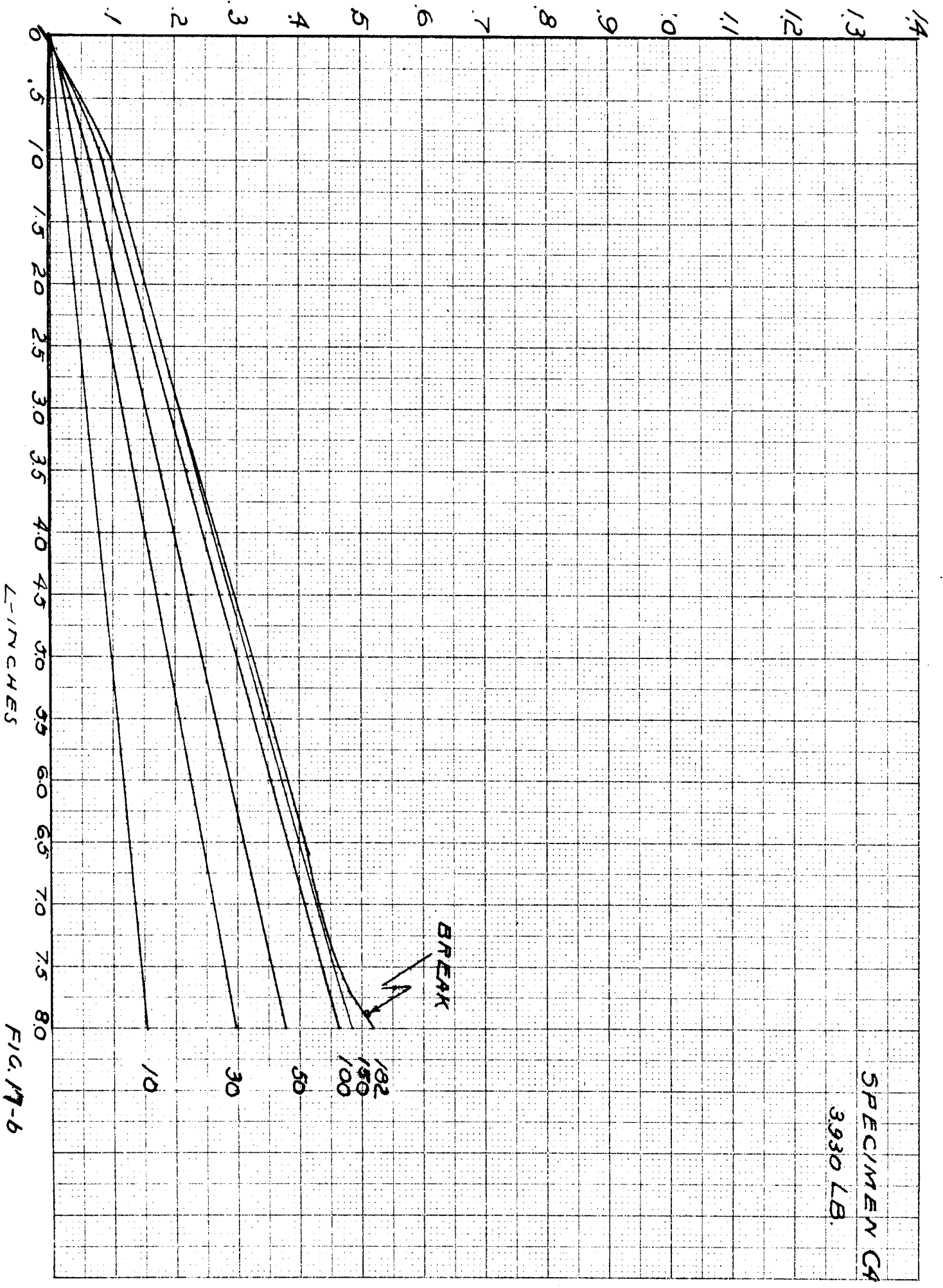


FIG. 17-6

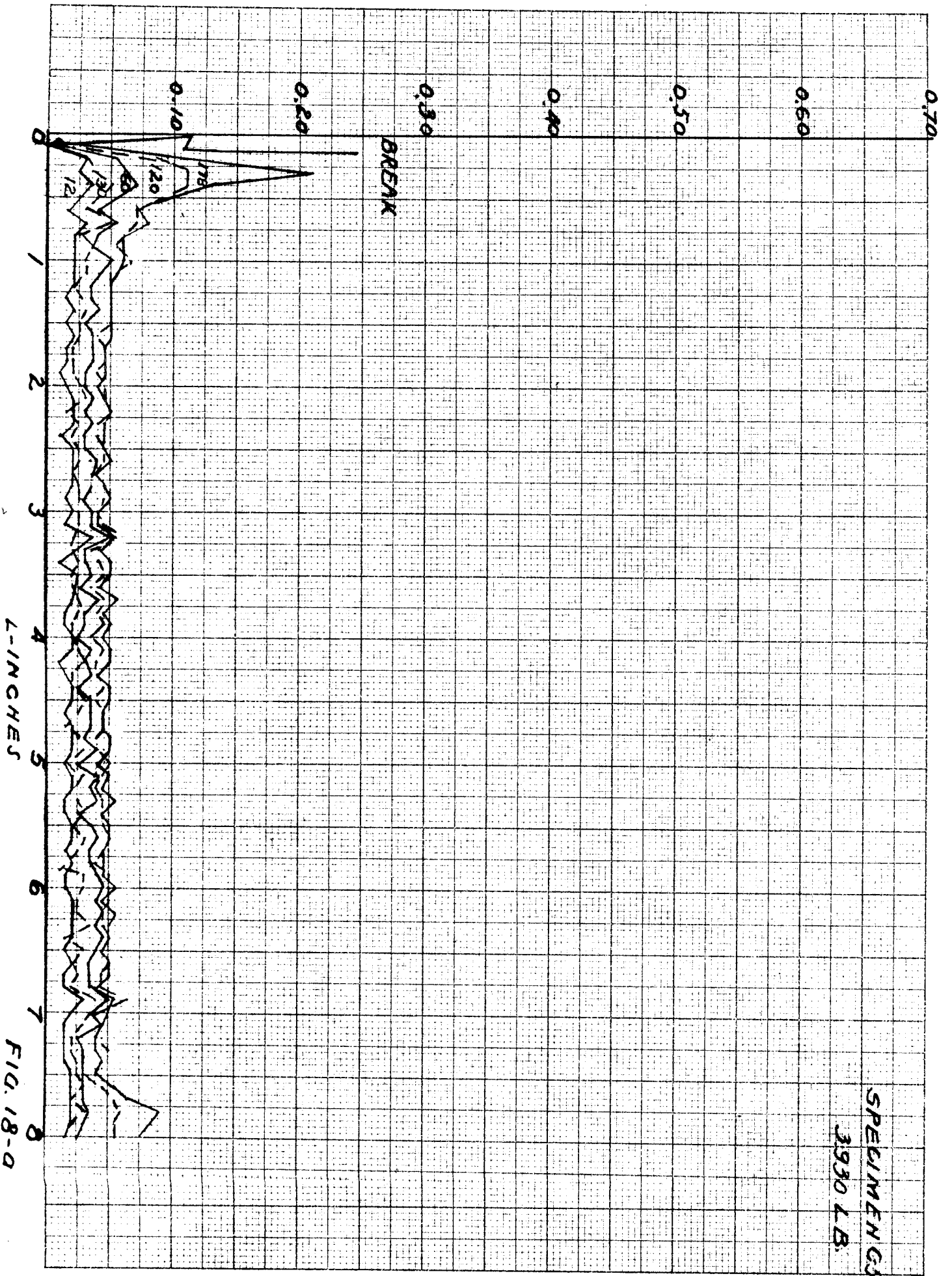
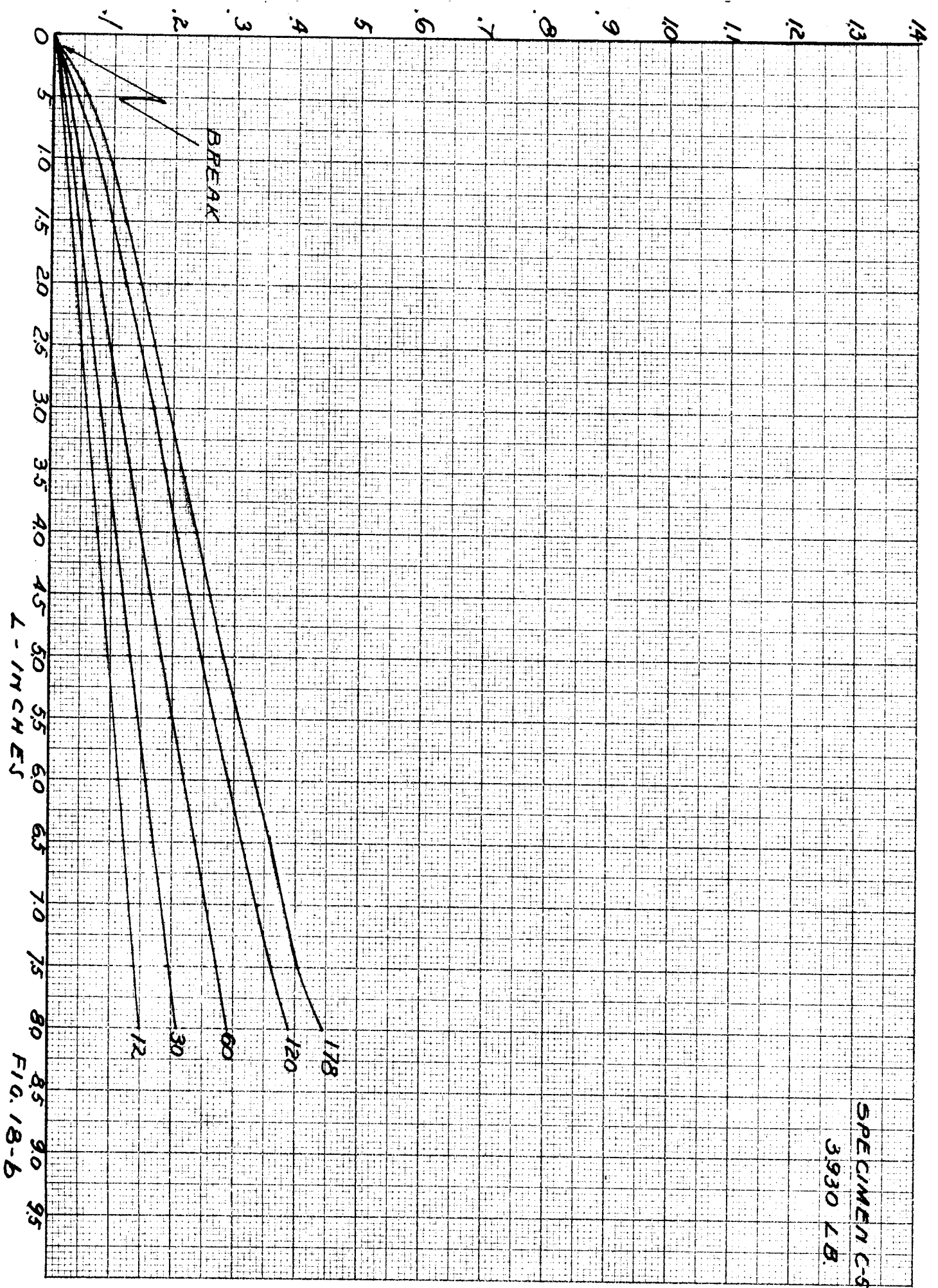


FIG. 18-0

SPECIMEN C-5
3.930 L.B.



L - INCHES

F10.18-6

UNIT ELONGATION - INCHES / 0.2 INCH

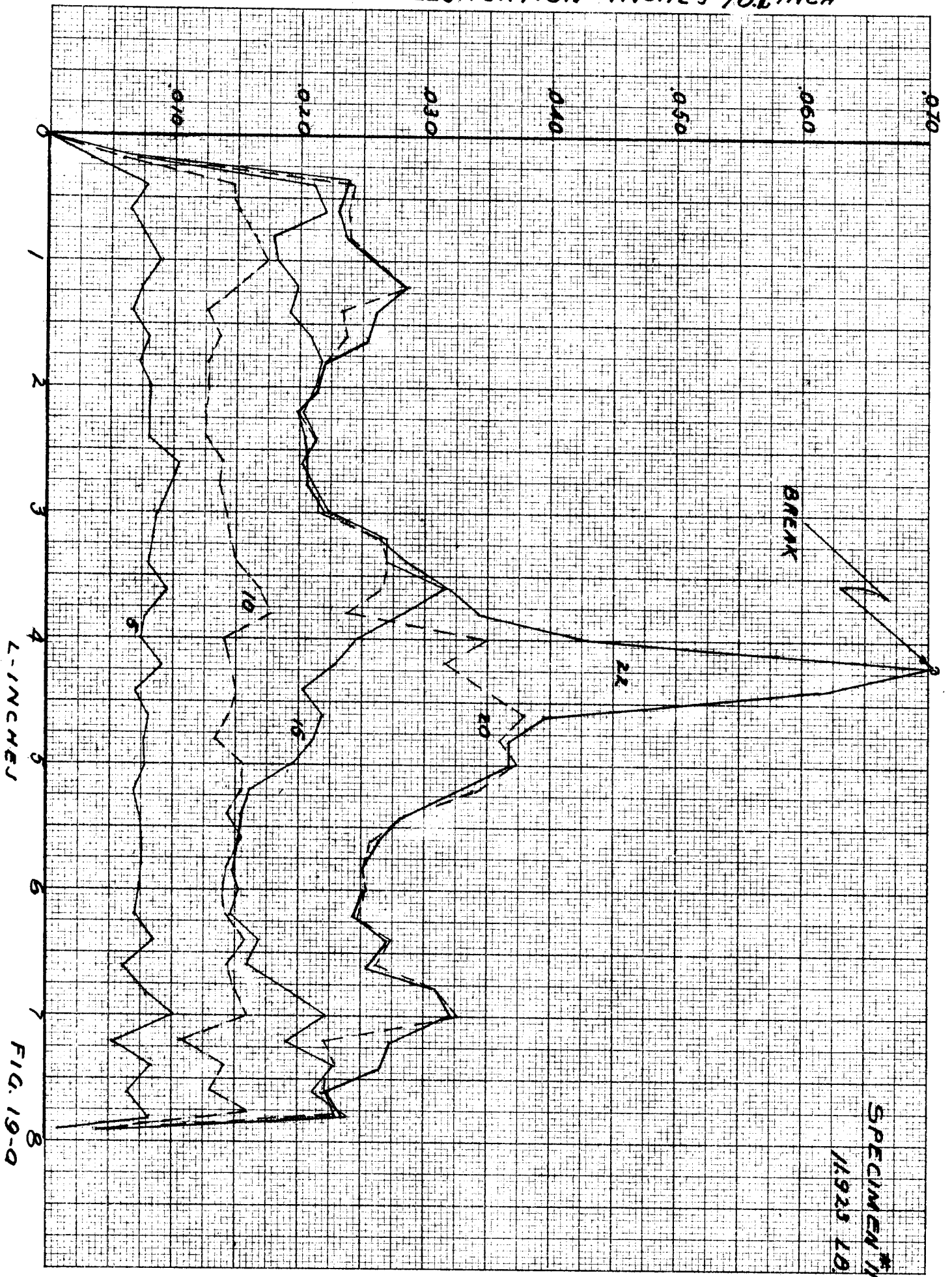
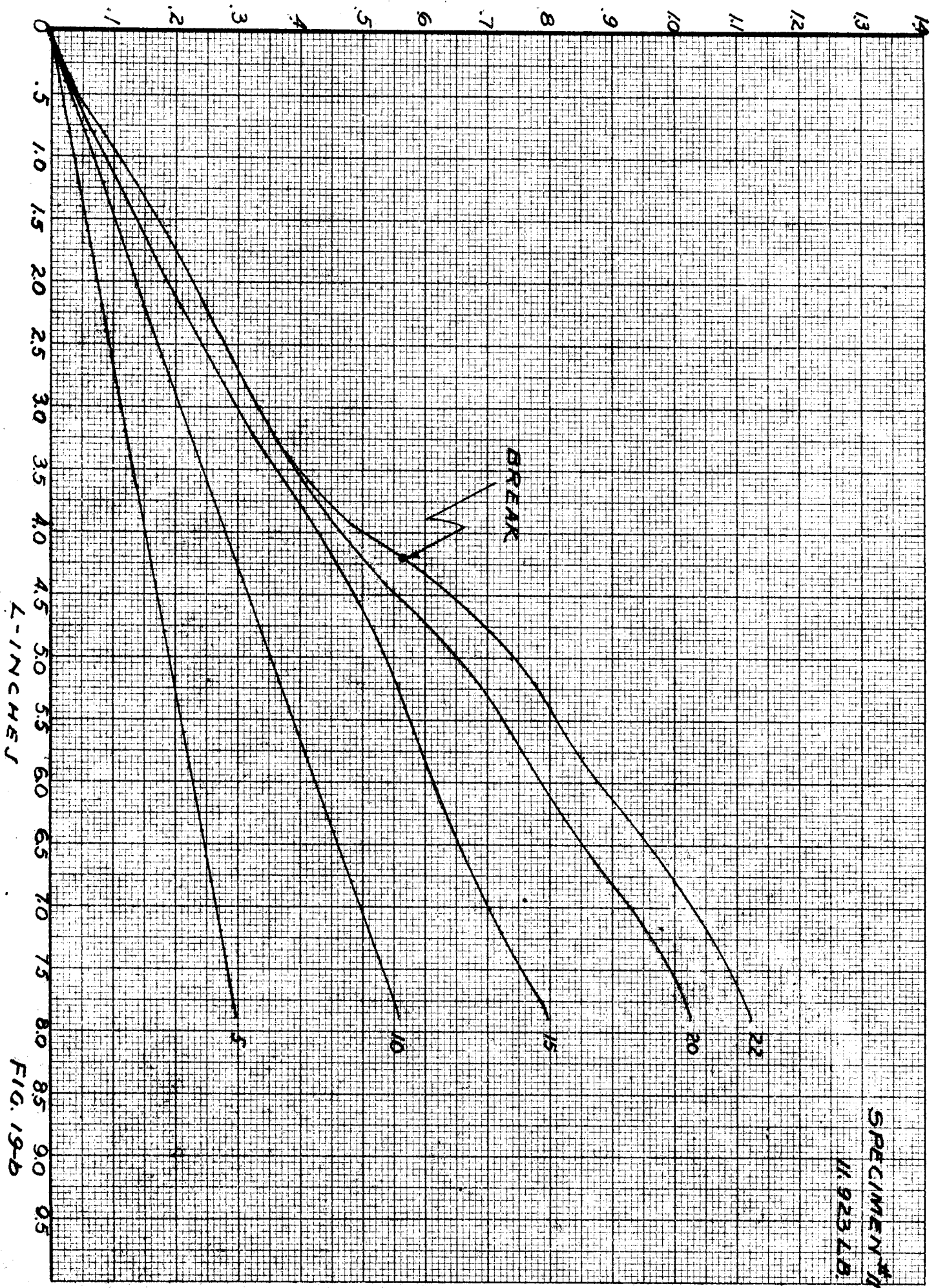


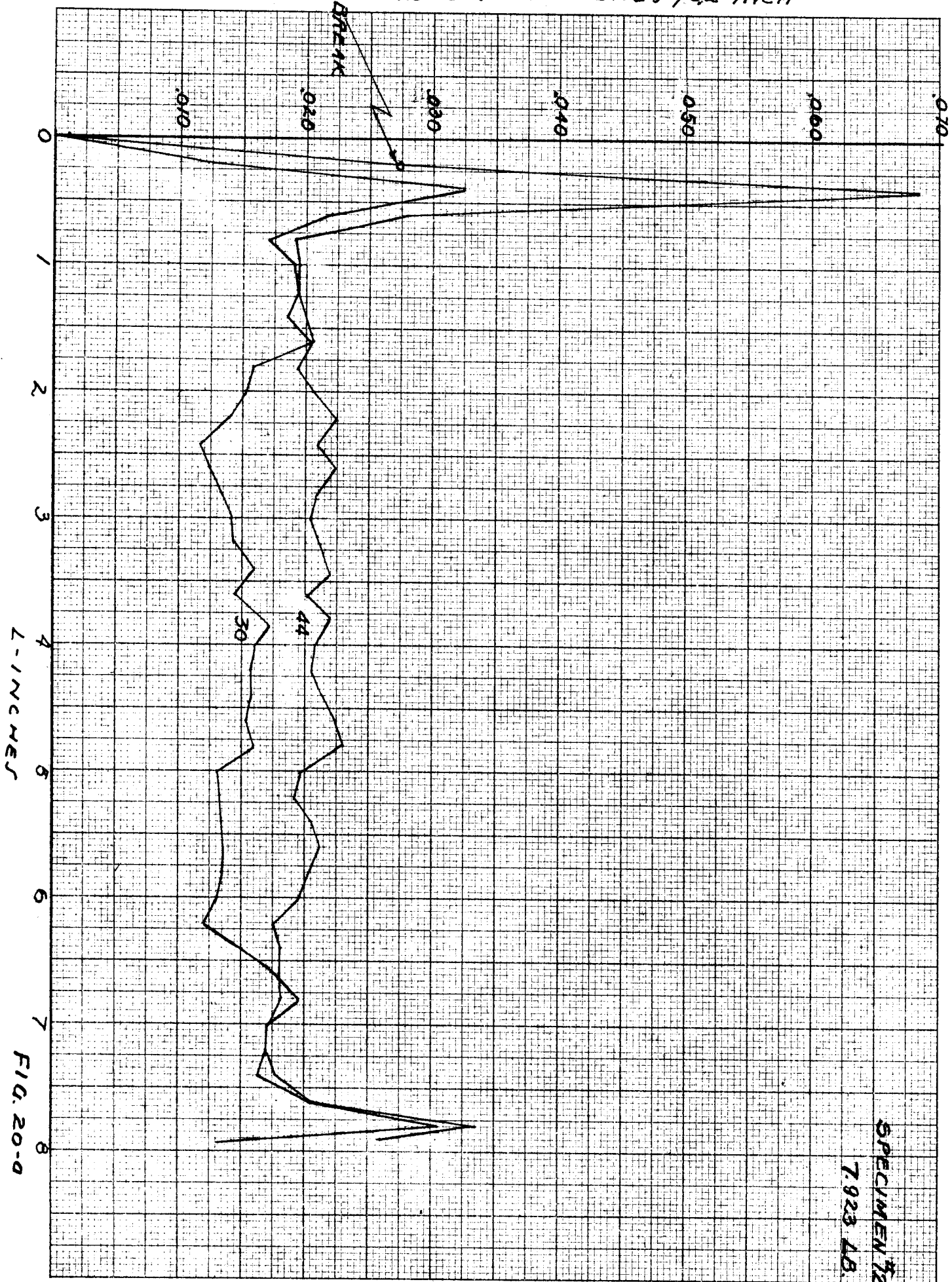
FIG. 19-0



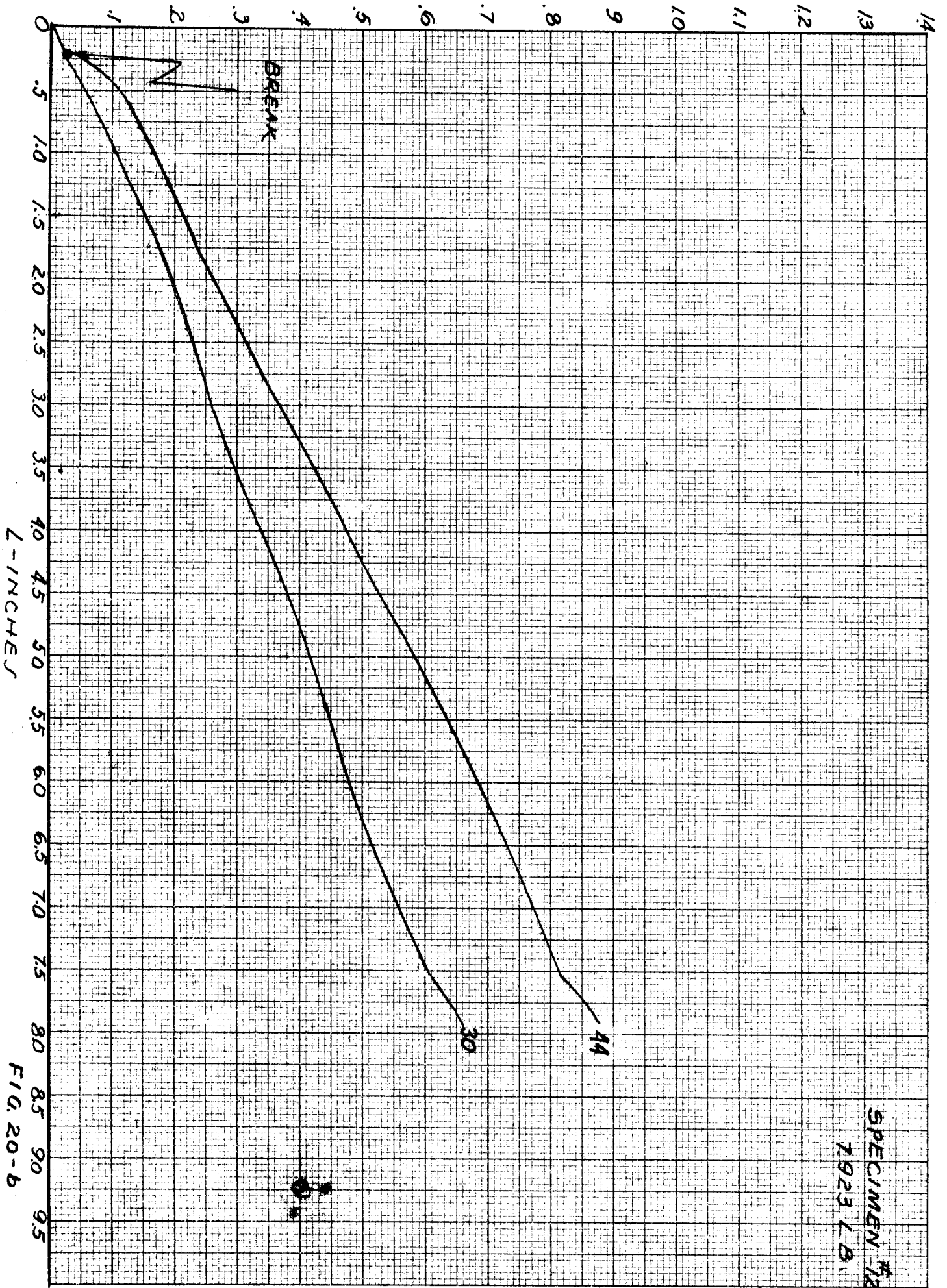
SPECIMEN #1
11.923LB.

FIG. 19-b

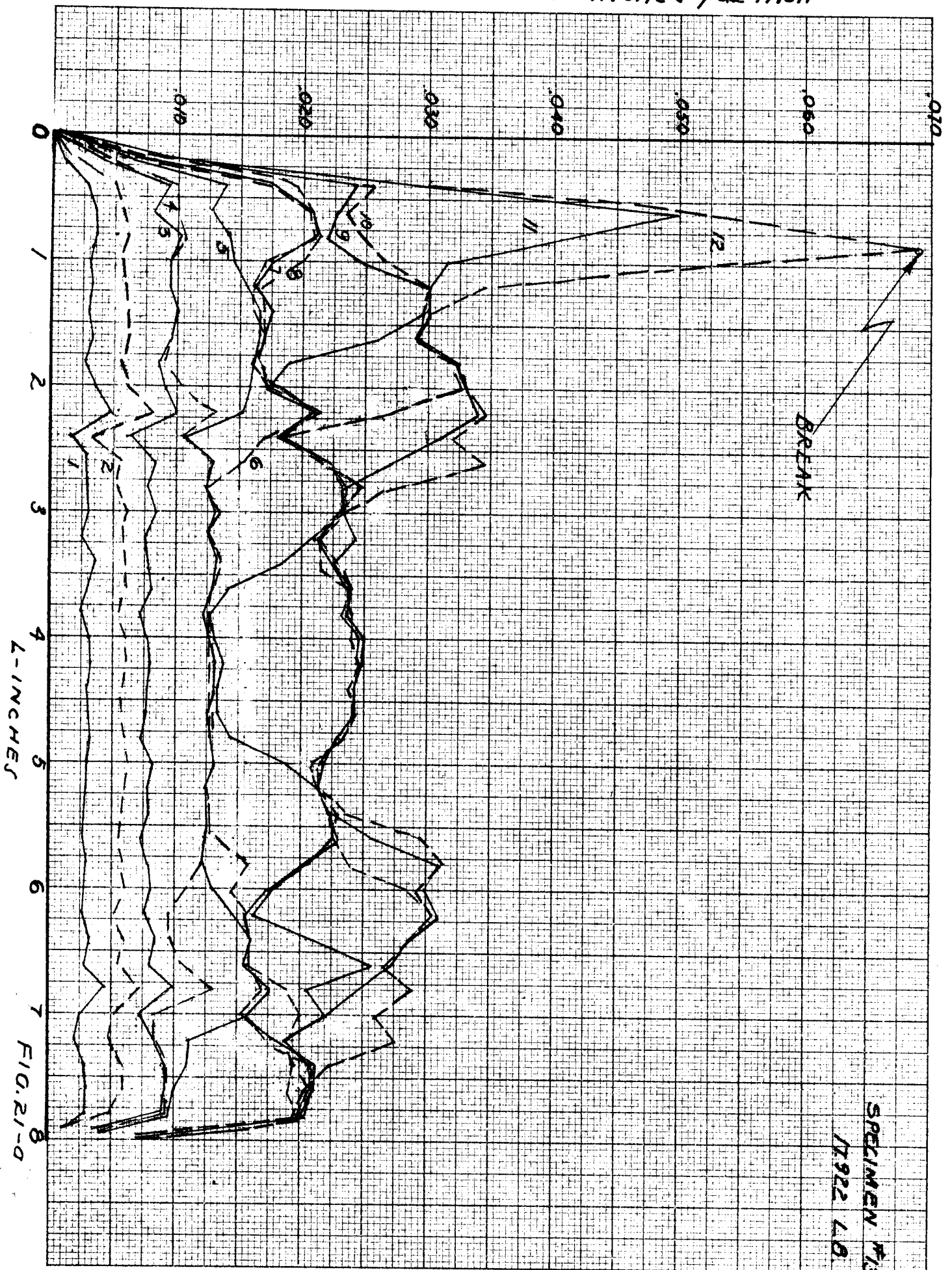
UNIT ELONGATION - INCHES / 0.2 INCH

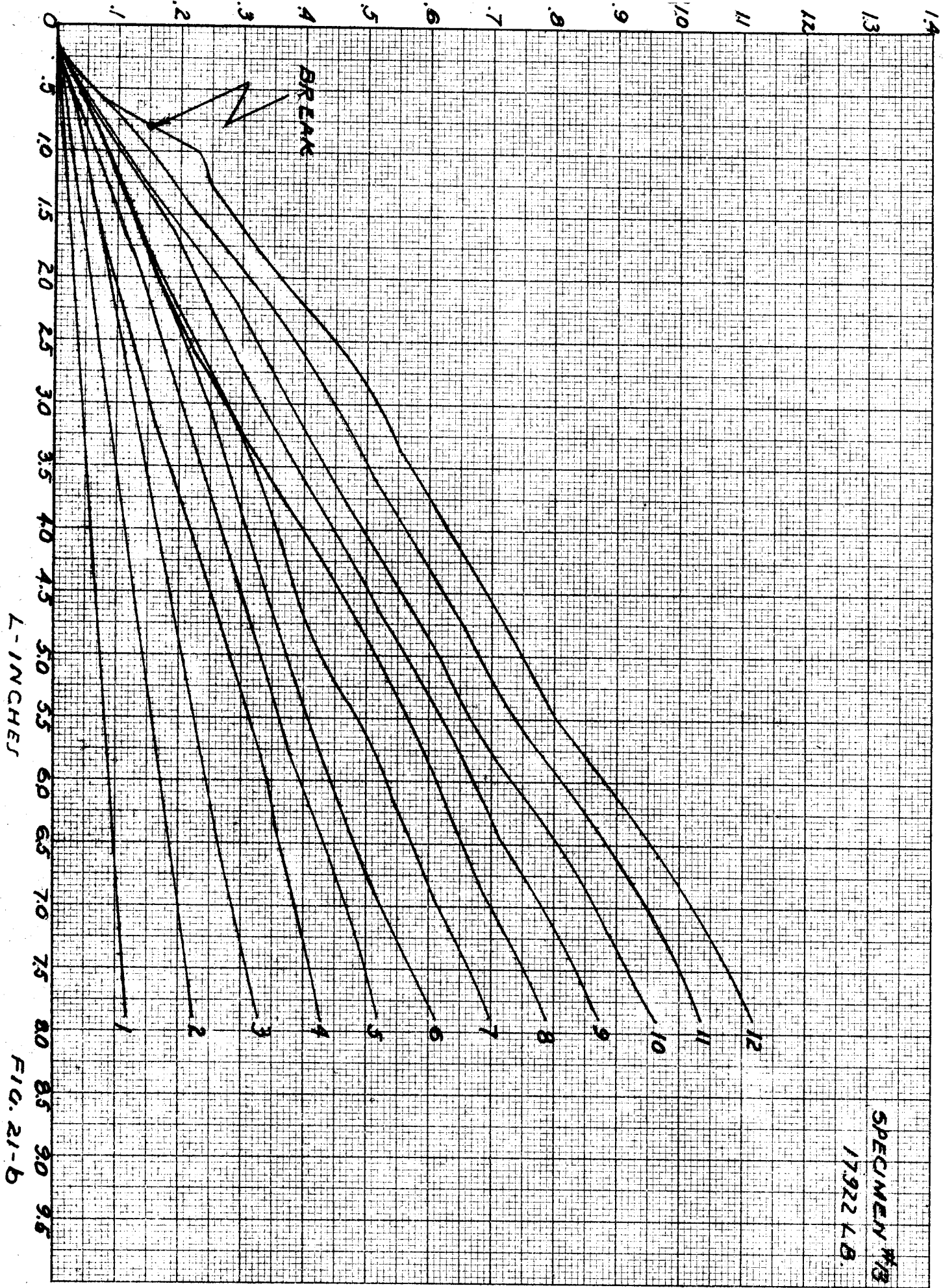


SPECIMEN #
7923 AB.



UNIT ELONGATION - INCHES / 0.2 INCH





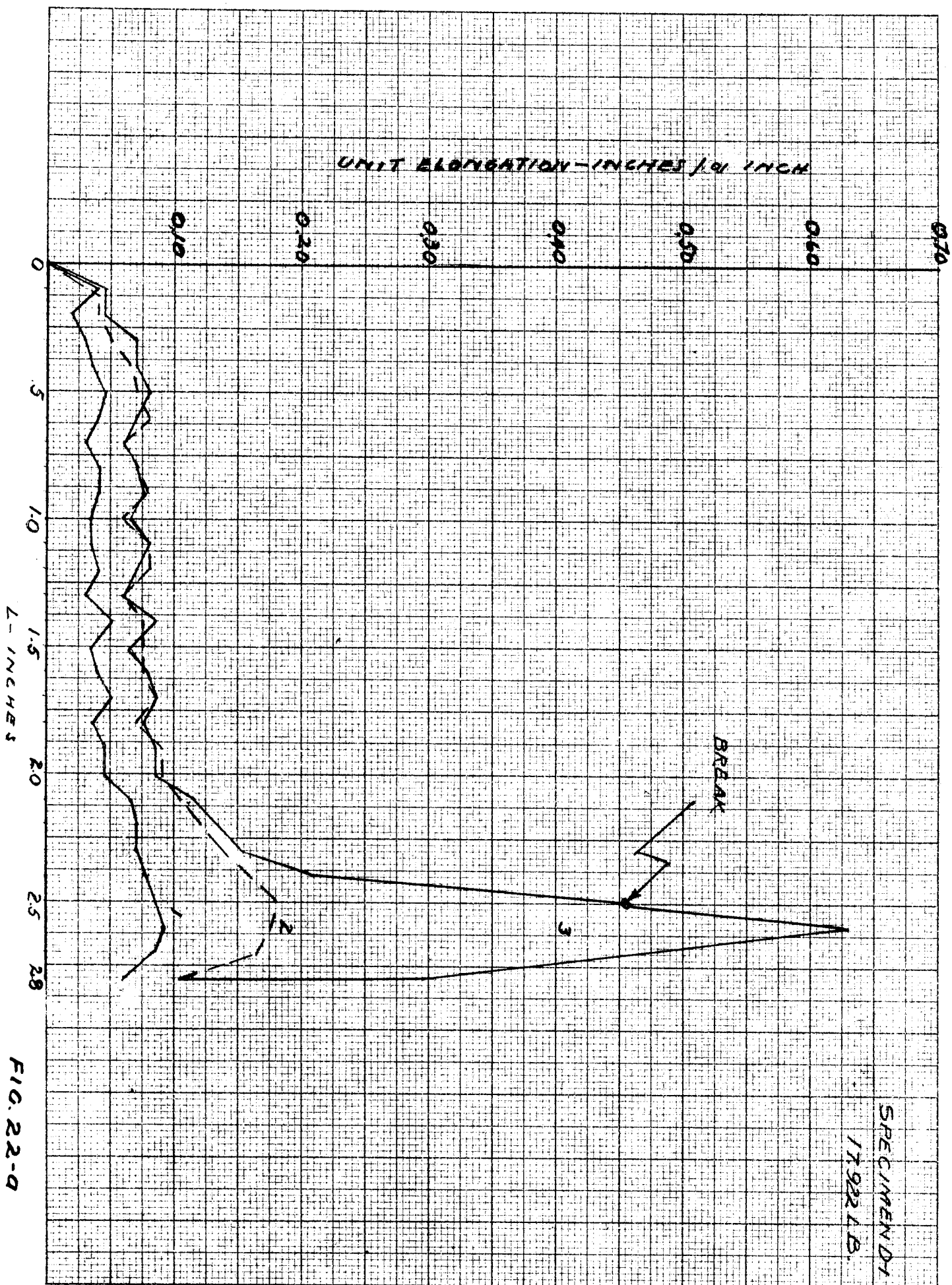


FIG. 22-9

TOTAL ELONGATION - INCHES

2-INCHES

SPECIMEN D1
17,922 LB.

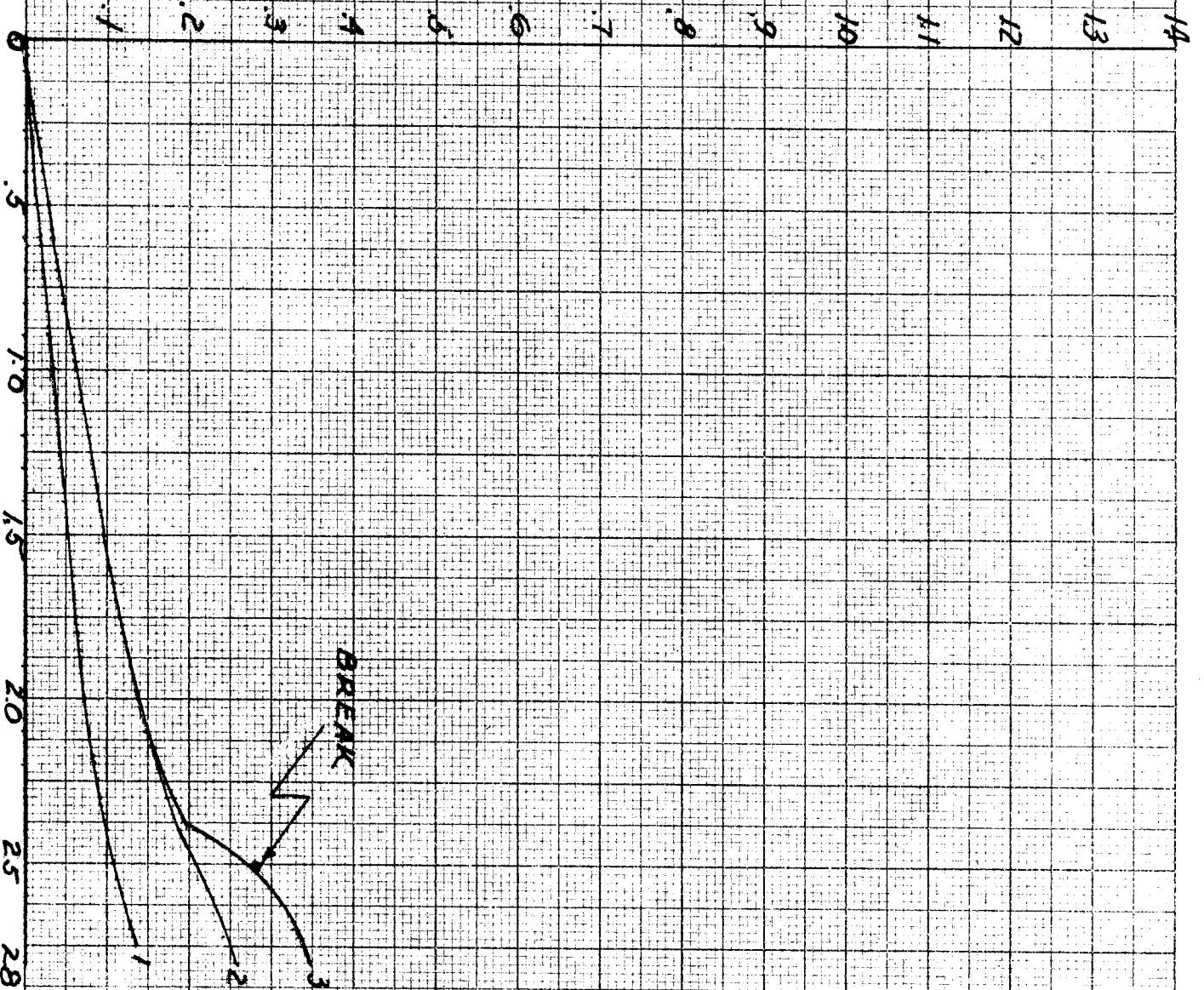


FIG. 22-b

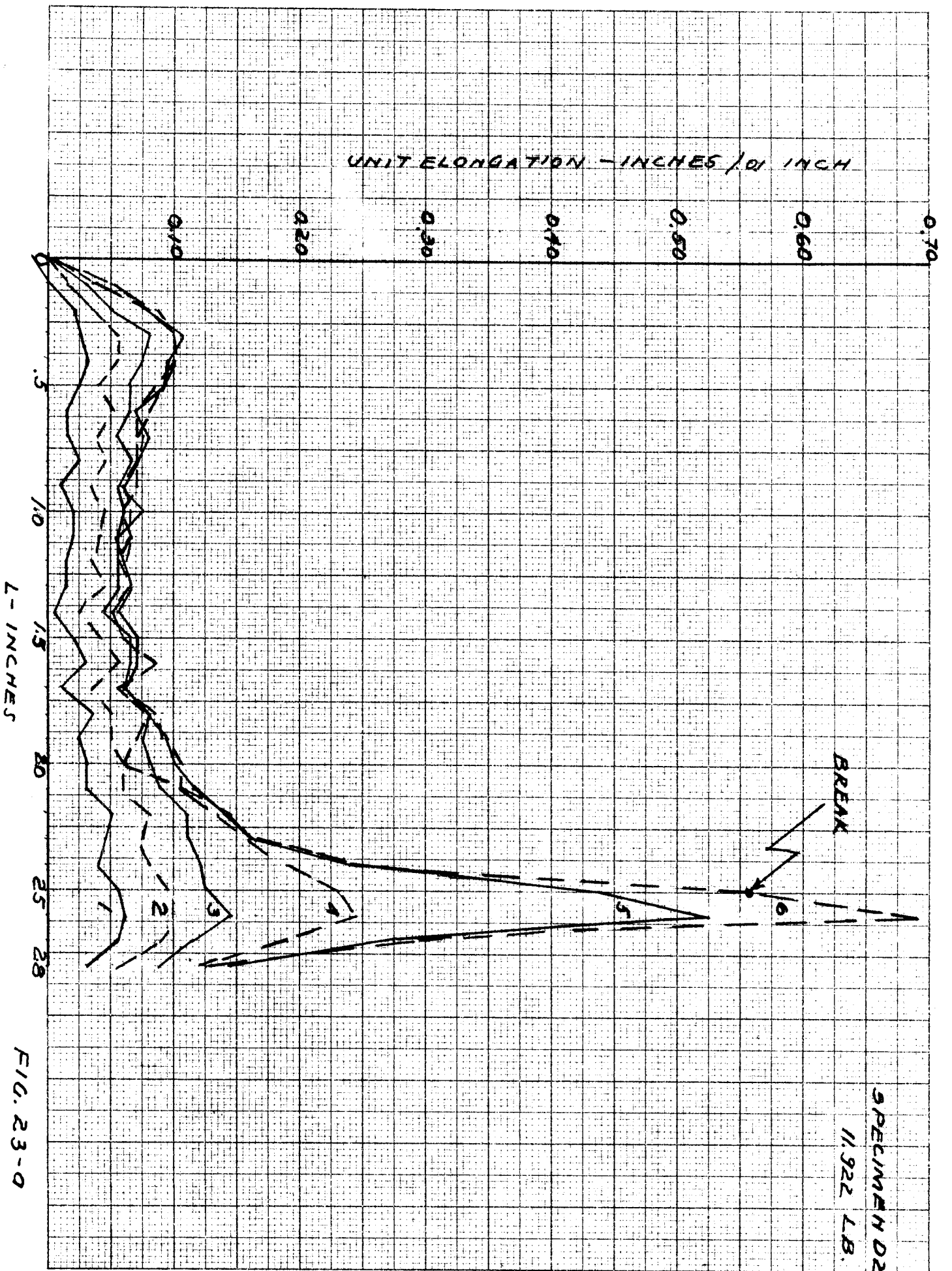
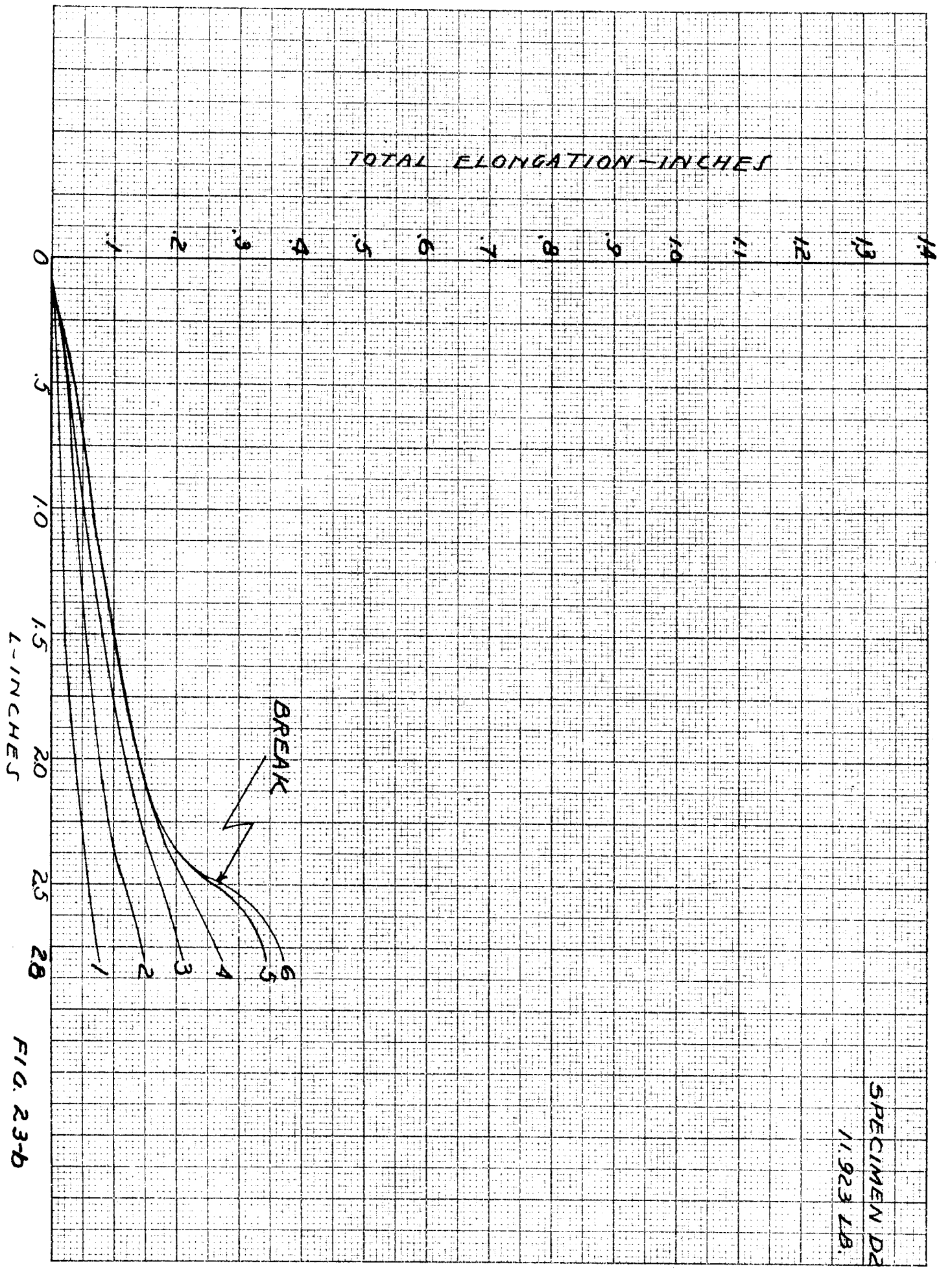
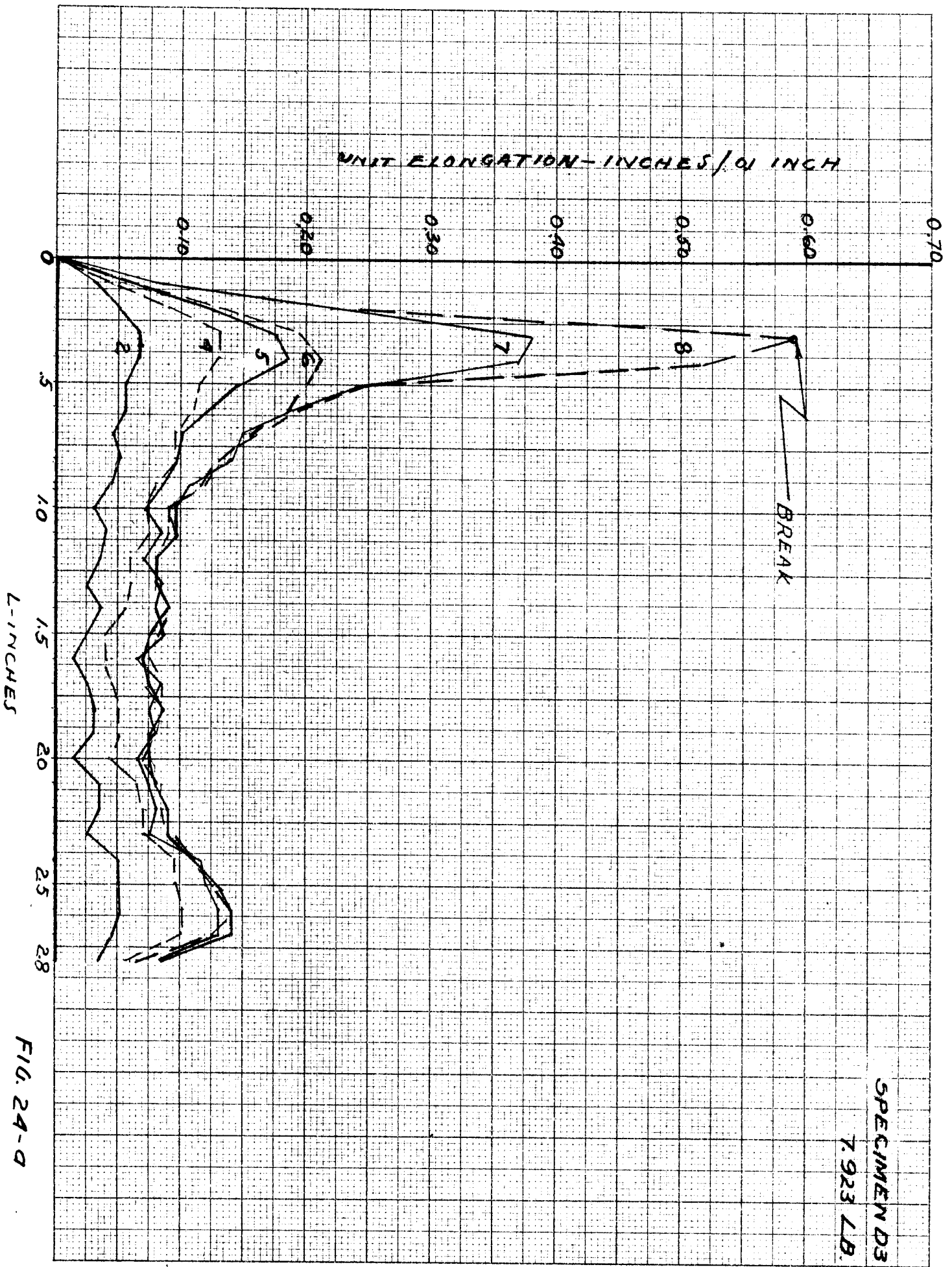


FIG. 23-0



SPECIMEN D2
11.923 LB.

FIG. 23-b



SPECIMEN D3
7.923 LB.

FIG. 24-D

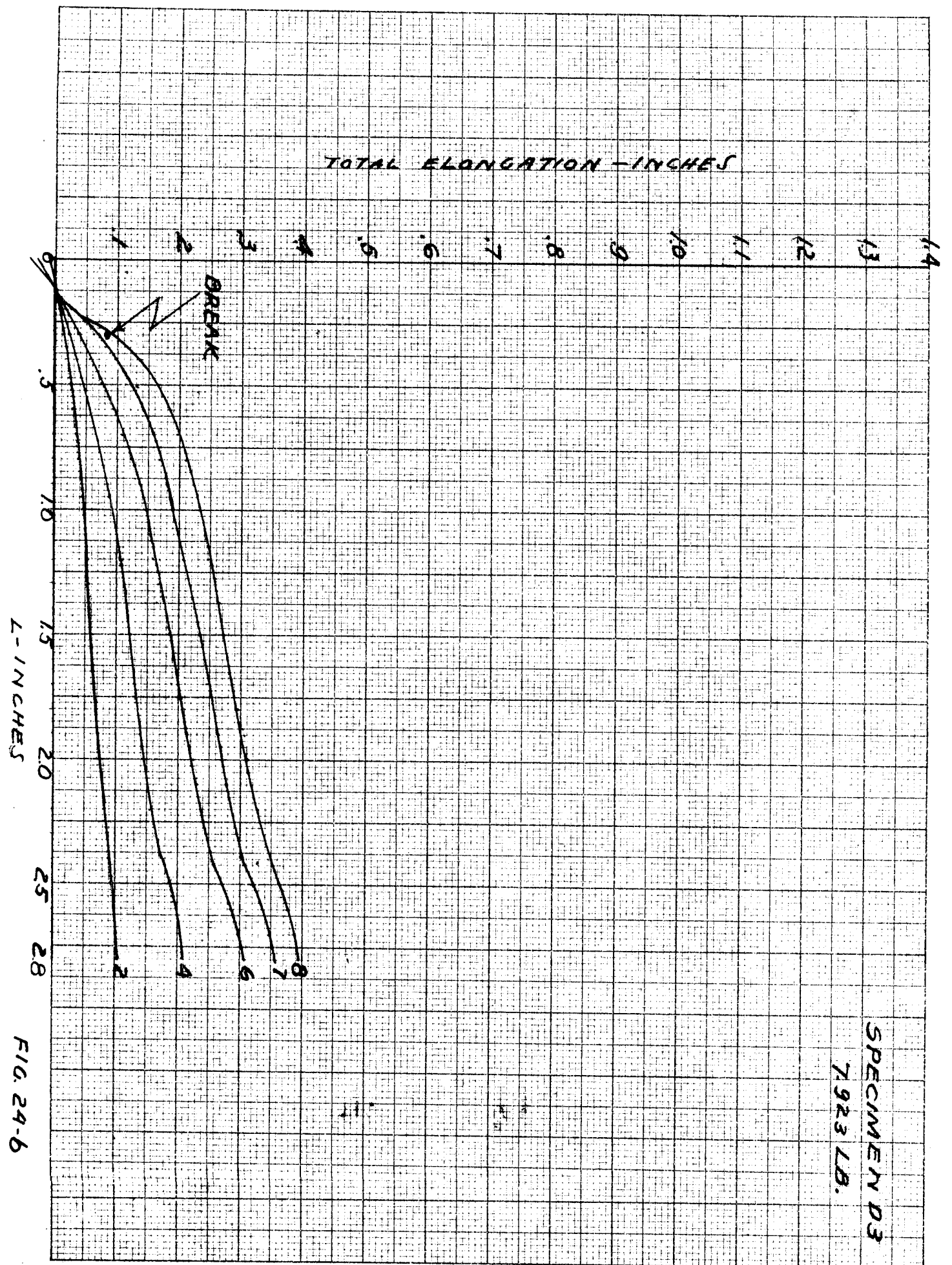


FIG. 24-6

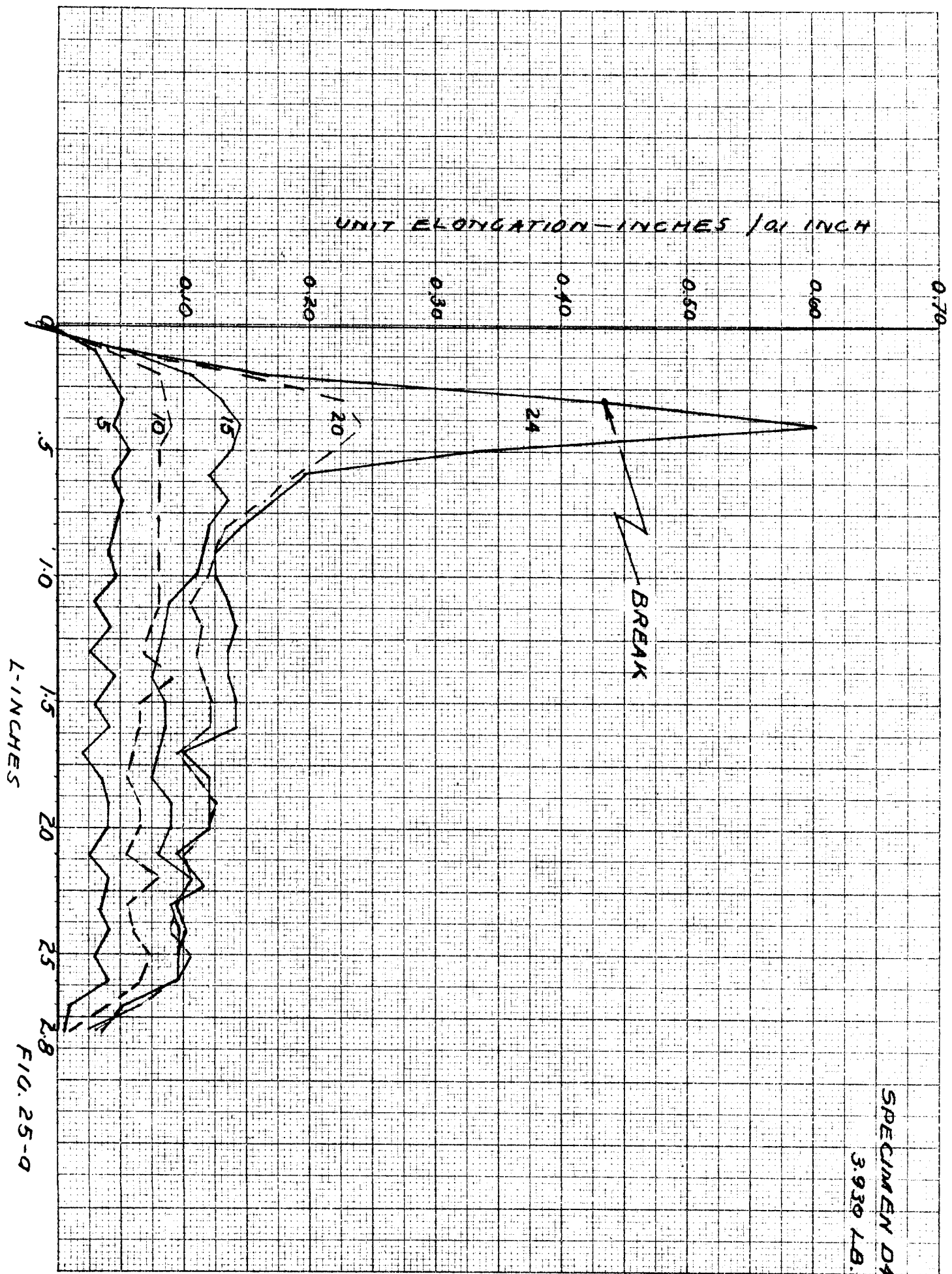
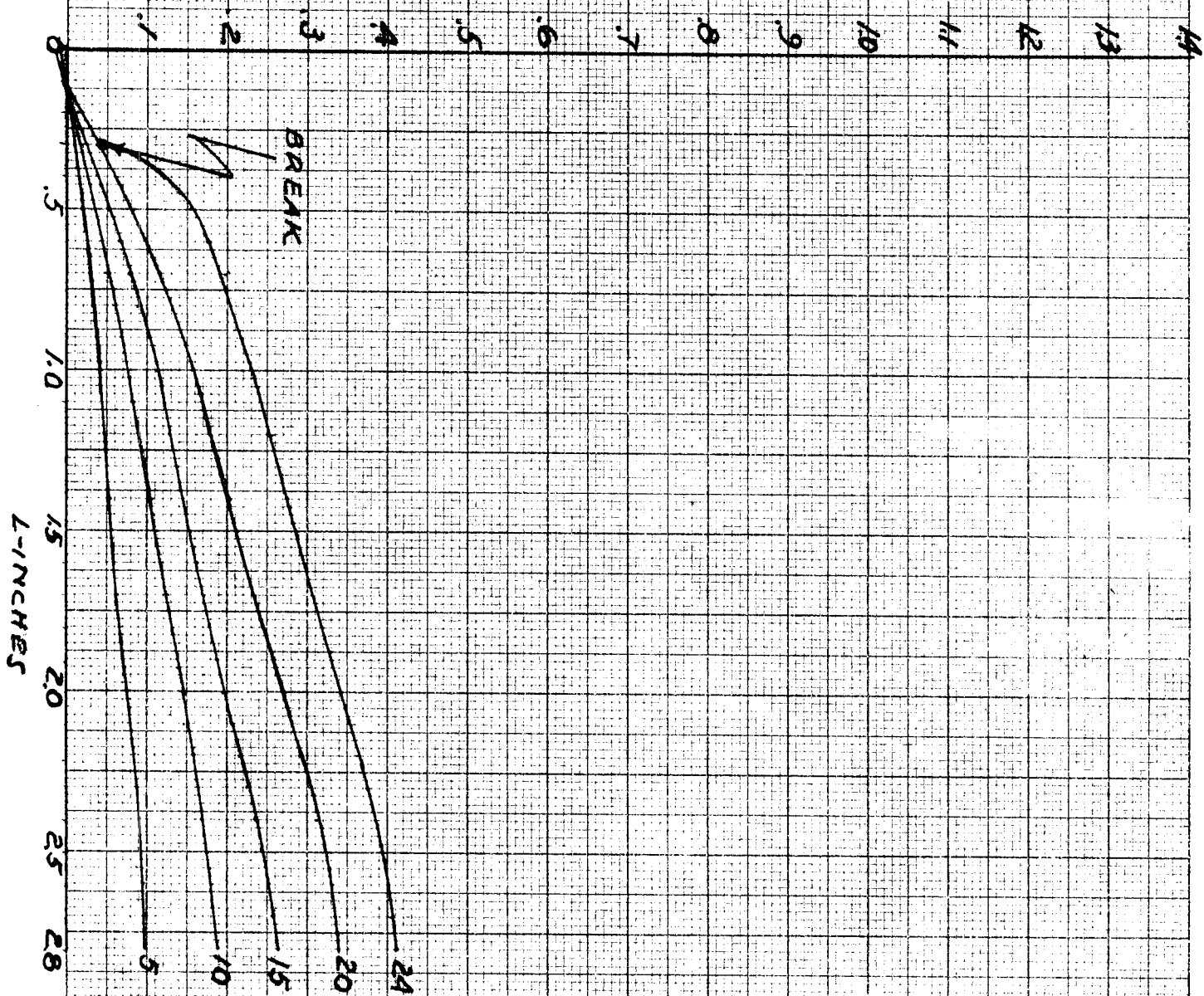


FIG. 25-0

TOTAL ELONGATION - INCHES



SPECIMEN D4
9,930 L.B.

FIG. 25-6

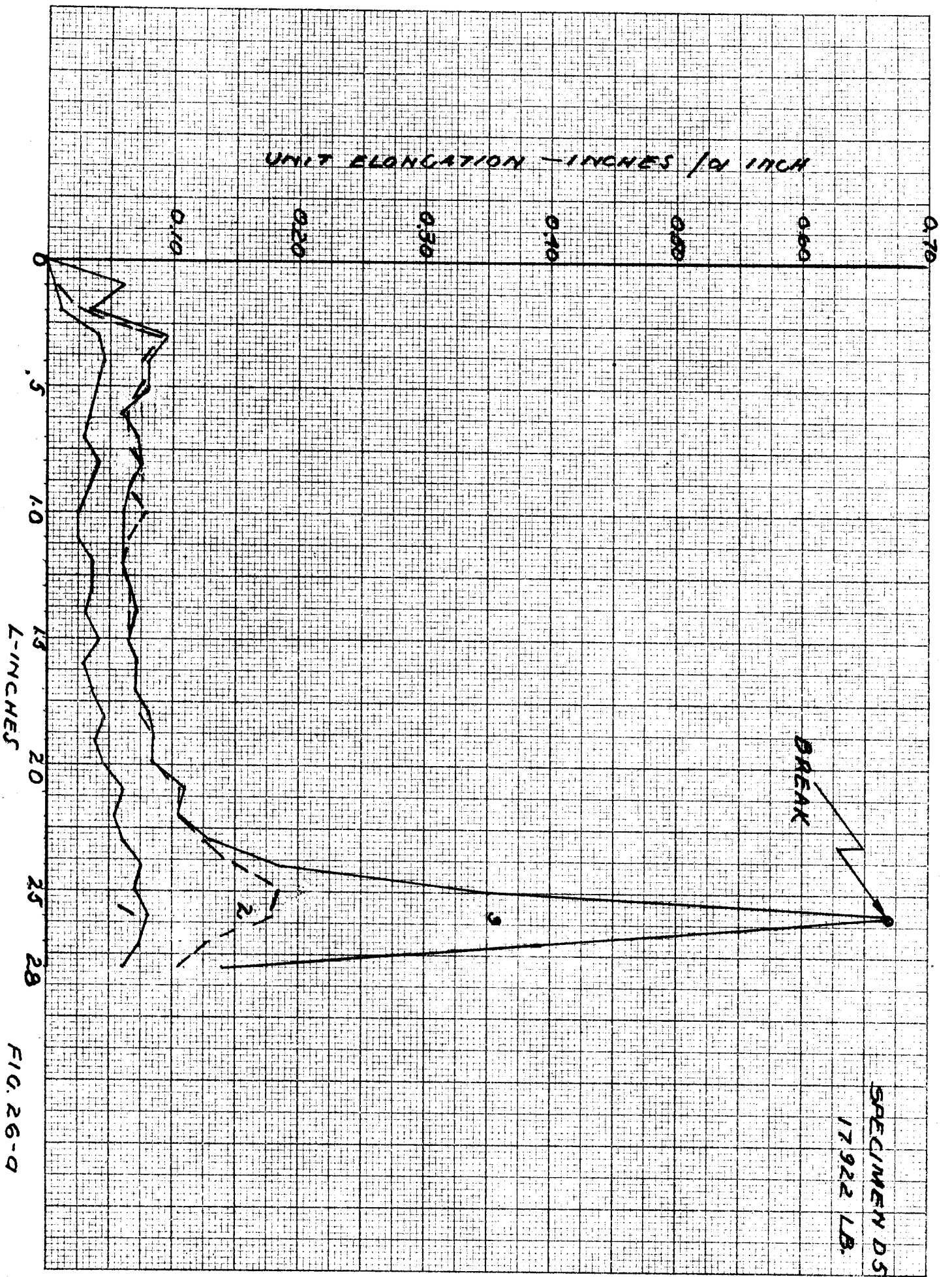
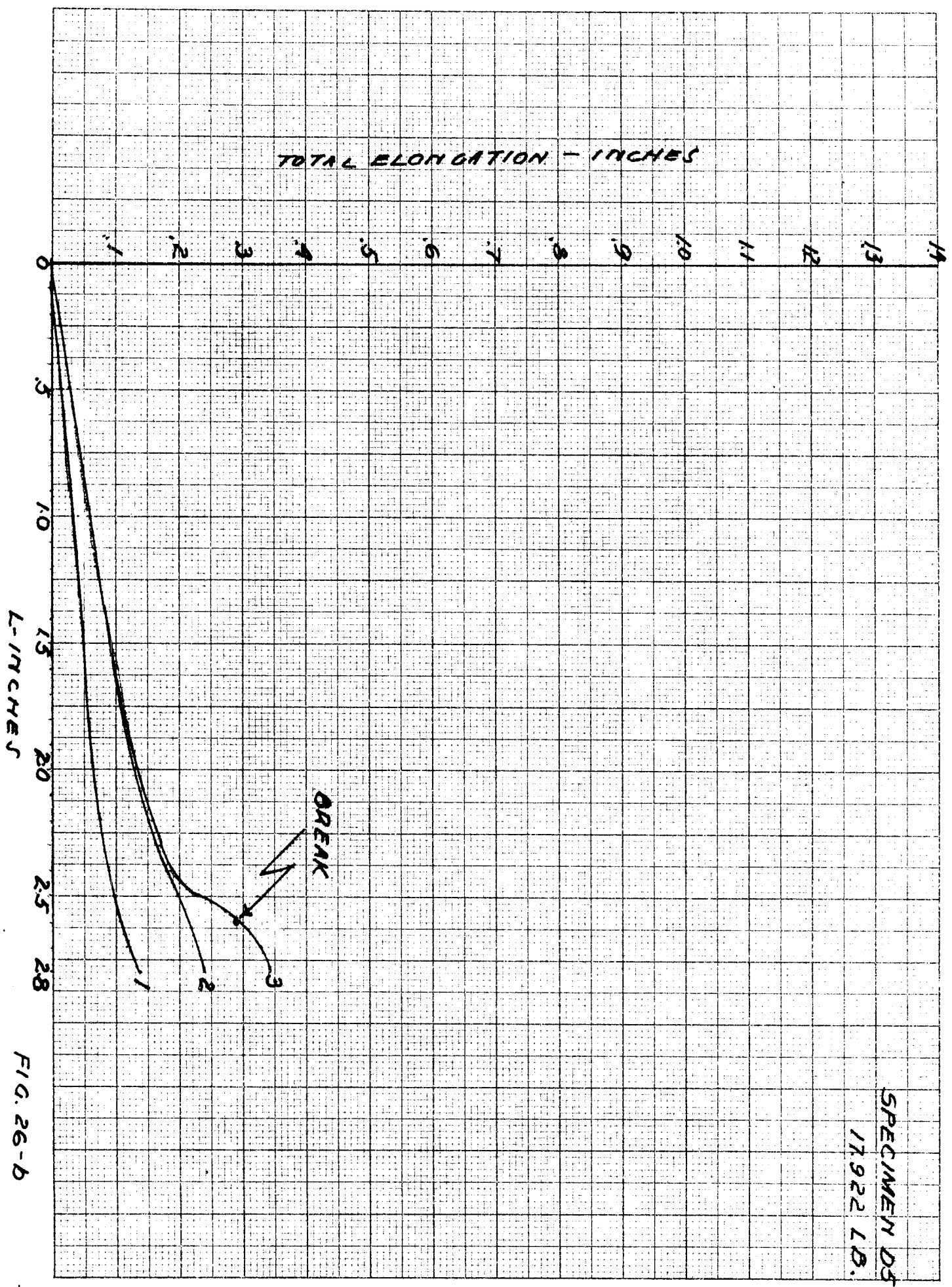


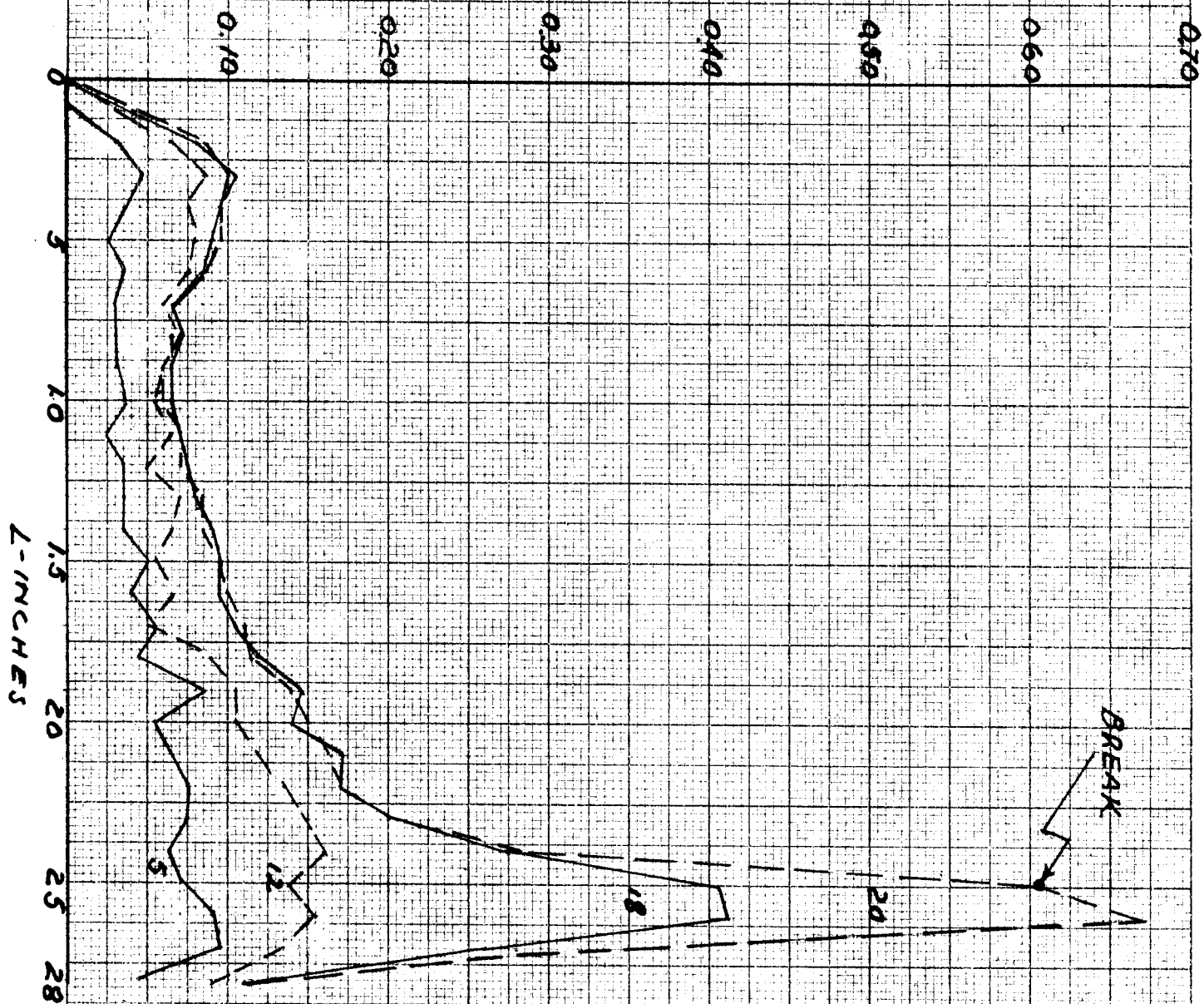
FIG. 26-9



SPECIMEN 05
17922 LB.

FIG. 26-b

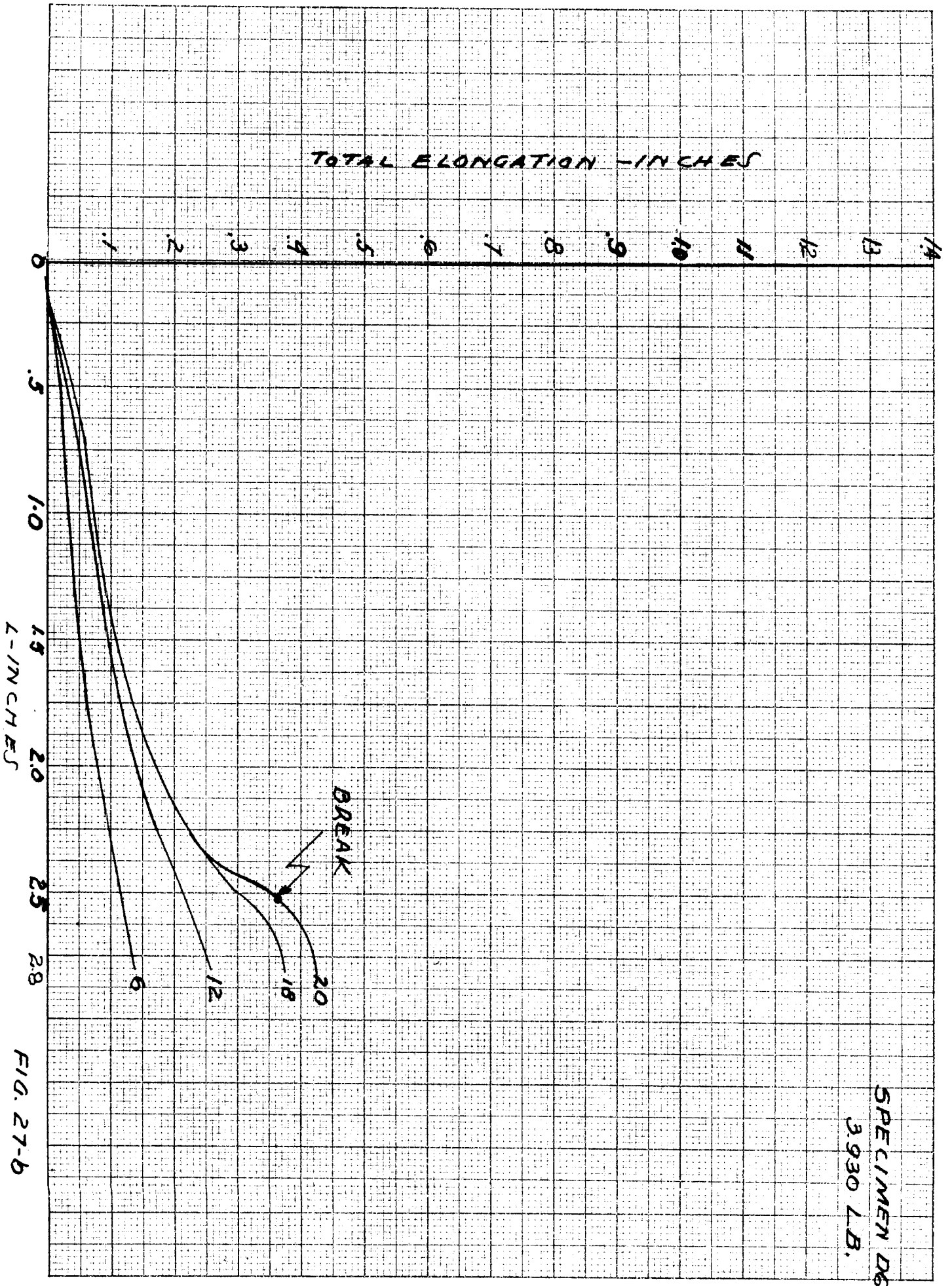
UNIT ELONGATION - INCHES / 01 INCH



SPECIMEN D6
3930 L.B.

FIG. 27-D

TOTAL ELONGATION - INCHES



SPECIMEN D6
3,930 L.B.

FIG. 27-b

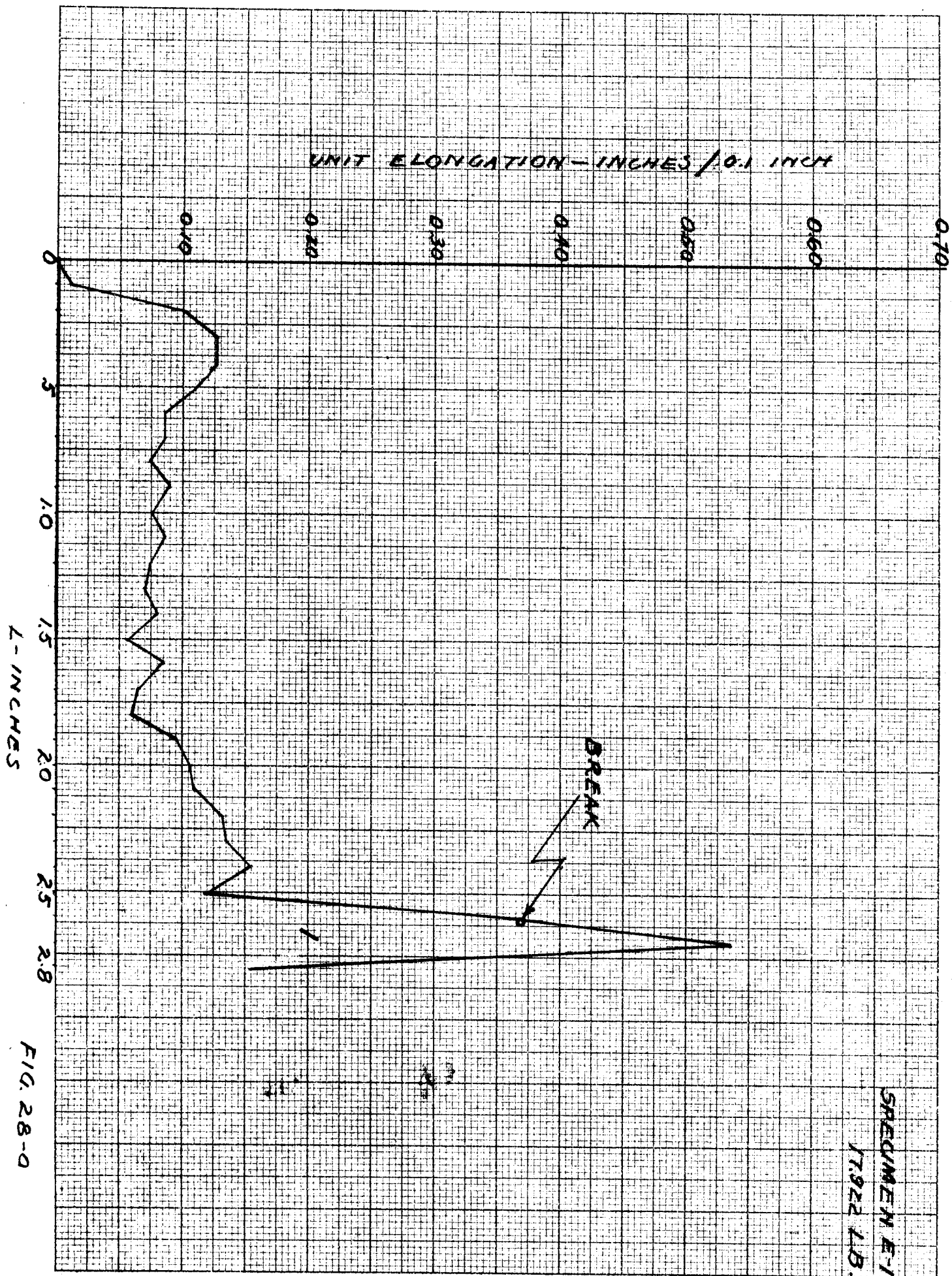


FIG. 28-0

TOTAL ELONGATION - INCHES

L-INCHES

SPECIMEN E1
17,922 LB.

BREAK

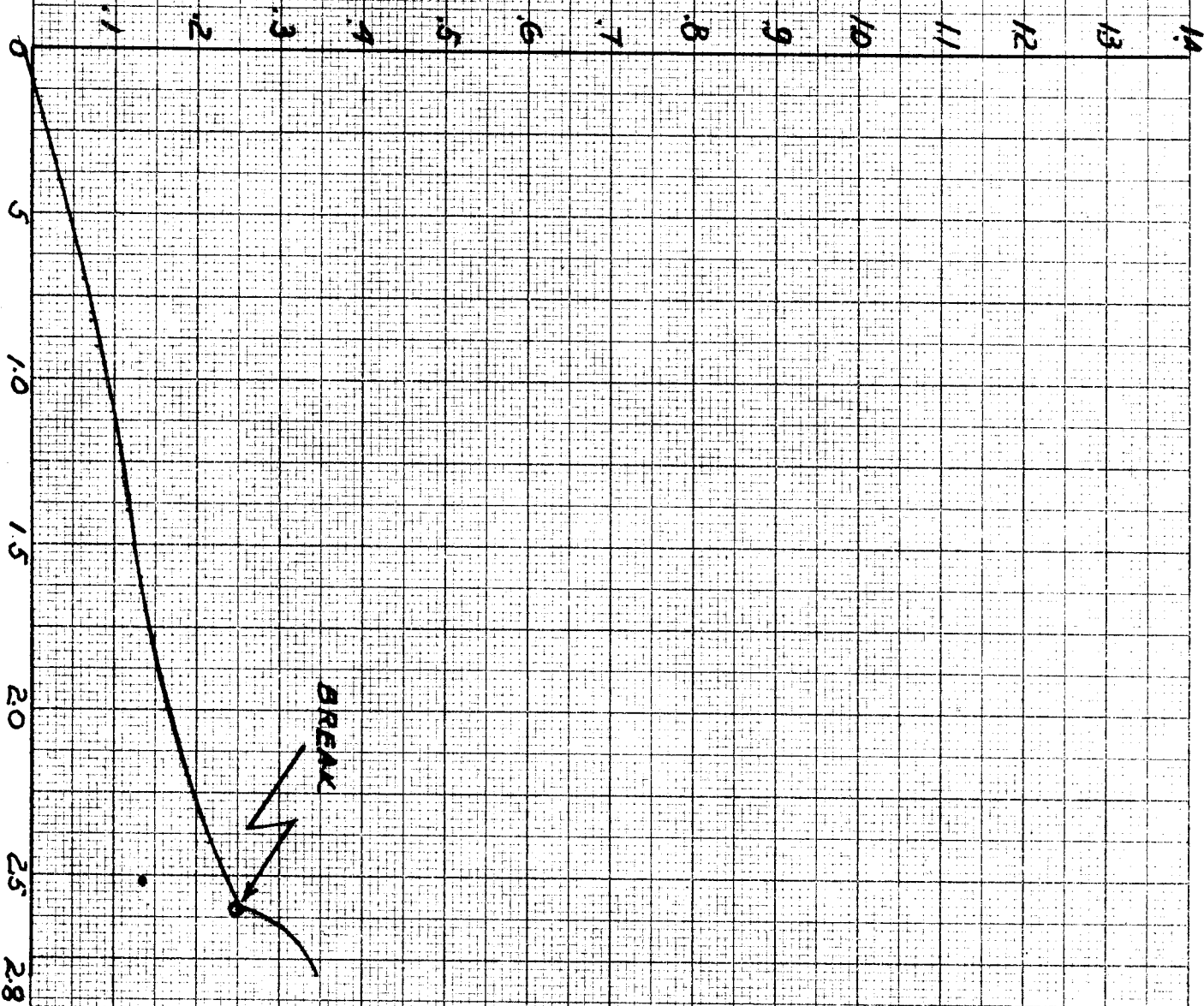


FIG. 28-b

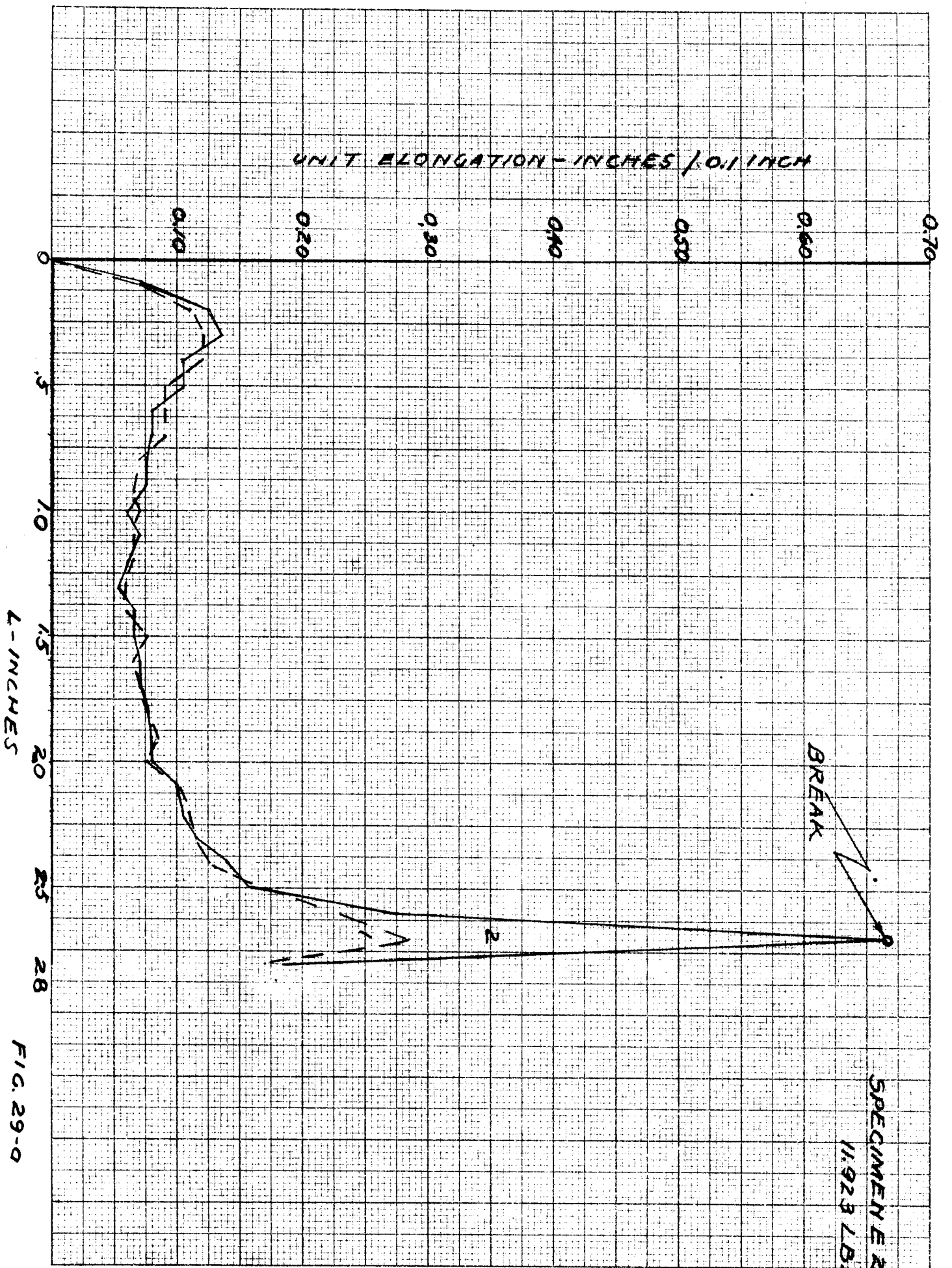
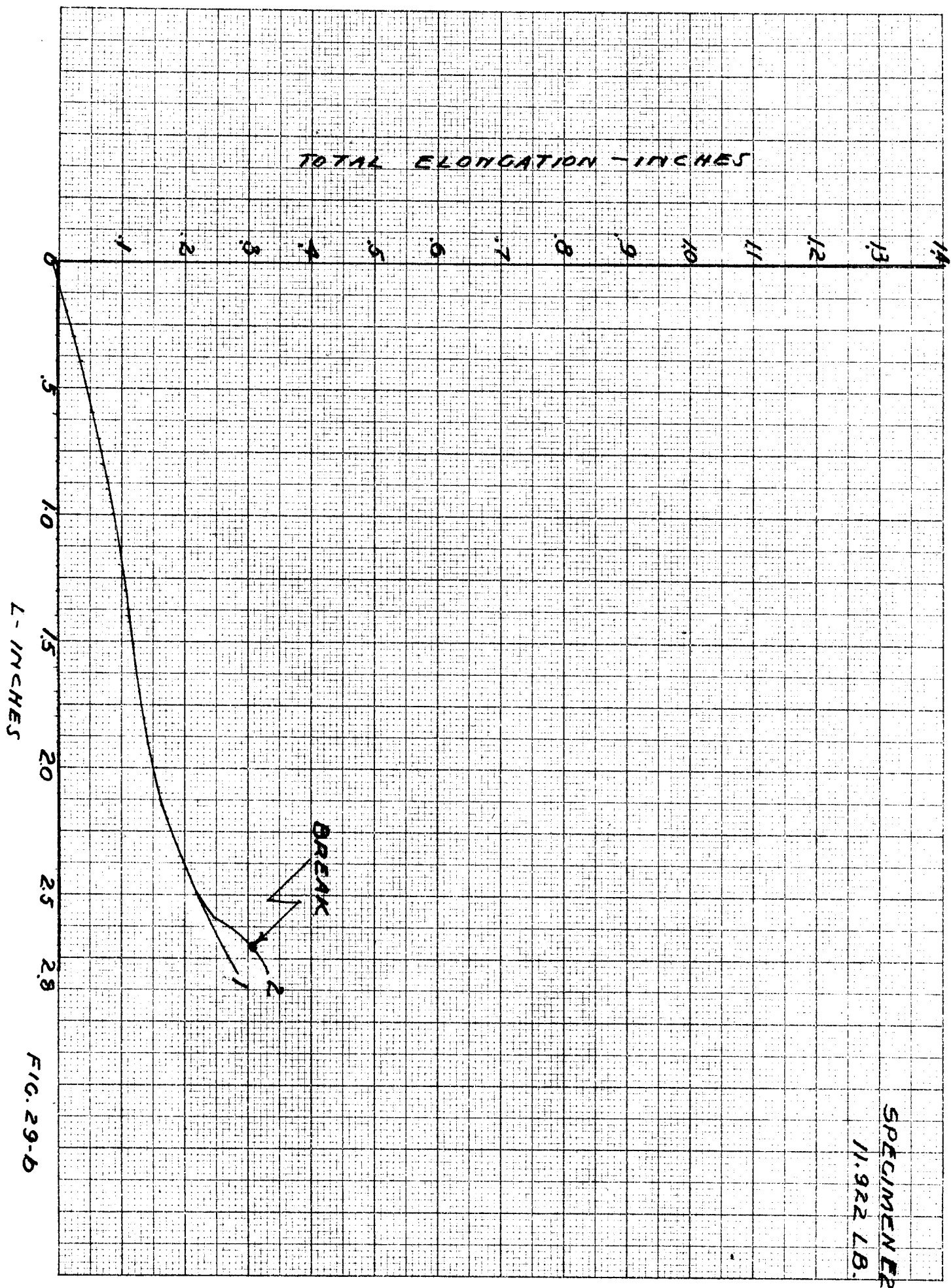


FIG. 29-0



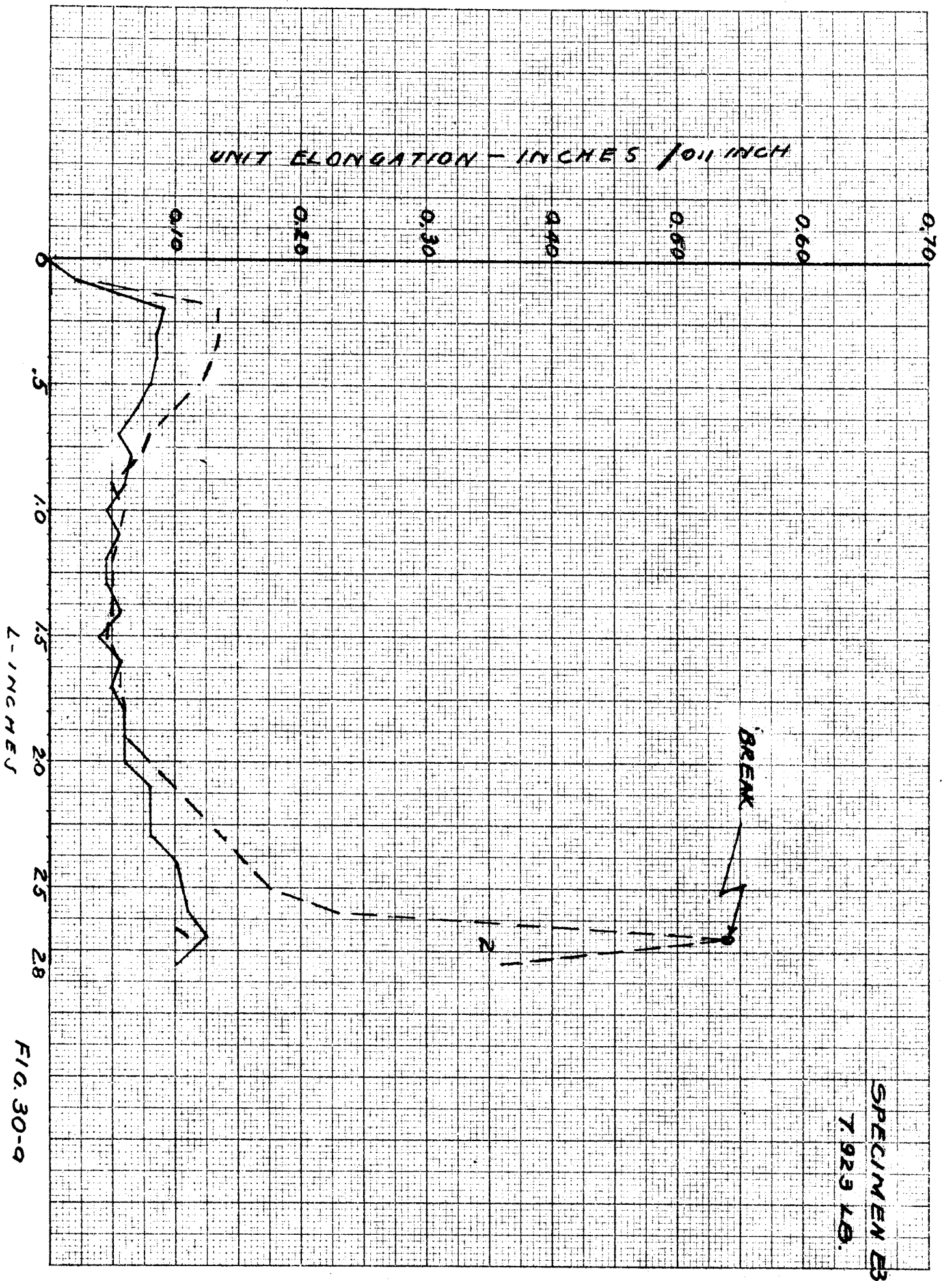
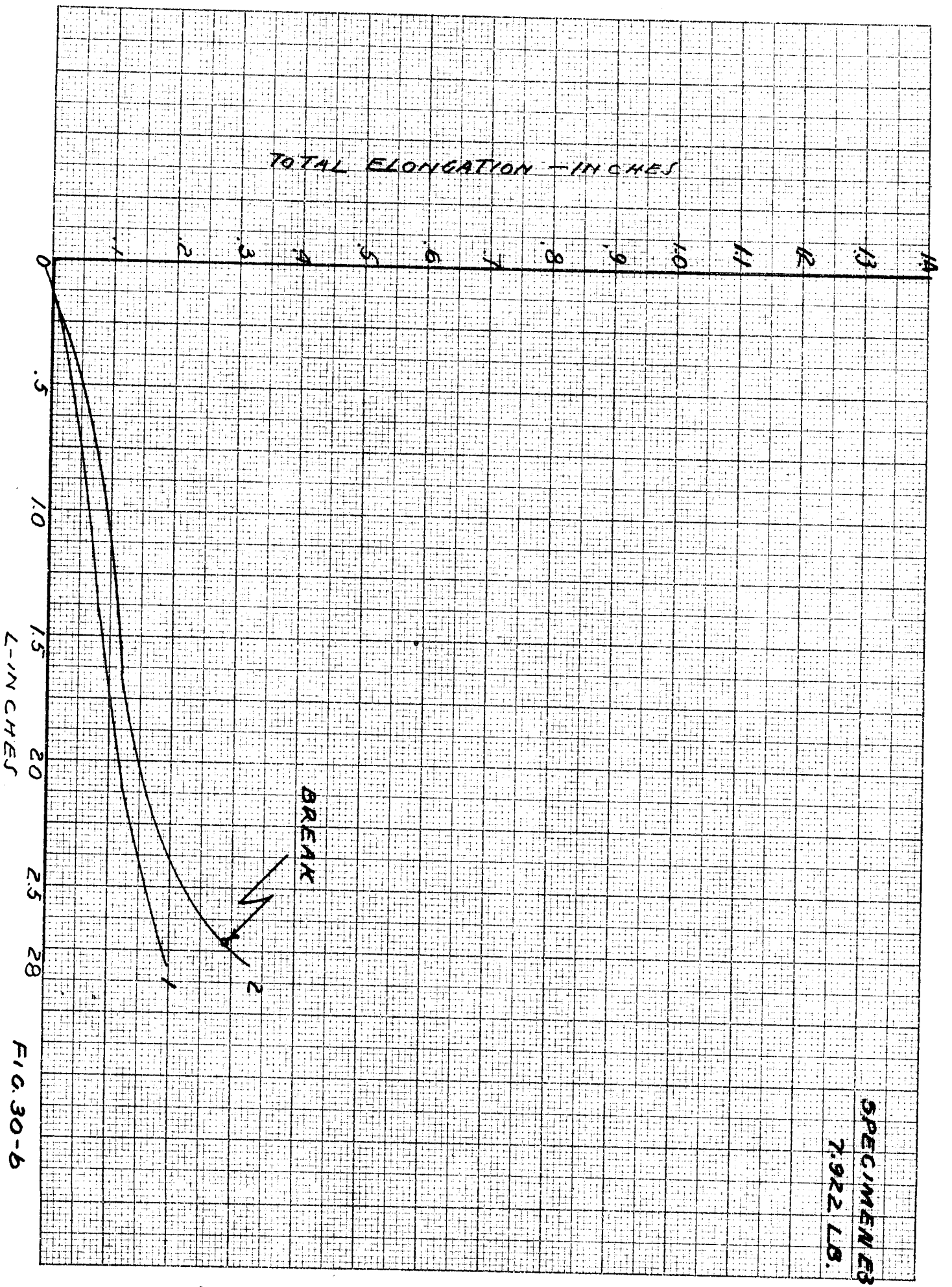


FIG. 30-9



SPECIMEN E8
7.922 LB.

FIG. 30-6

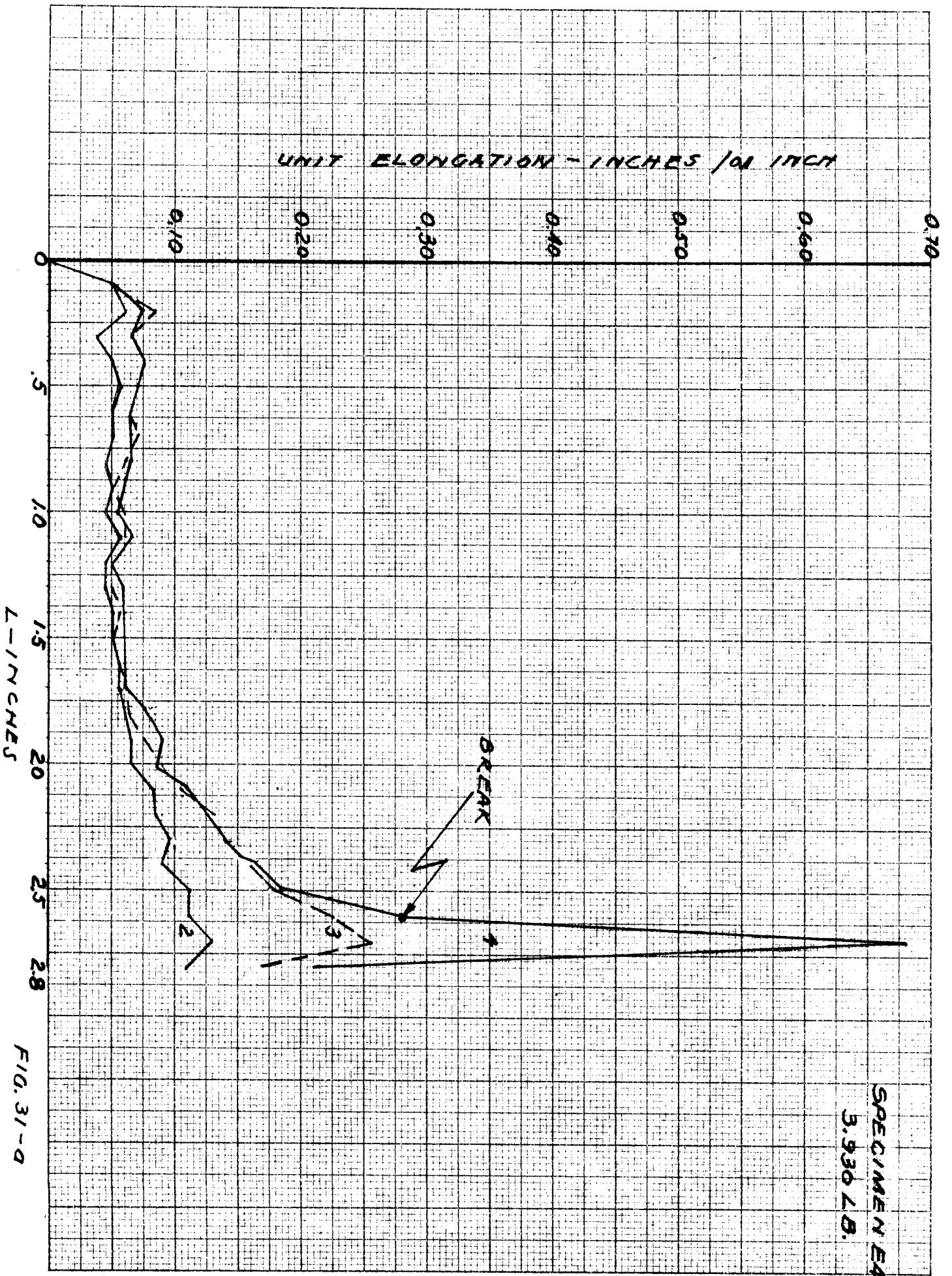
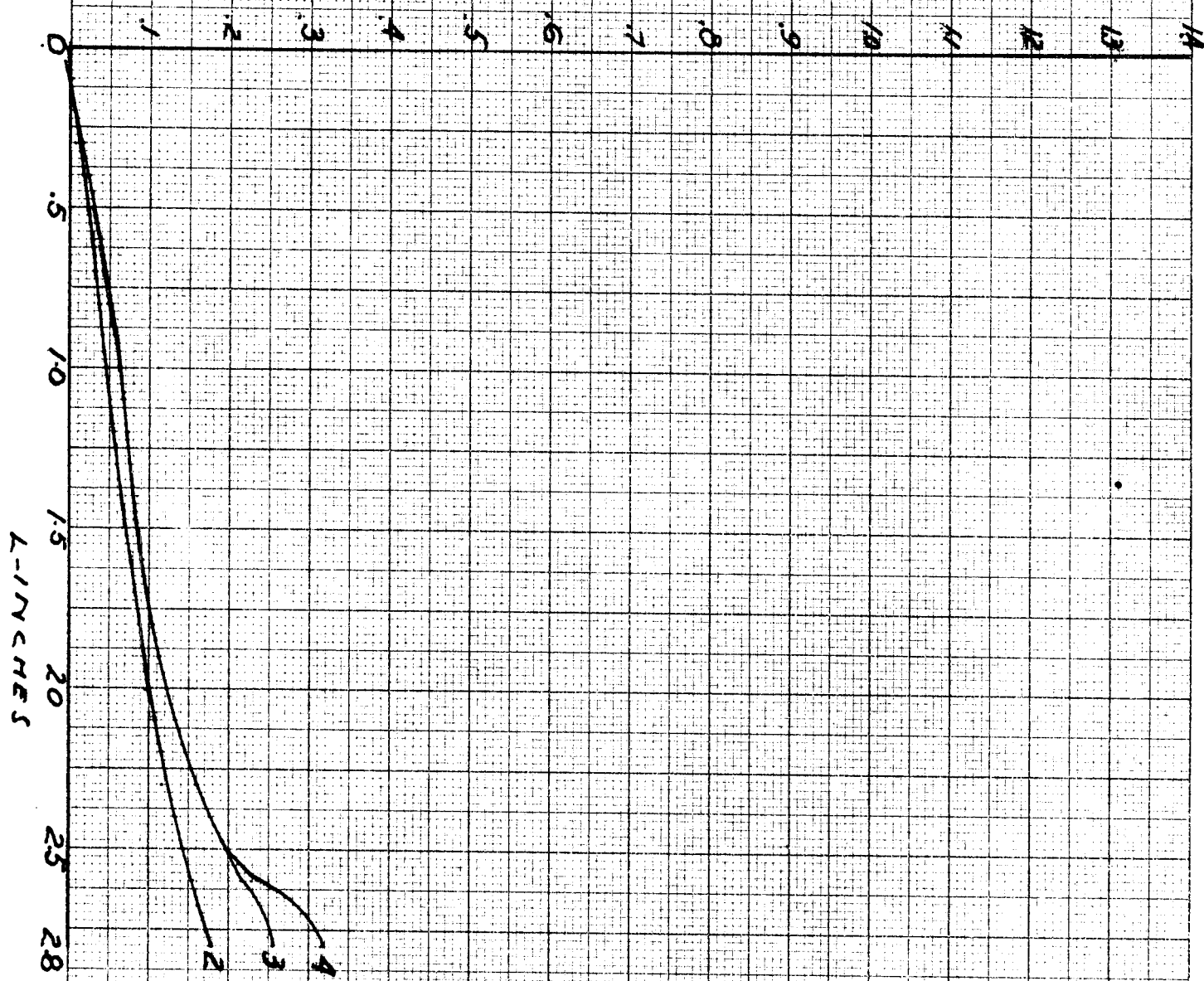


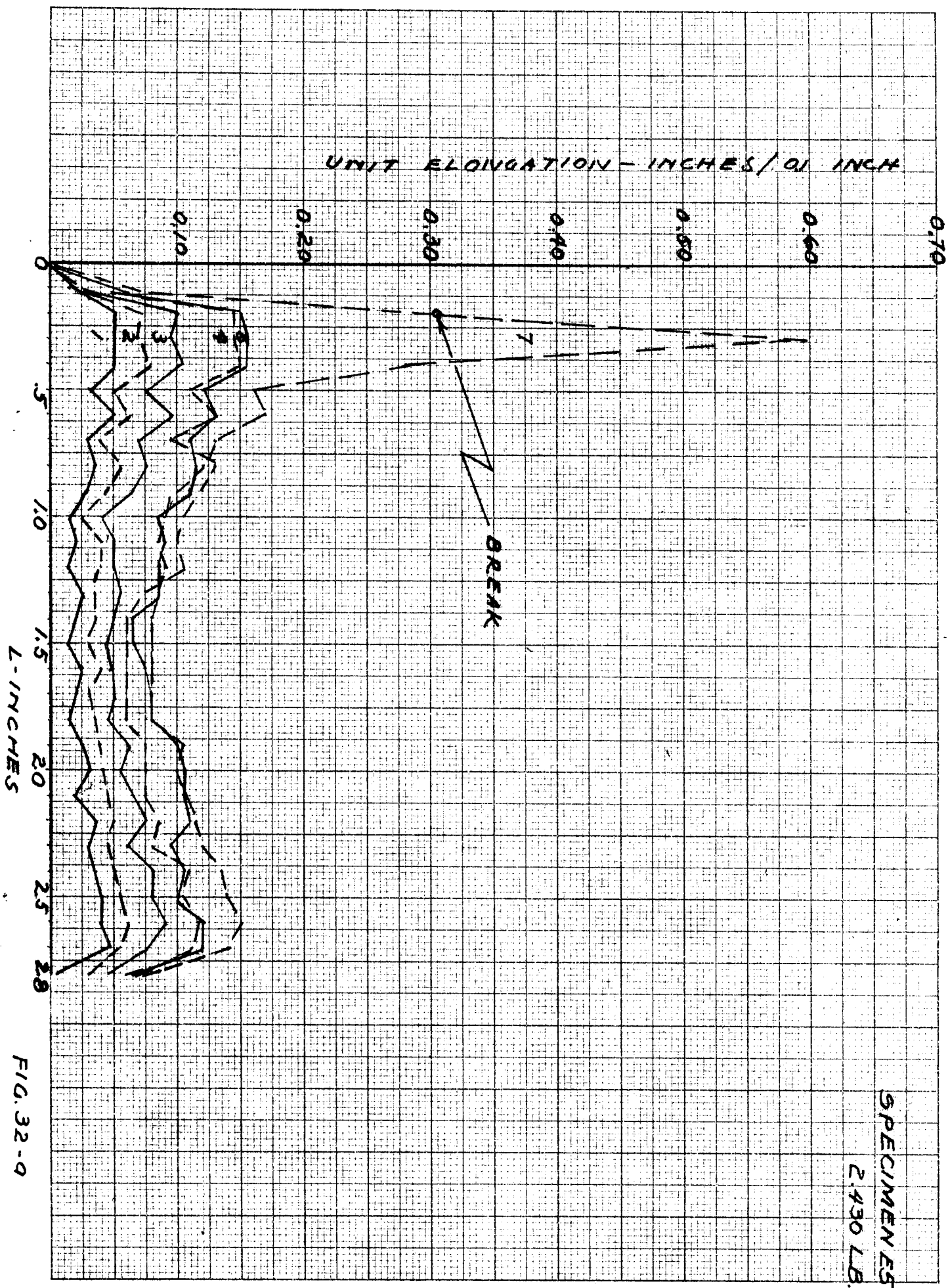
FIG. 31-a

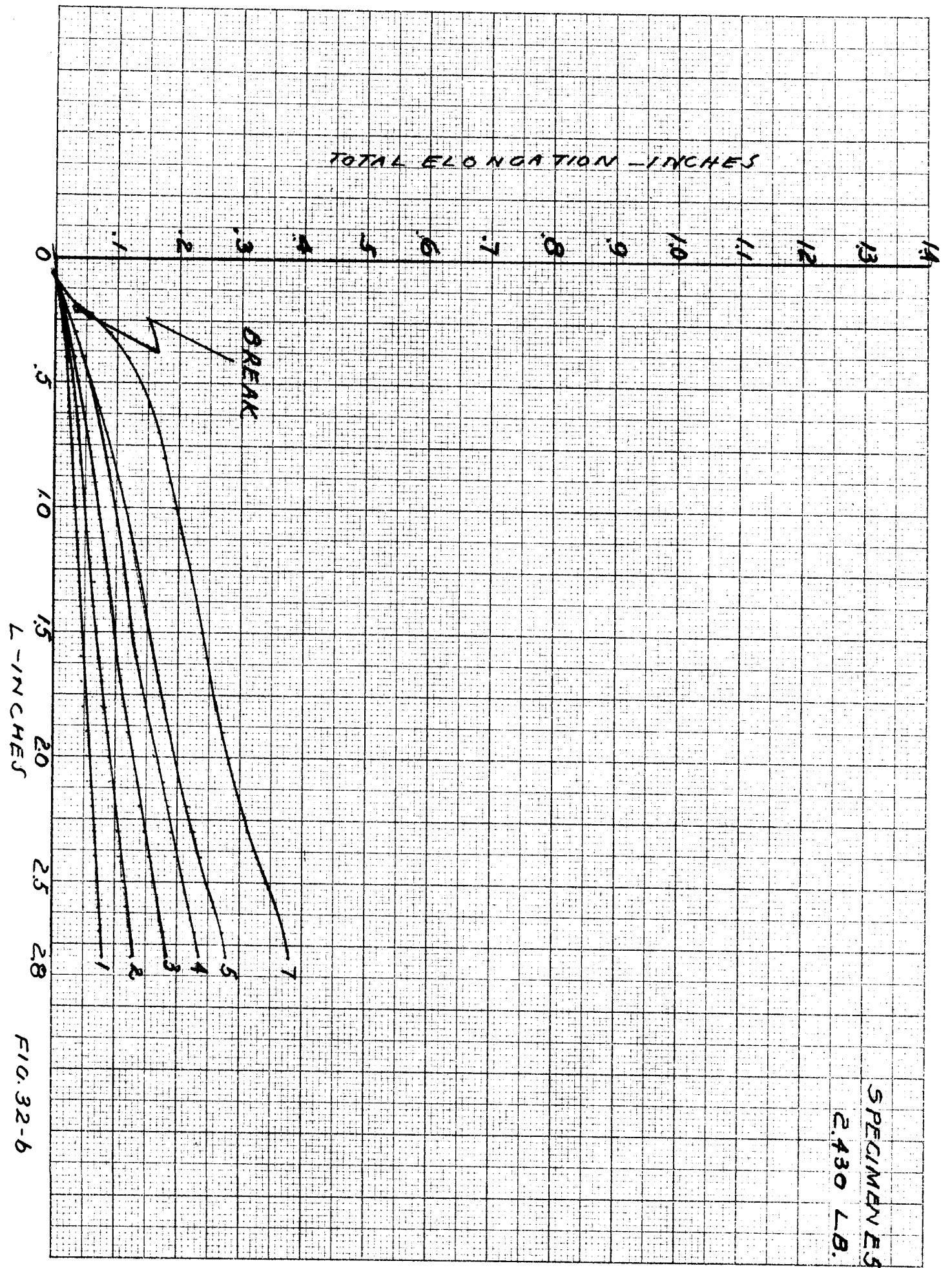
TOTAL ELONGATION - INCHES



SPECIMEN E4
3930 LB.

FIG. 31-b





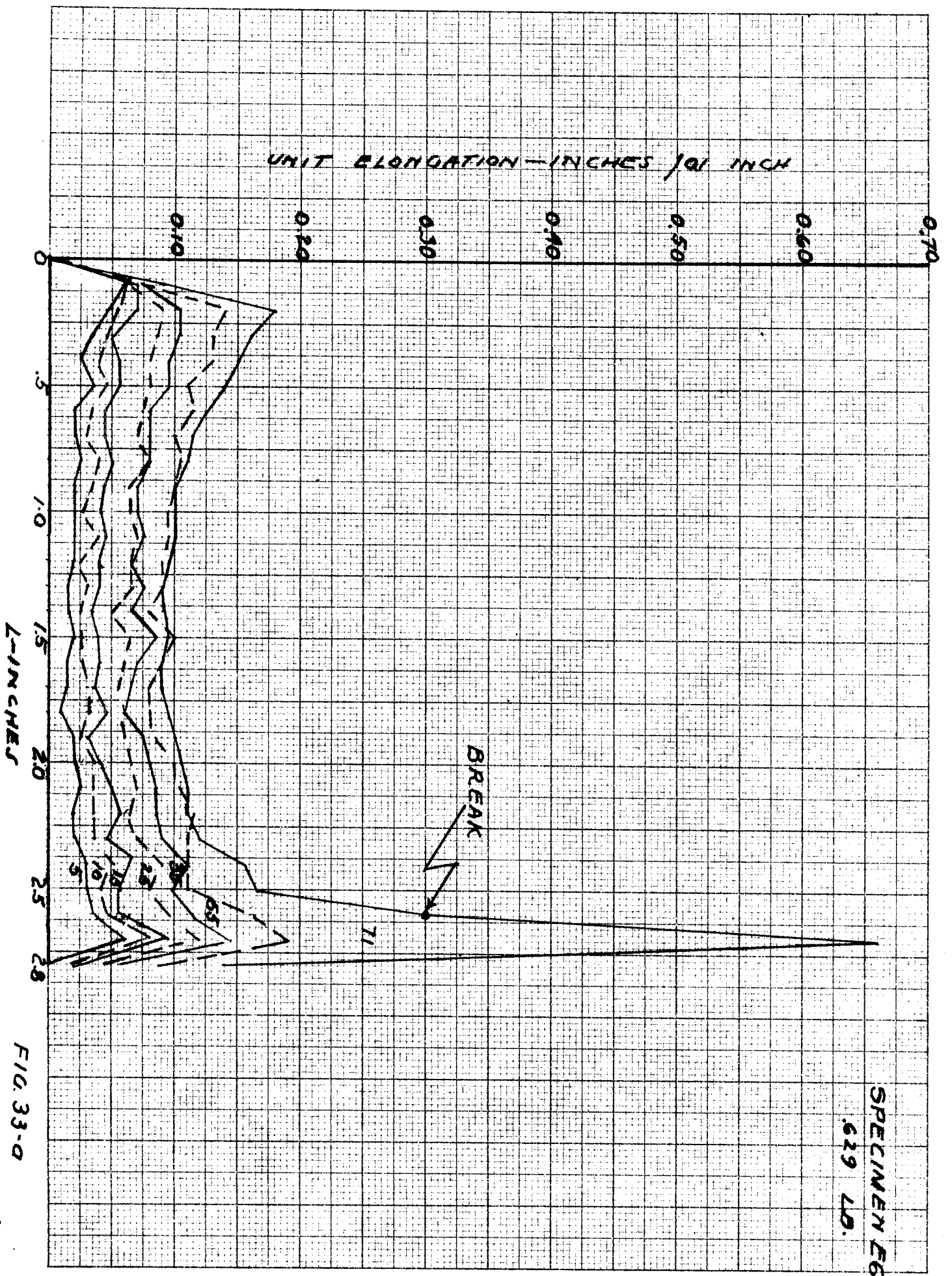
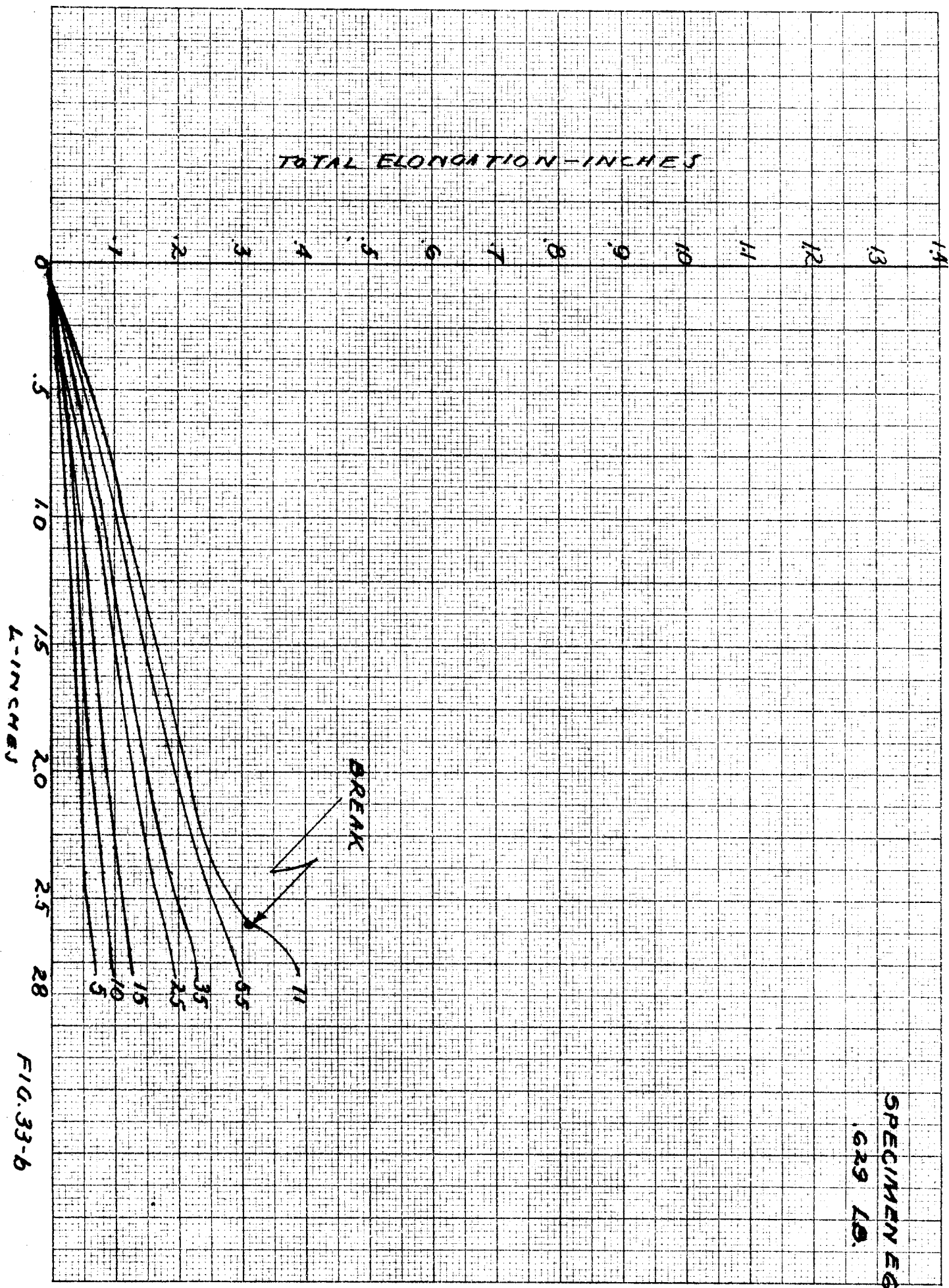
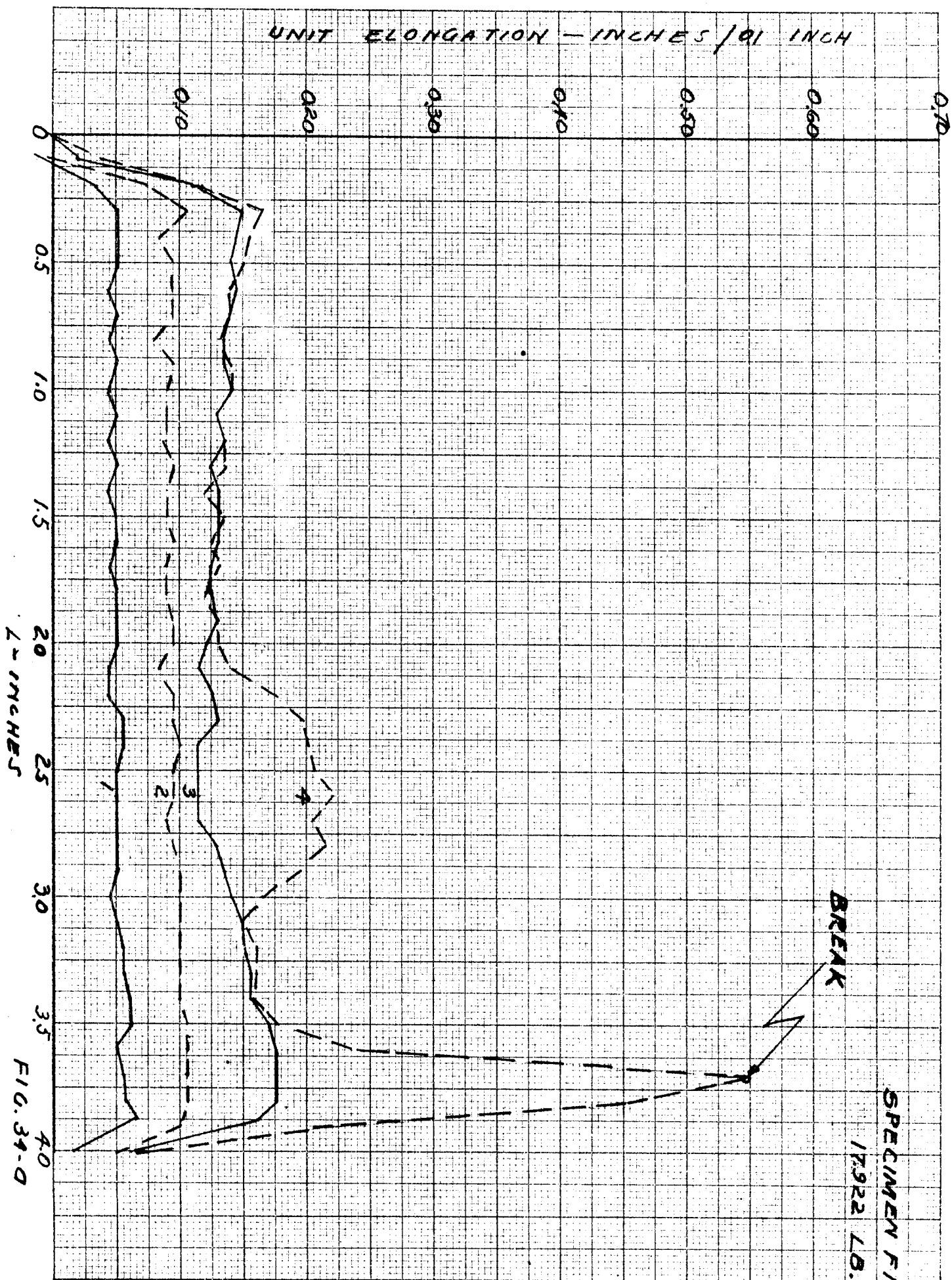
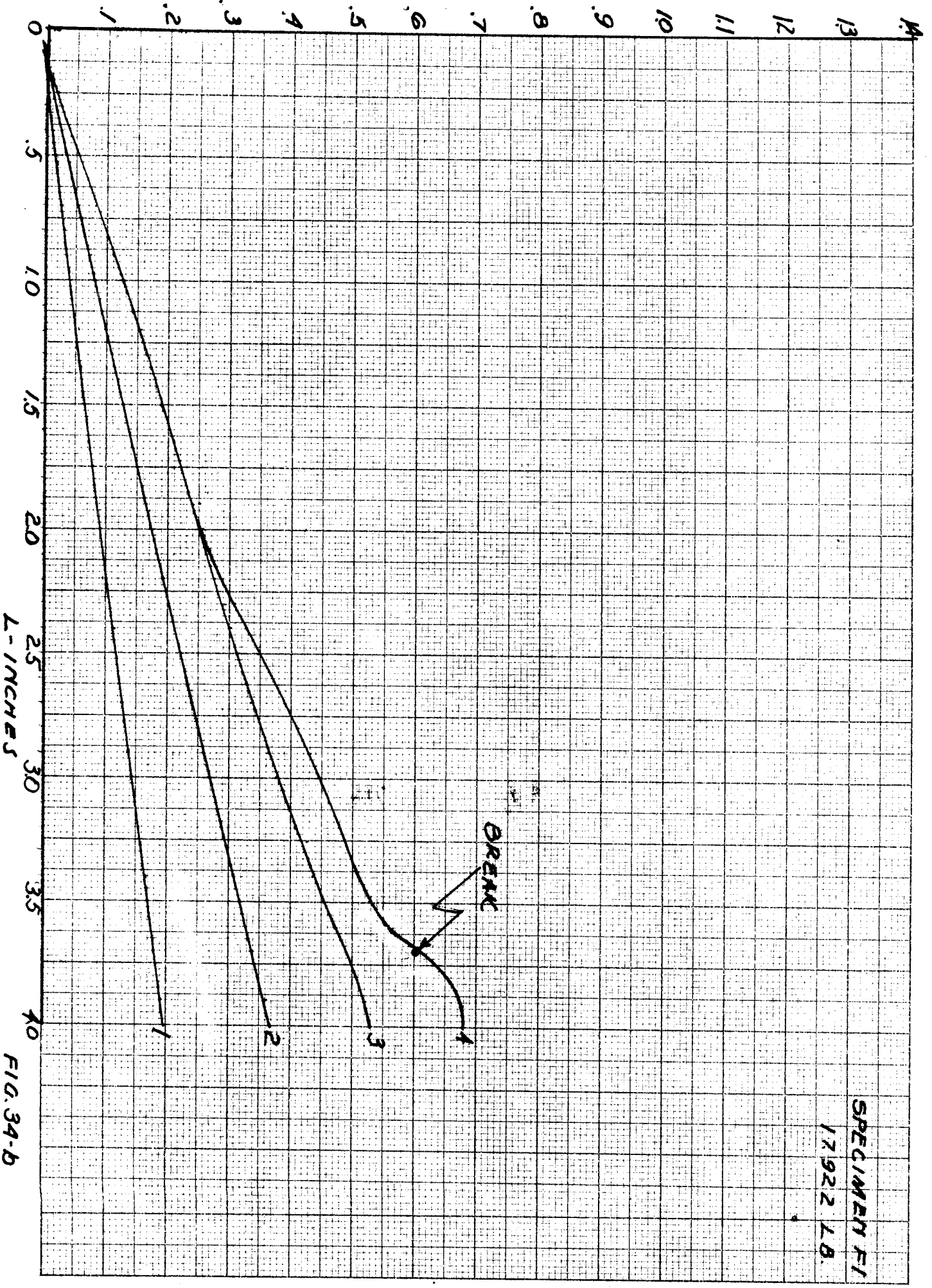


FIG. 33-0

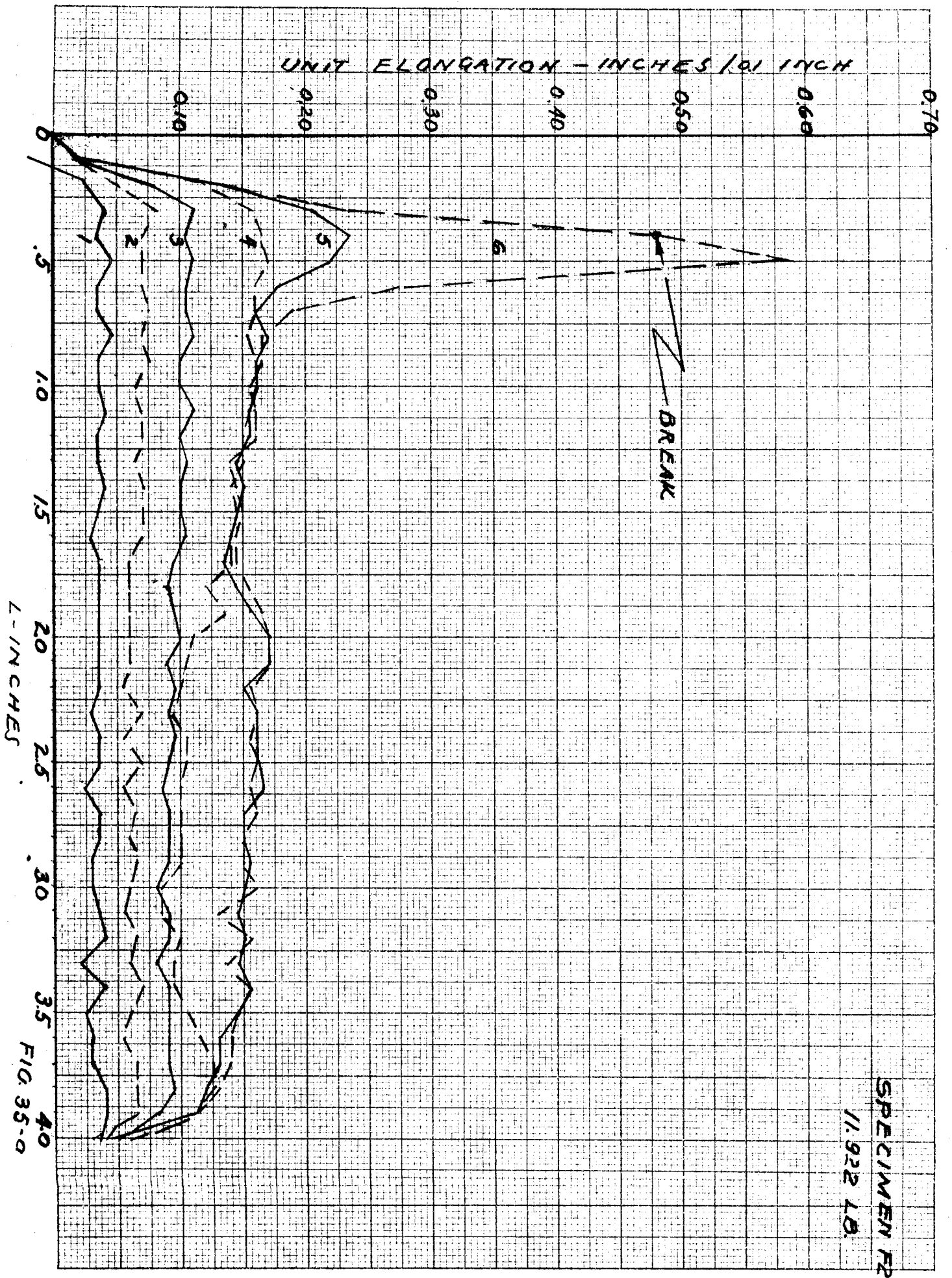






SPECIMEN F1
17922 LB.

FIG. 34-B



SPECIMEN F2
17922 LB.

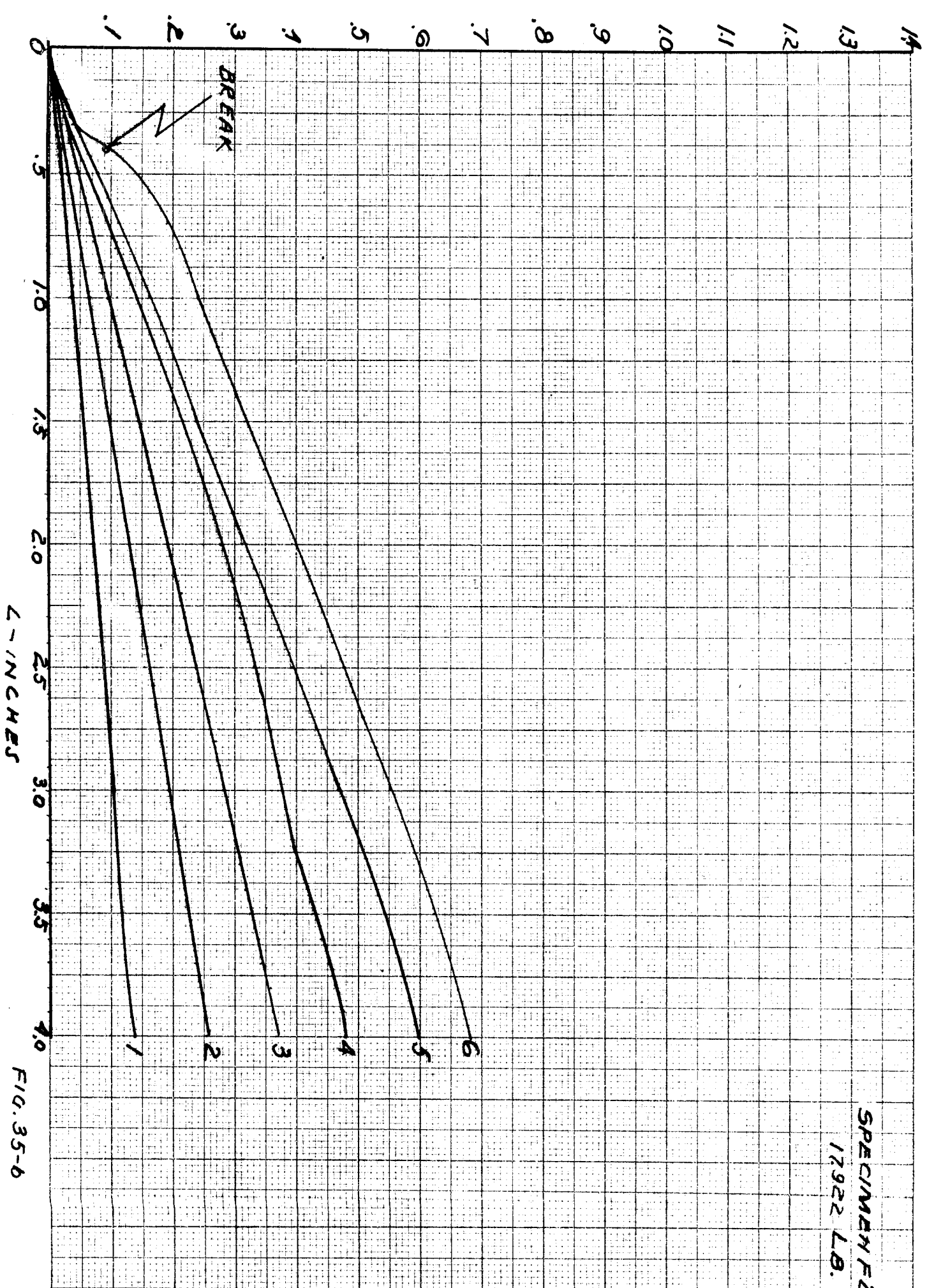
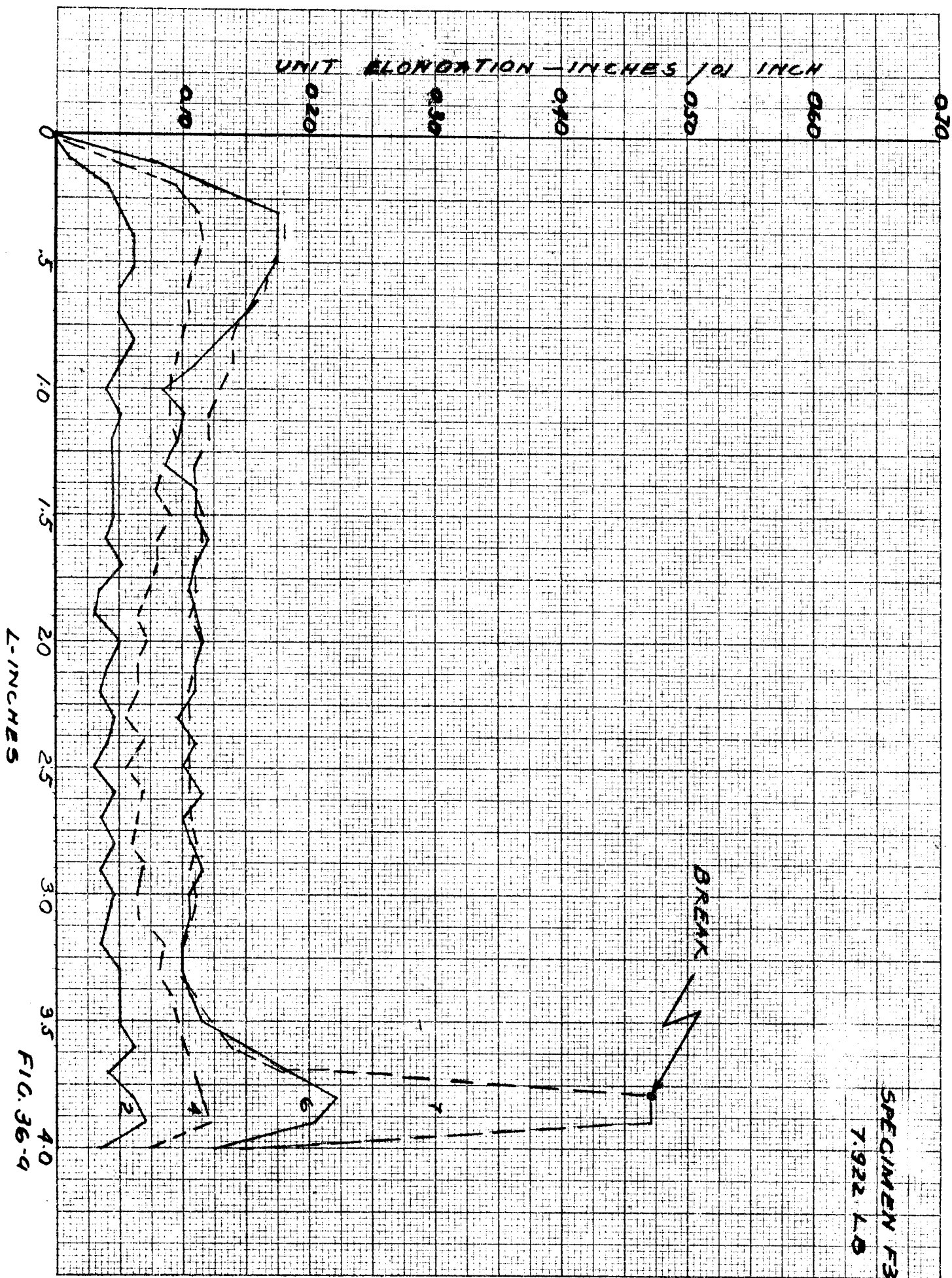
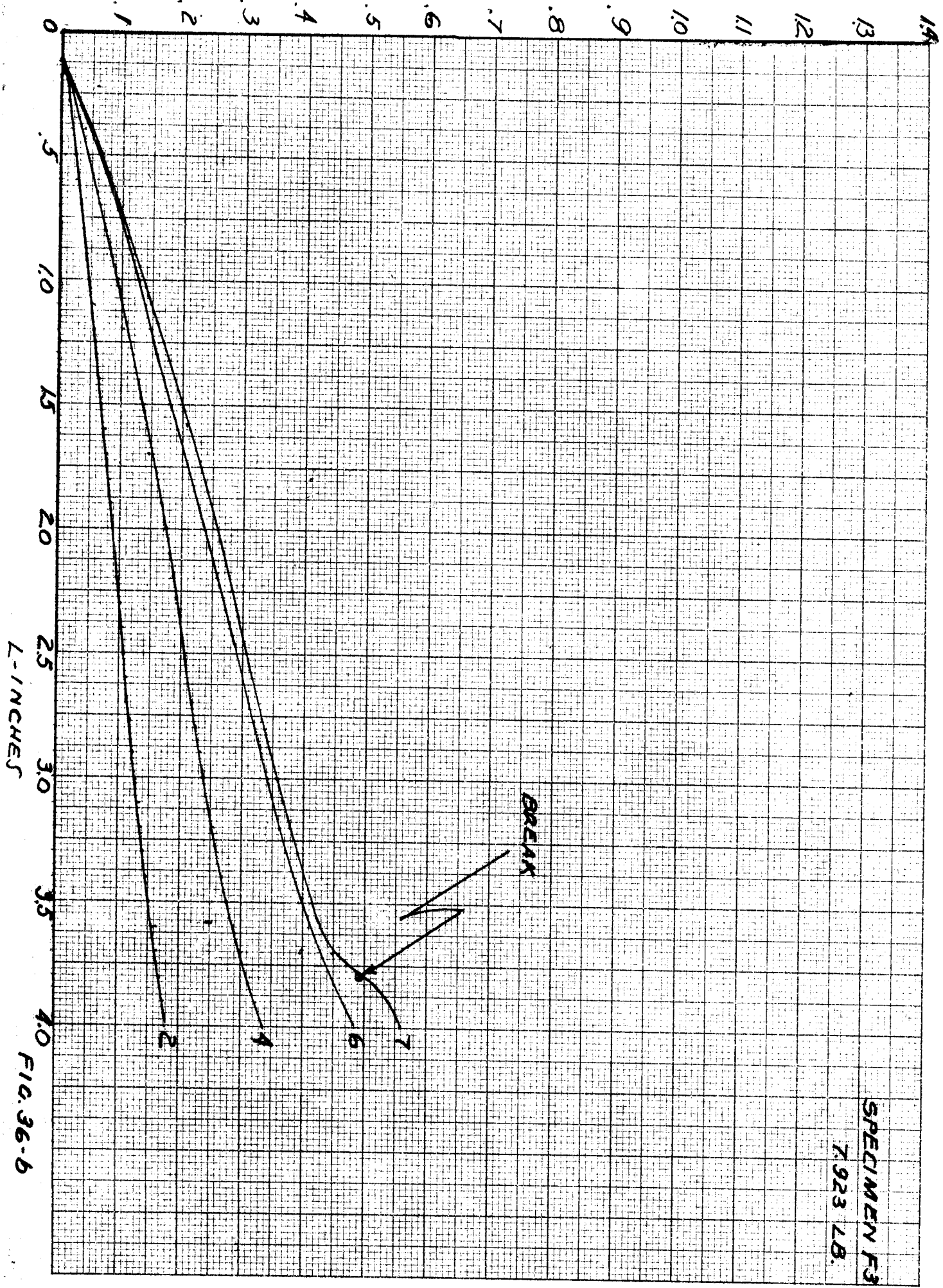


FIG. 35-6



SPECIMEN F3
7.923 LB.



L-INCHES

FIG. 36-6

UNIT ELONGATION - INCHES / INCH

0.70
0.60
0.50
0.40
0.30
0.20
0.10
0

0
.5
1.0
1.5
2.0
2.5
3.0
3.5
4.0

1-INCHES

FIG. 37-D

SPECIMEN F4
3.930 LB.

BREAK

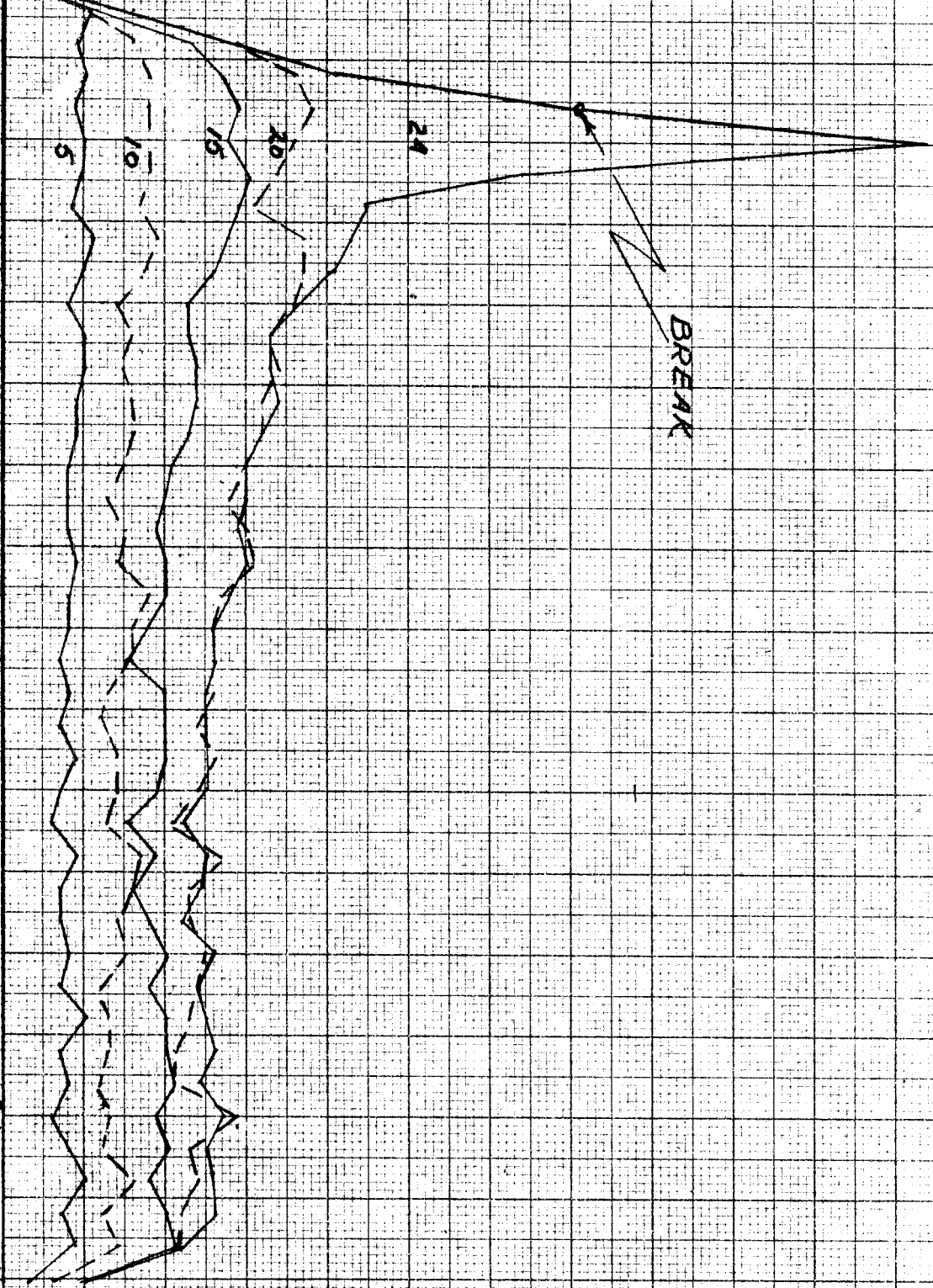
24

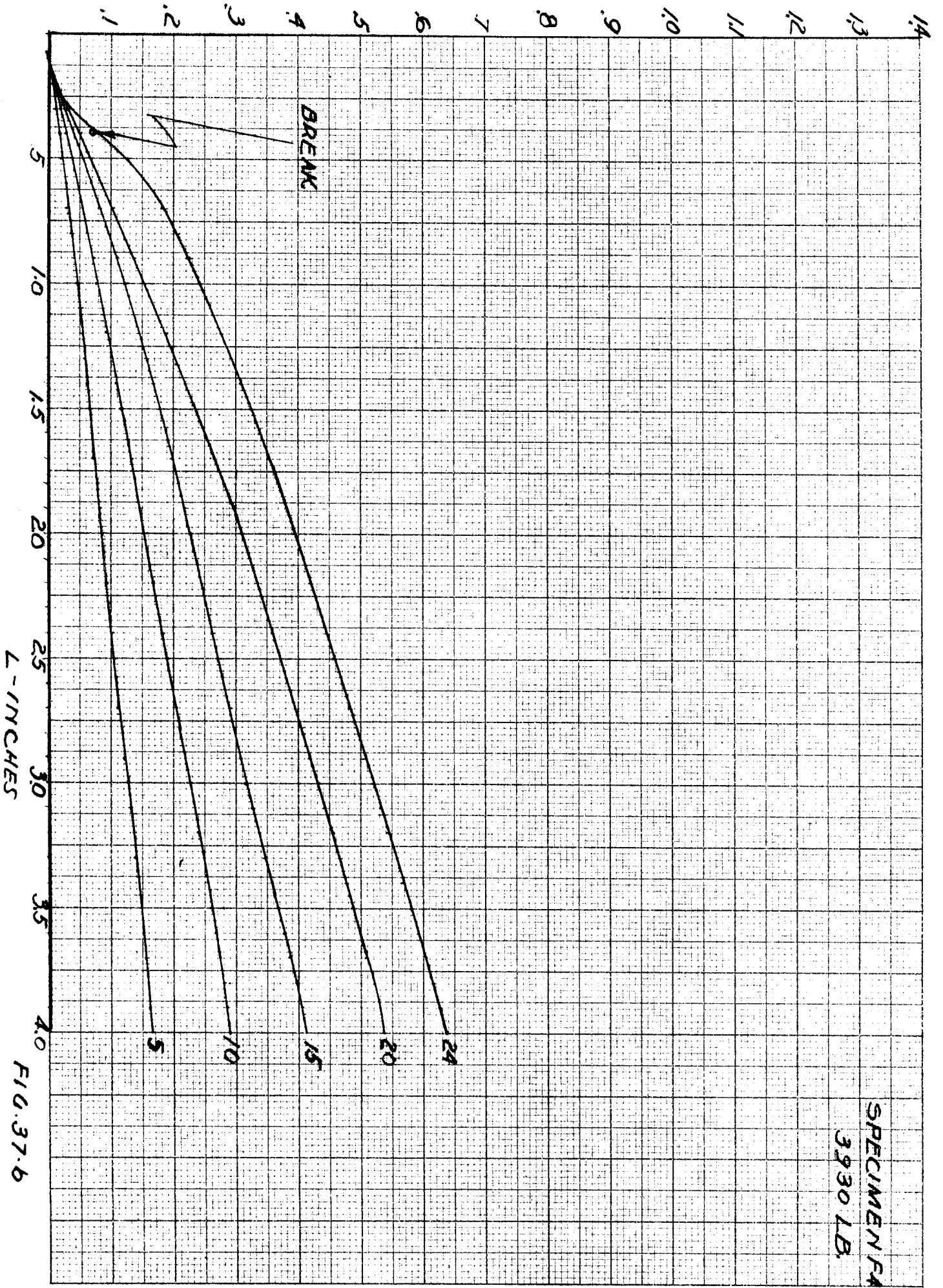
40

15

10

5





SPECIMEN FA
3930 LB.

FIG. 37.6

UNIT ELONGATION - INCHES / 0.1 INCH

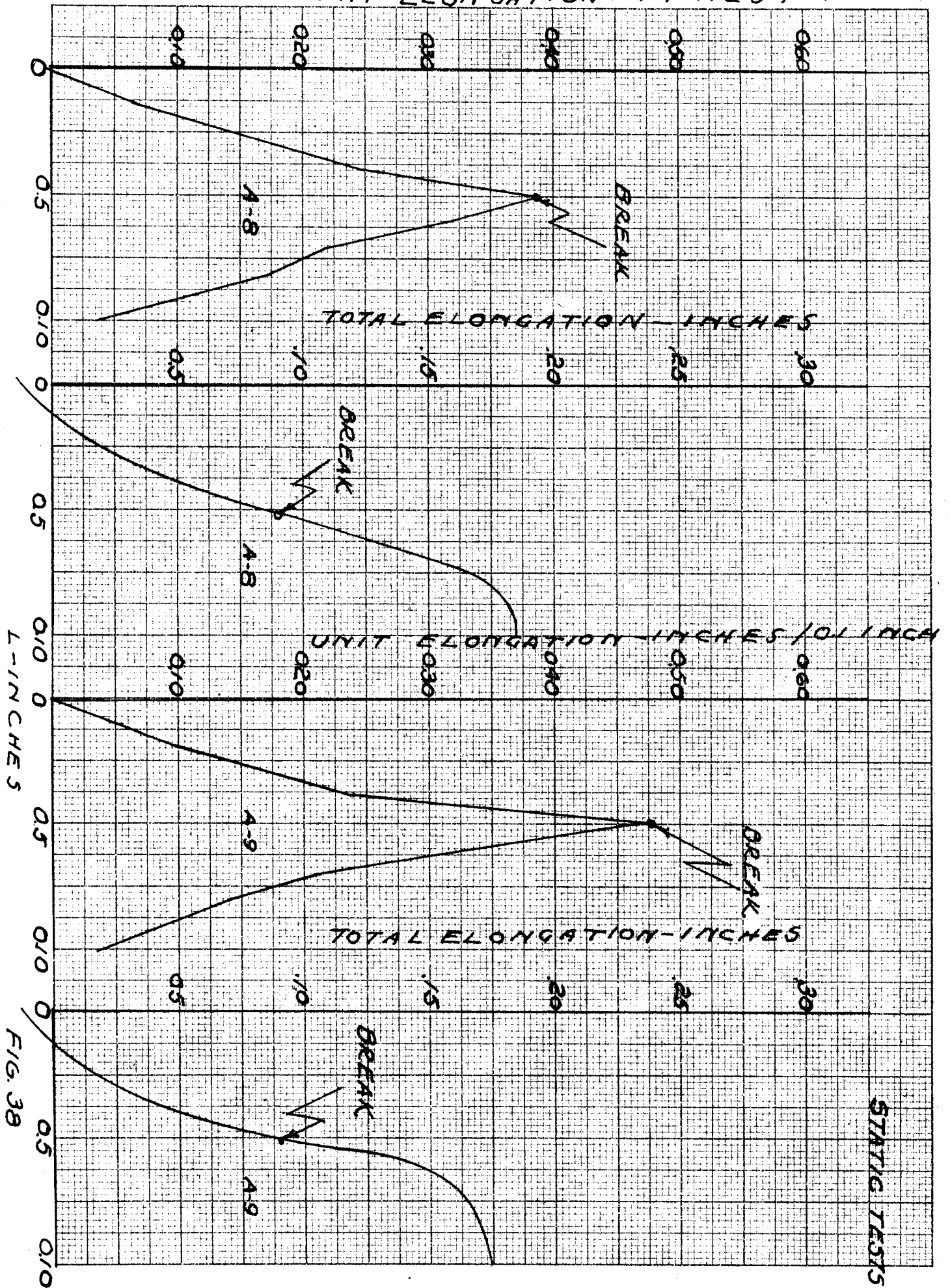


FIG. 38

UNIT ELONGATION - INCHES

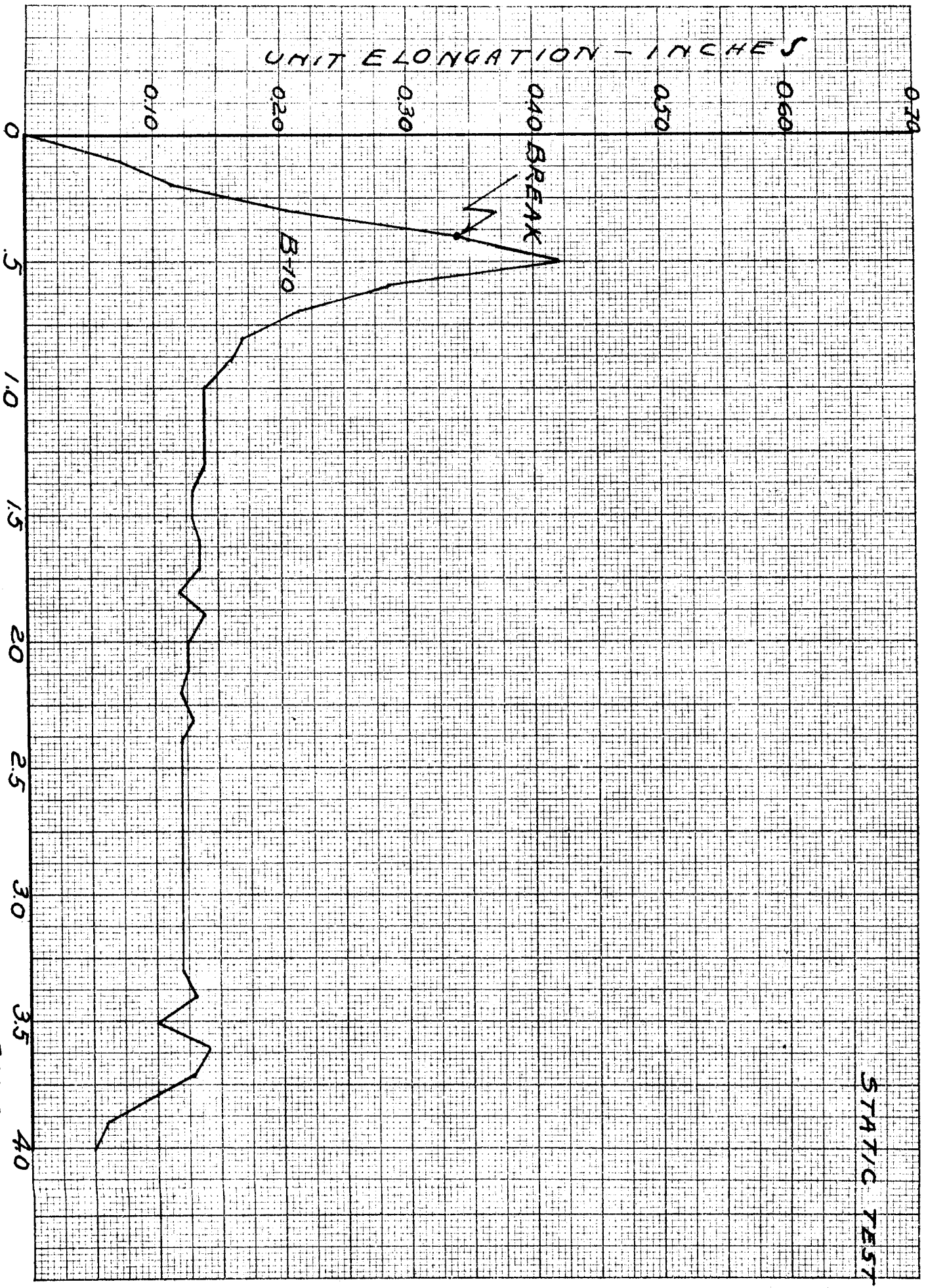
STATIC TEST

0.40 BREAK

B-10

1 - INCHES

FIG. 39-a



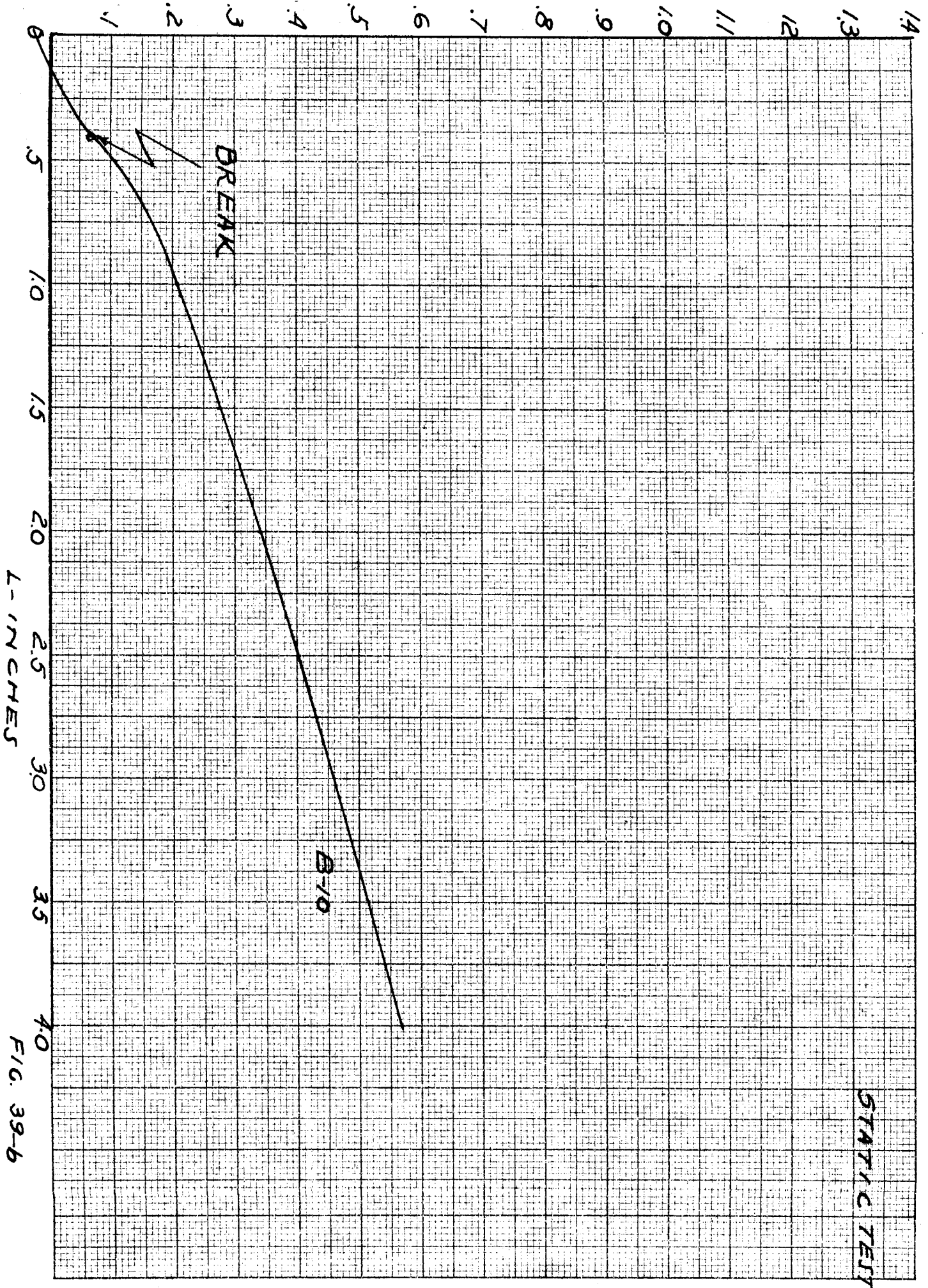
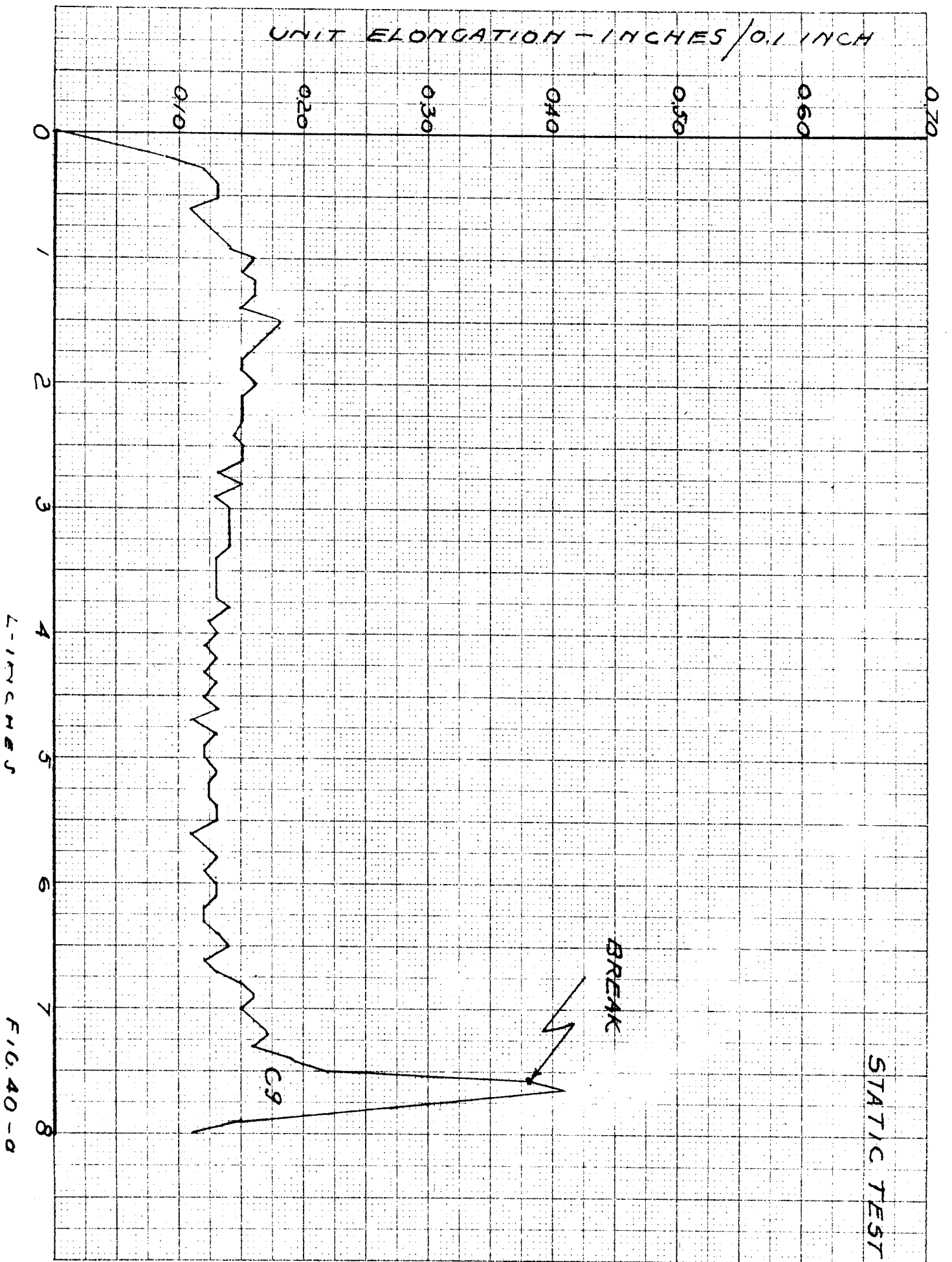


FIG. 39-6



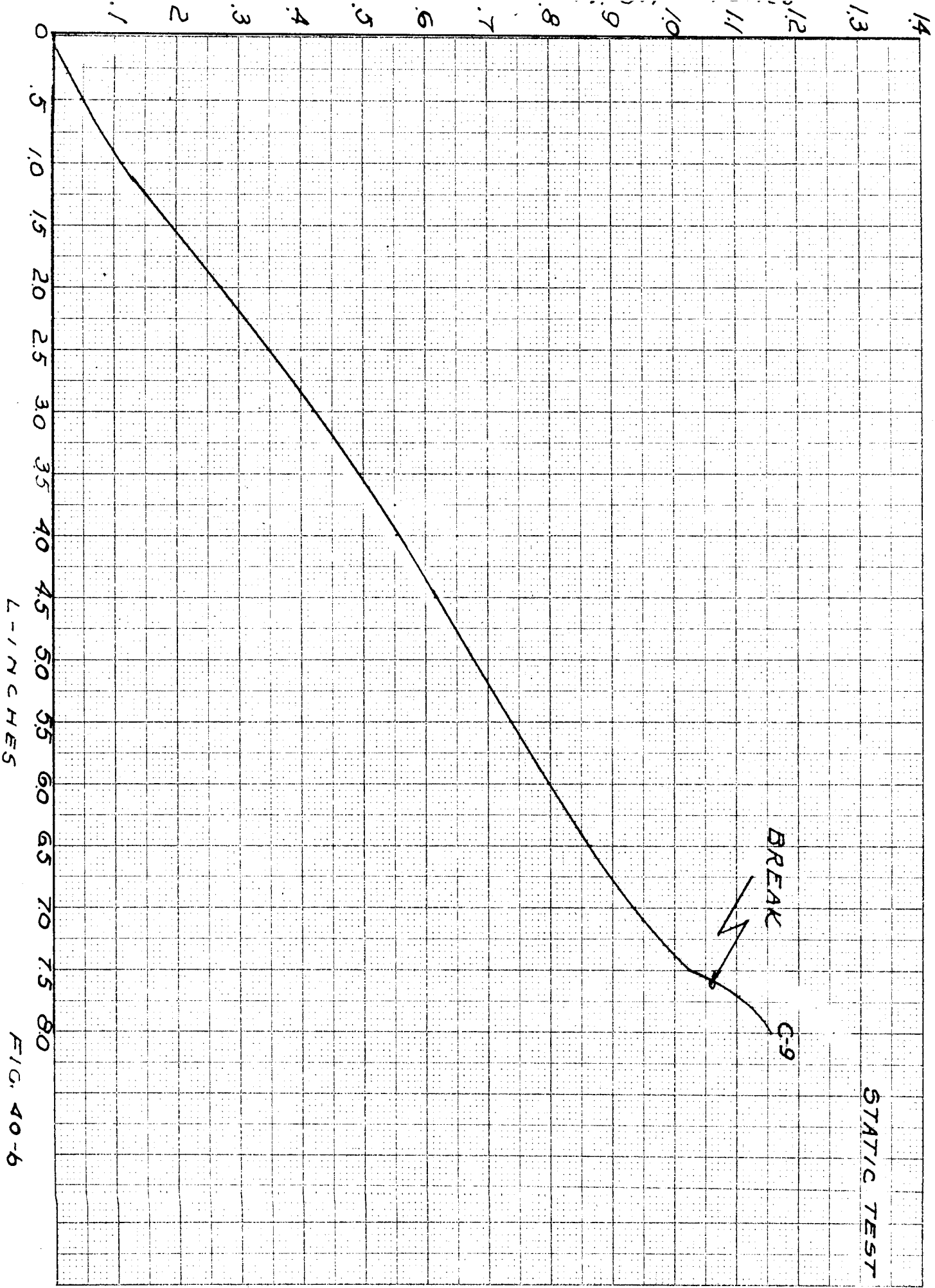


FIG. 40-6

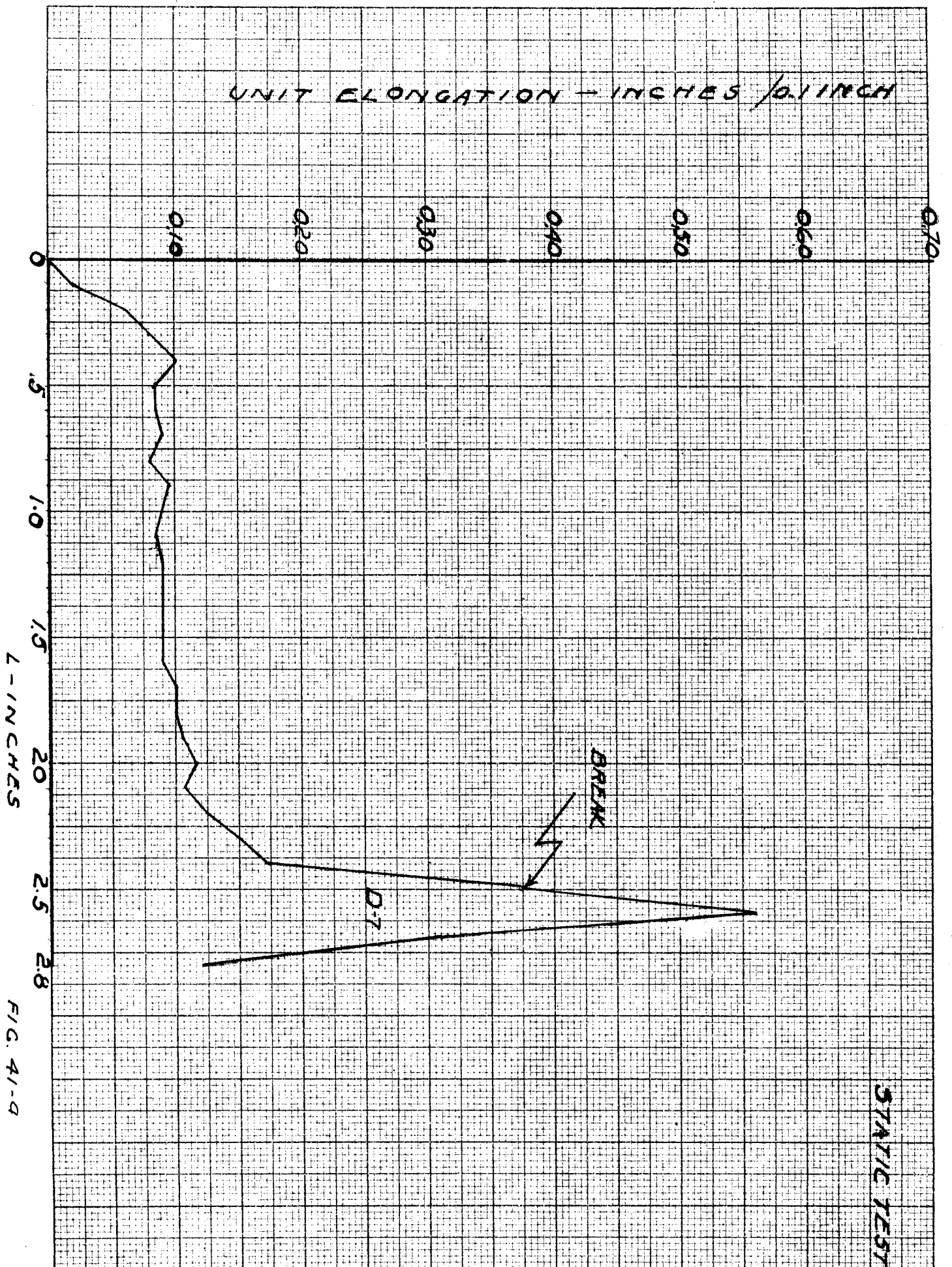
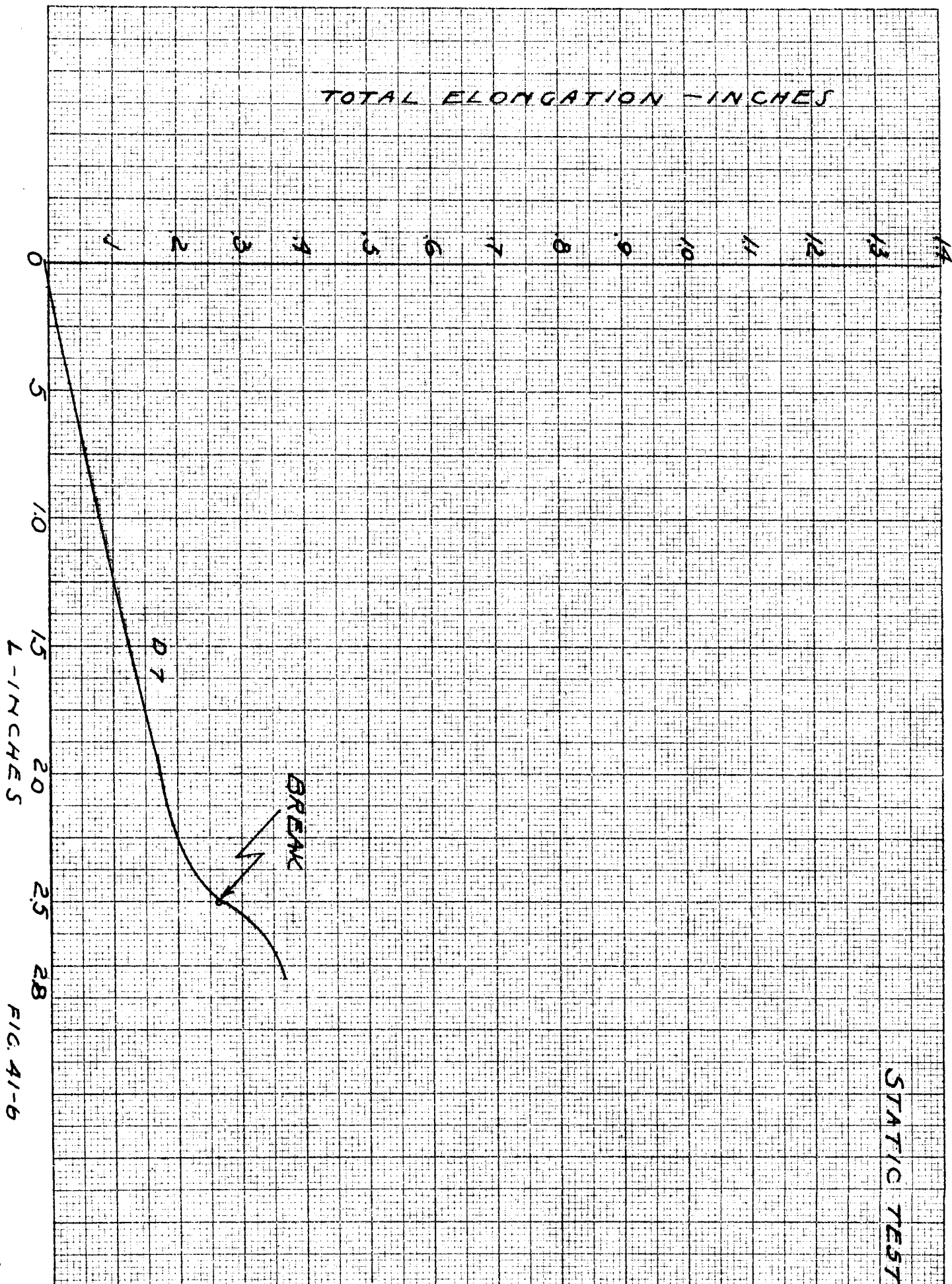


FIG. 41-9

TOTAL ELONGATION - INCHES



STATIC TEST

L - INCHES

FIG. 41-6

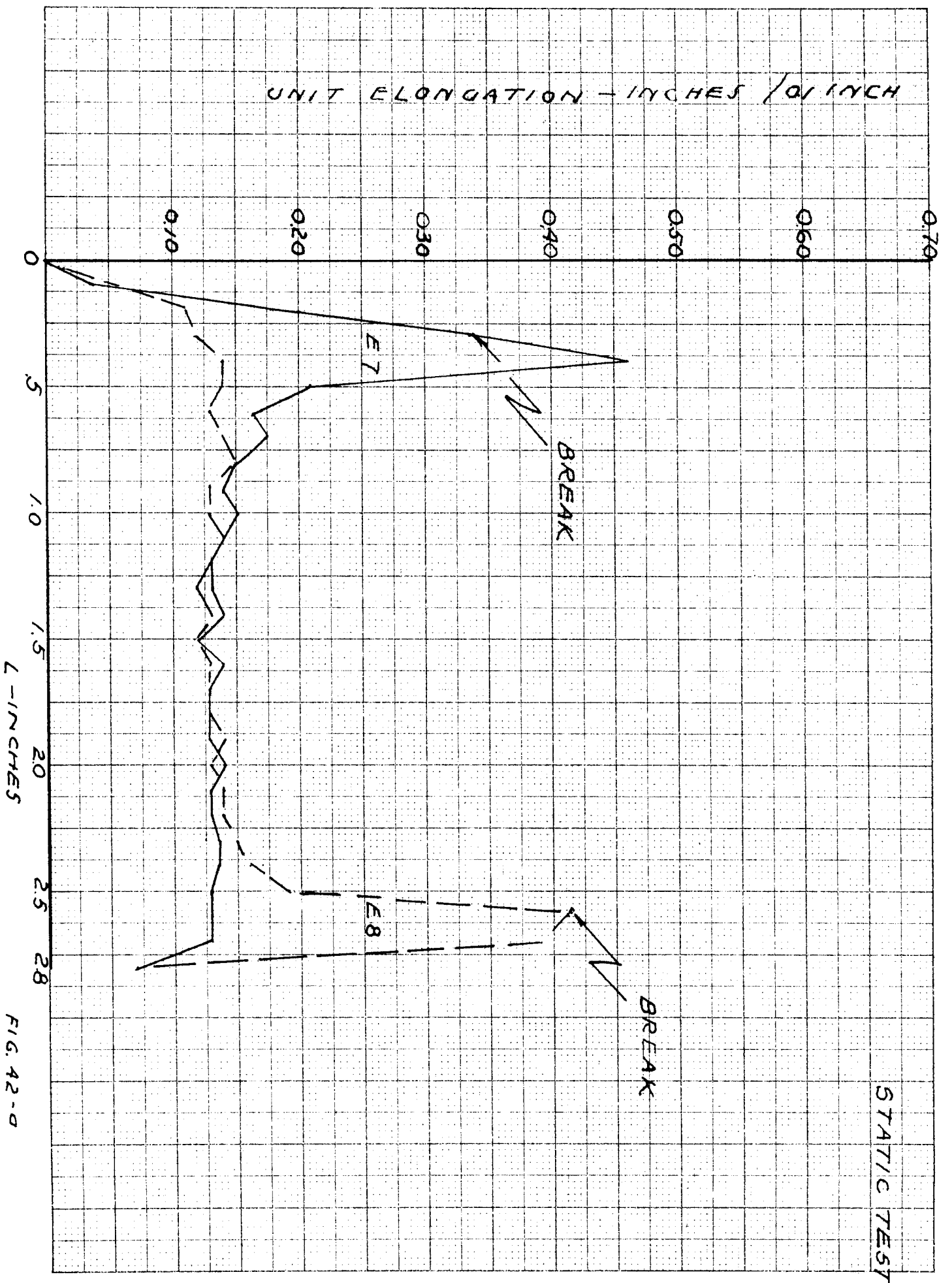


FIG. 42-0

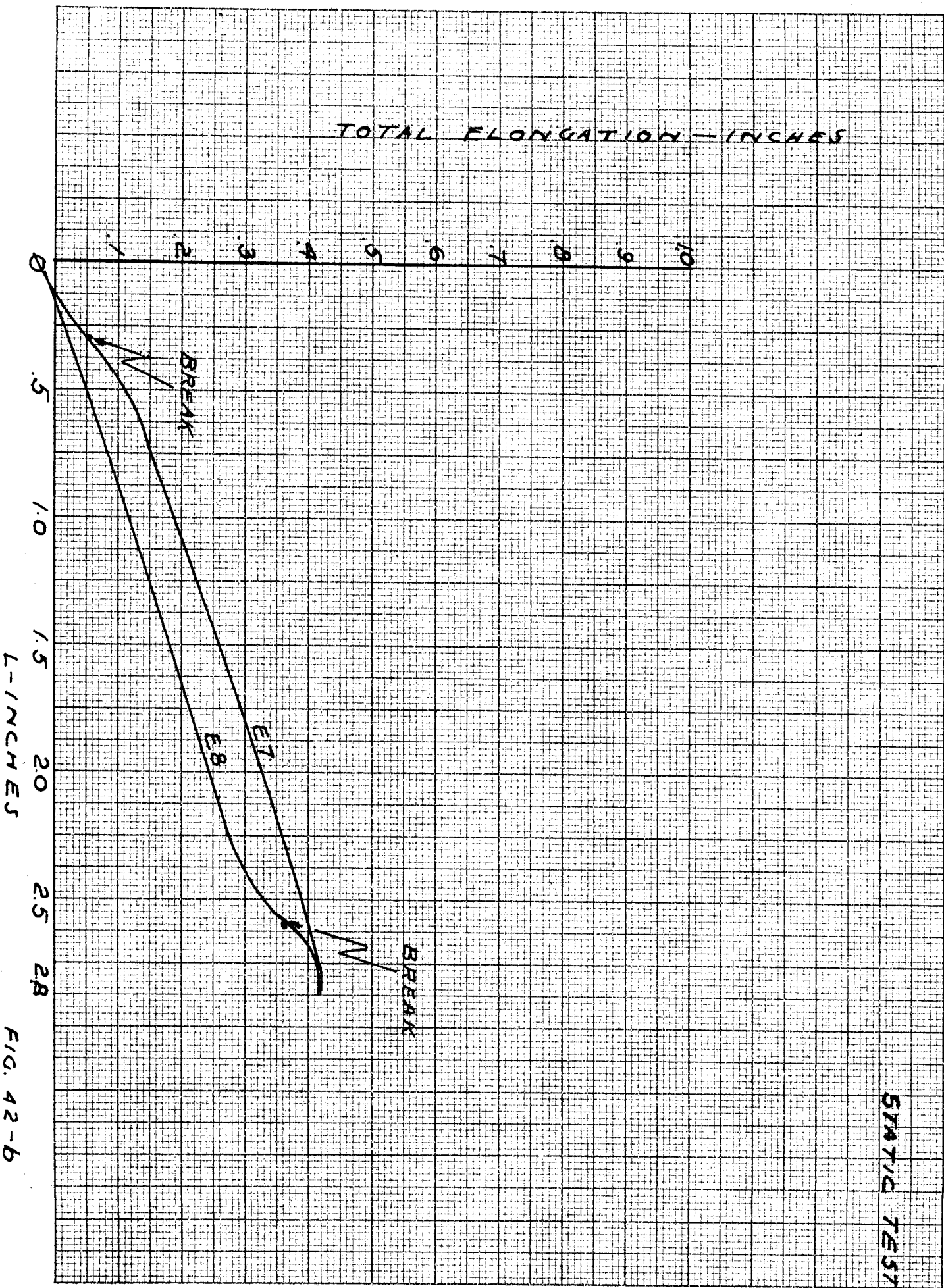
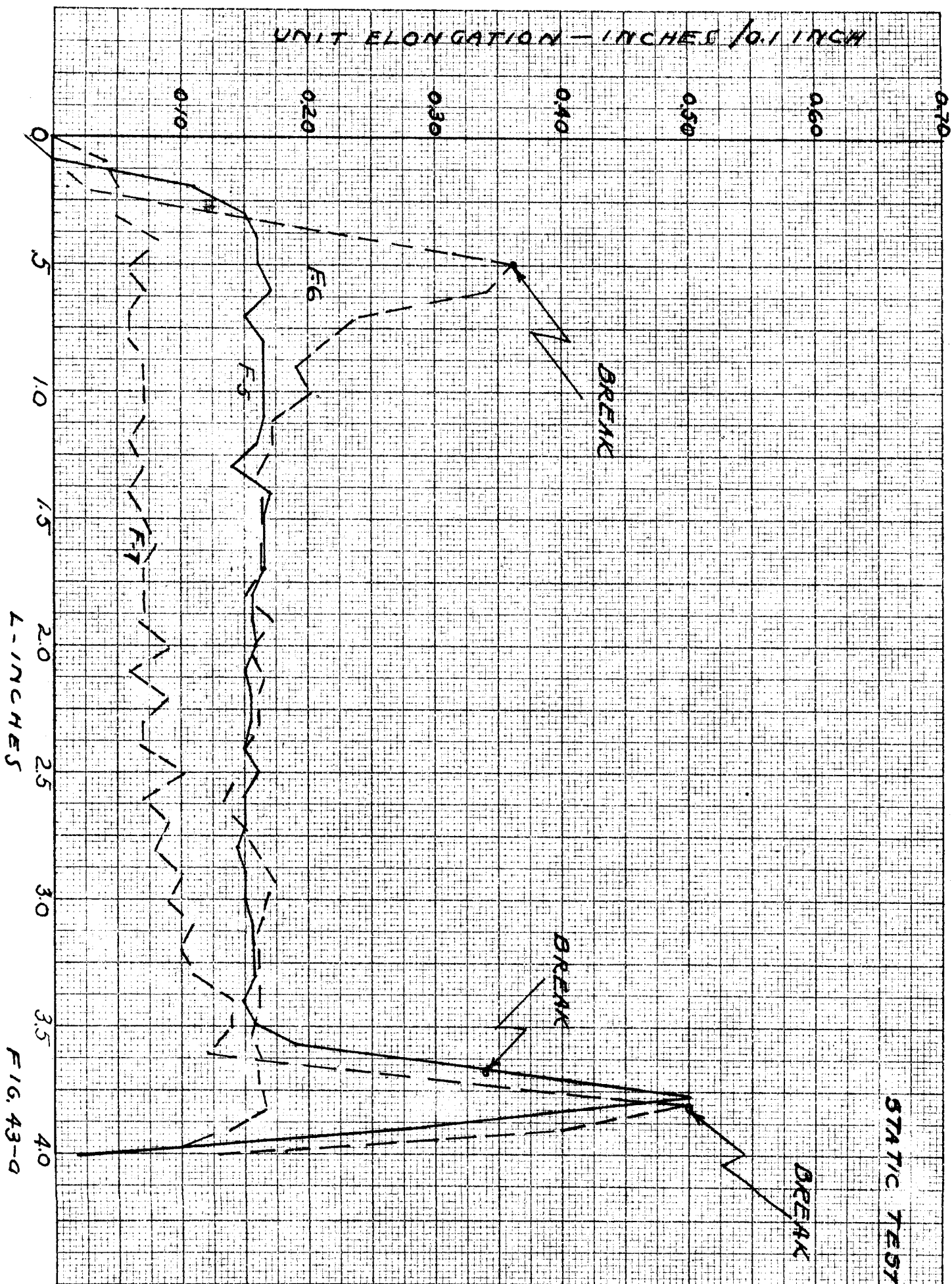
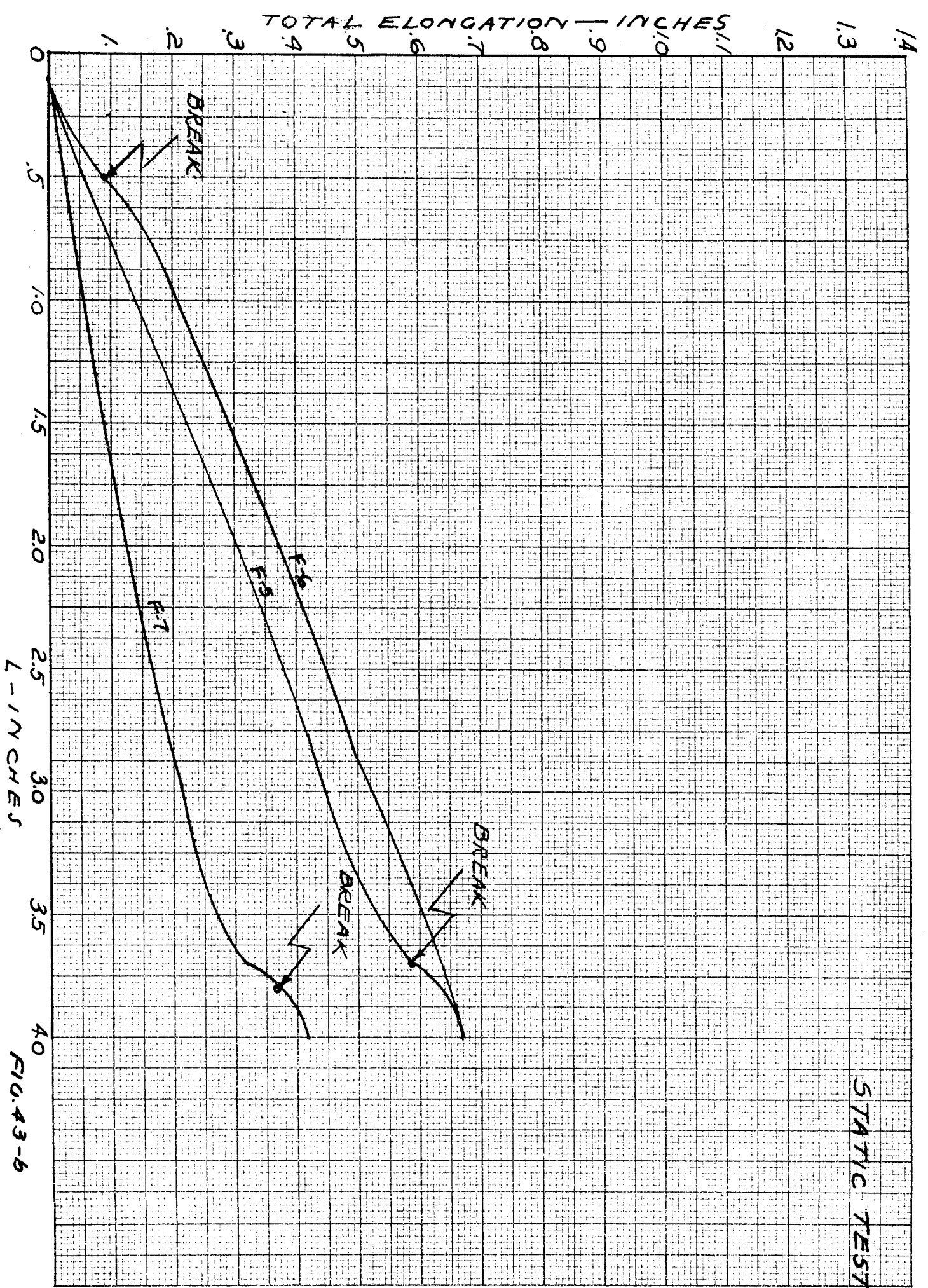
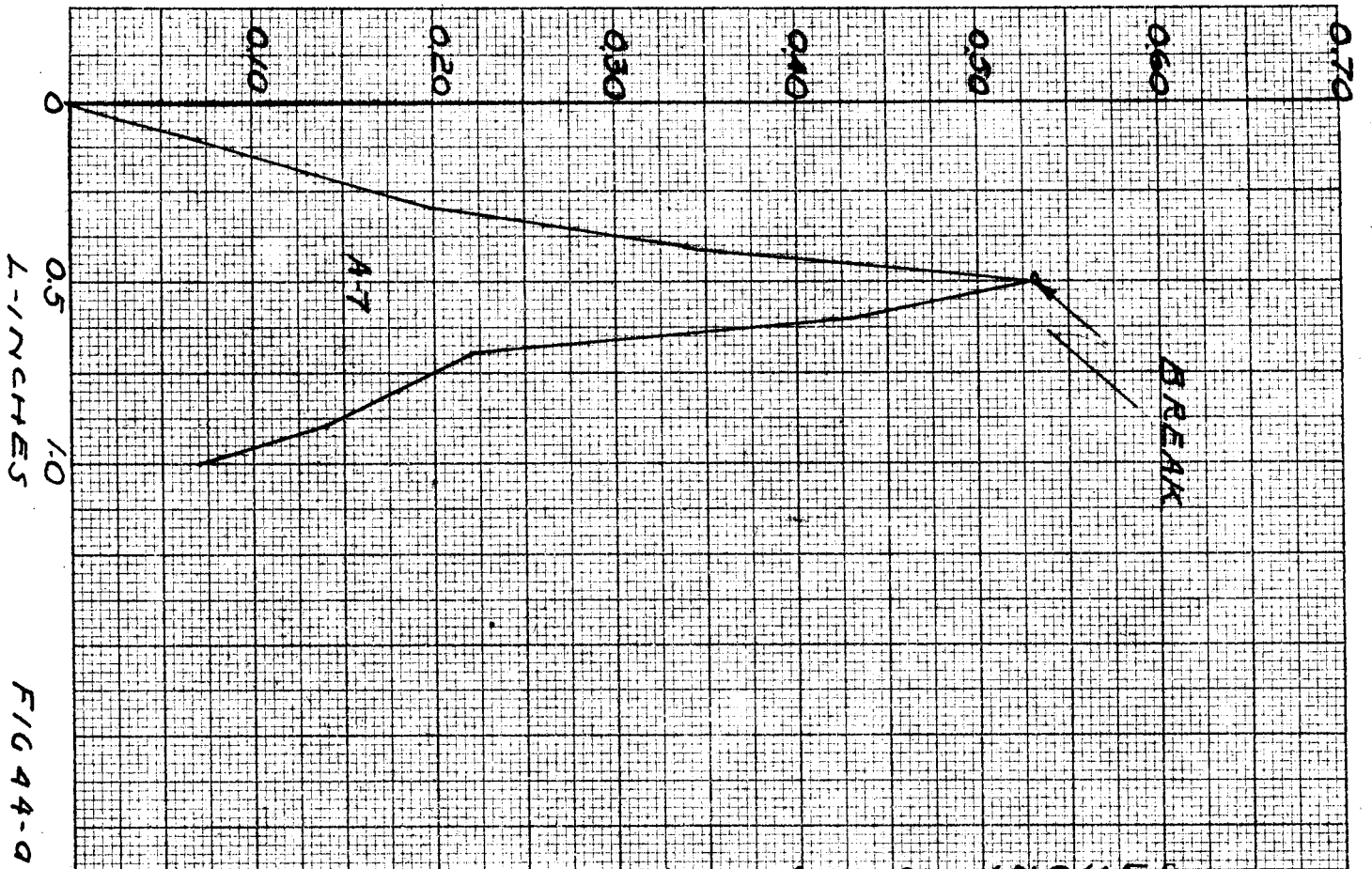


FIG. 42-6

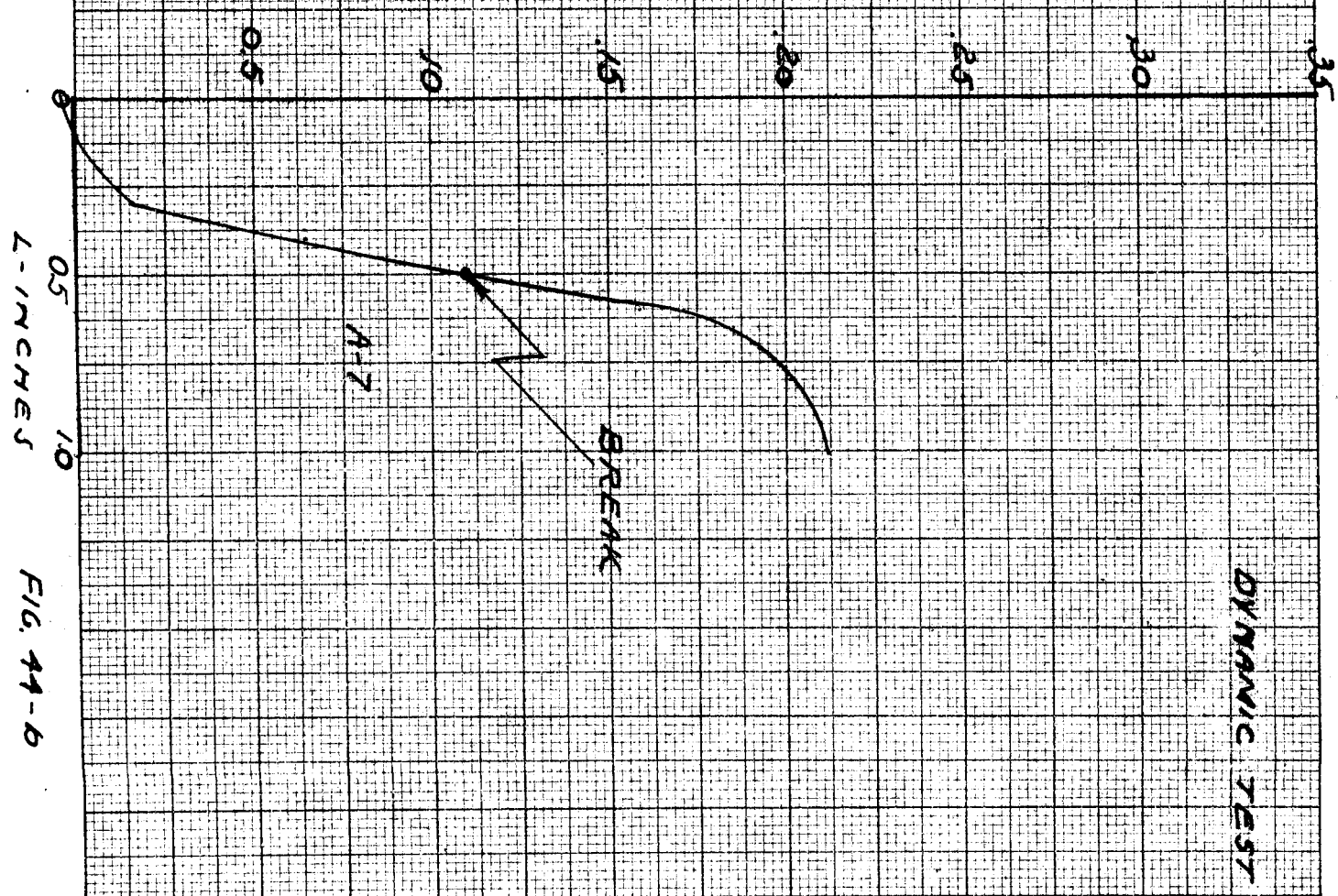




UNIT ELONGATION - INCHES / 0.1 INCH

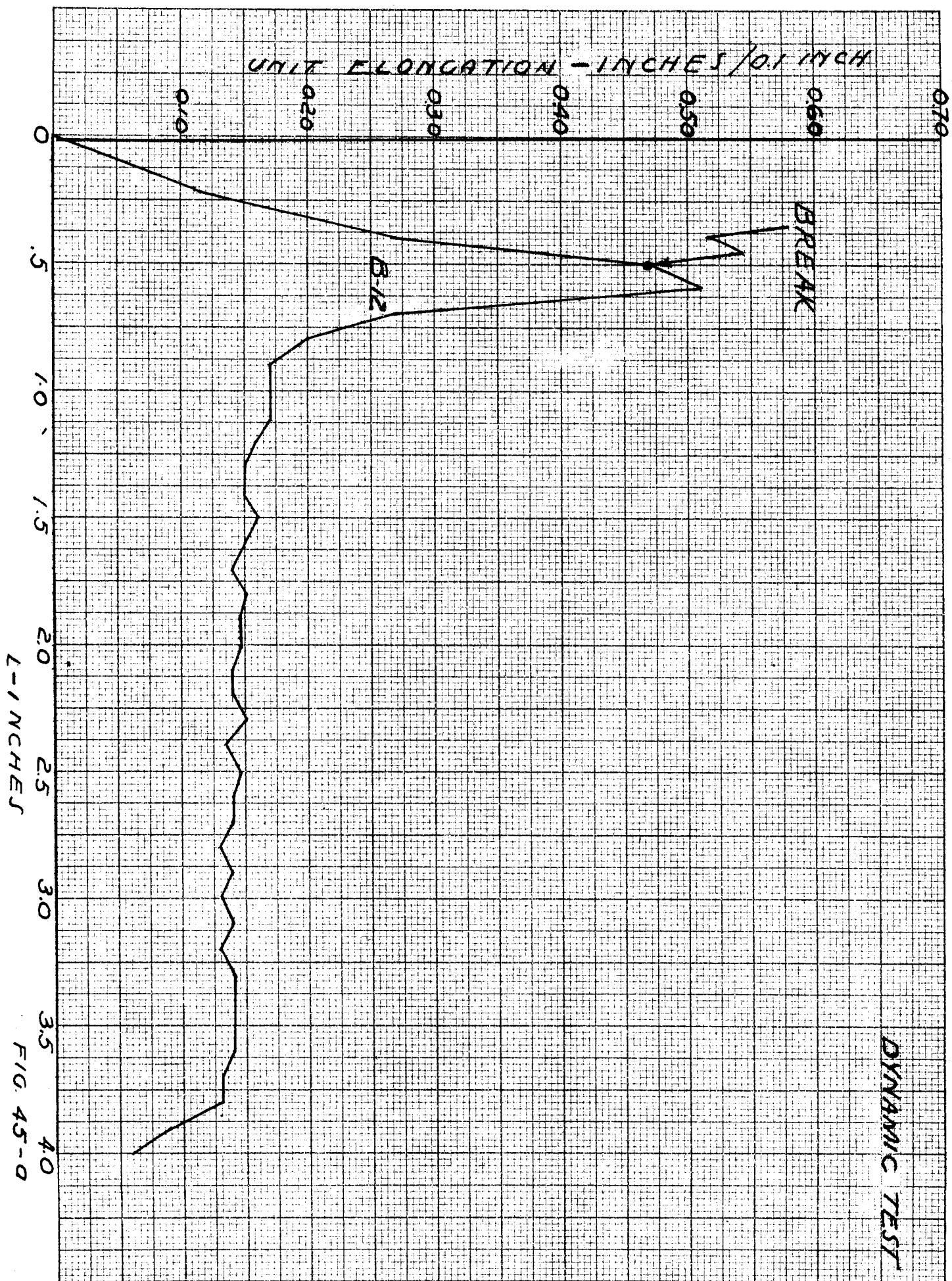


TOTAL ELONGATION - INCHES



DYNAMIC TEST

FIG. 44-b



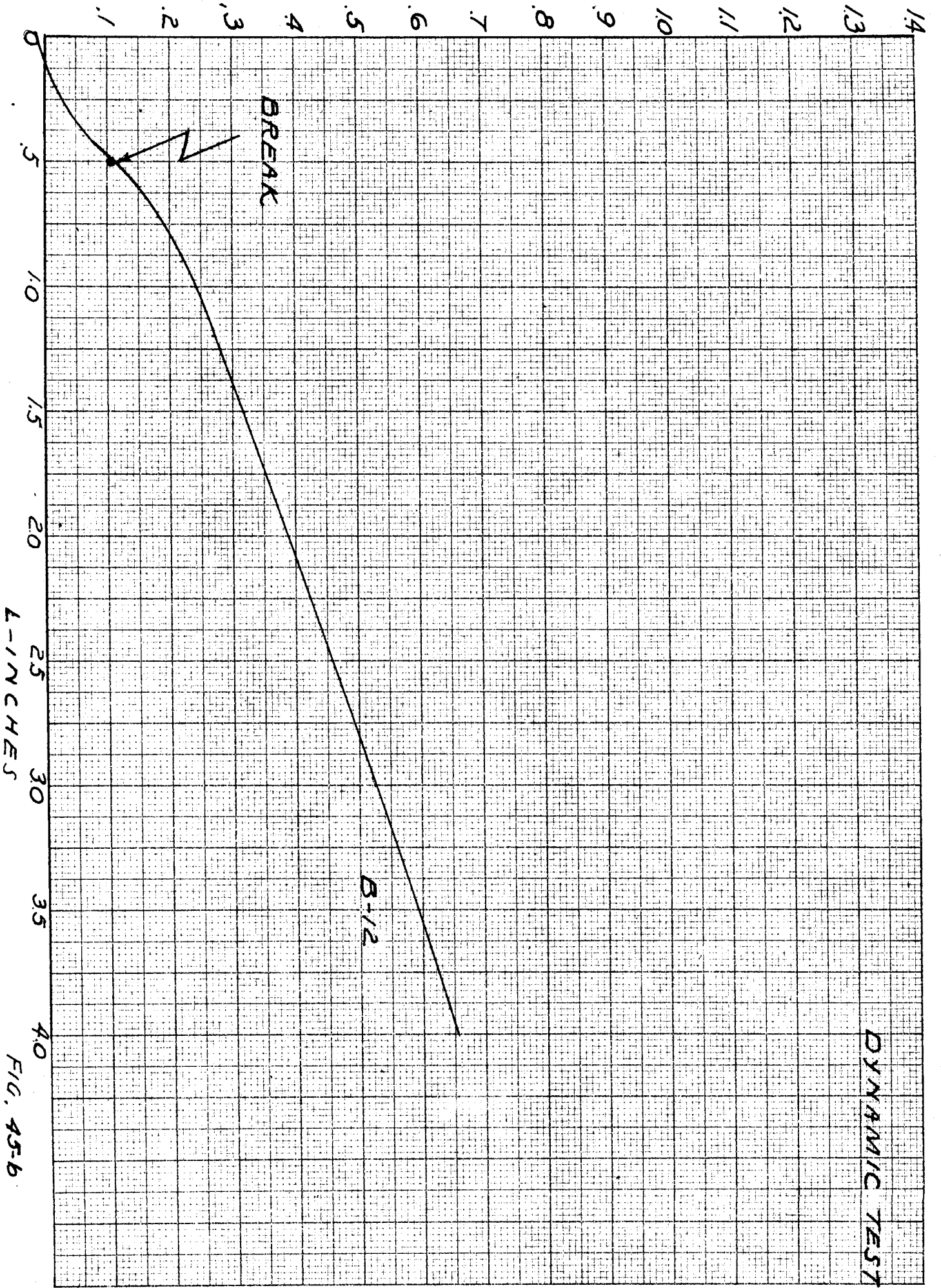


FIG. 45-6

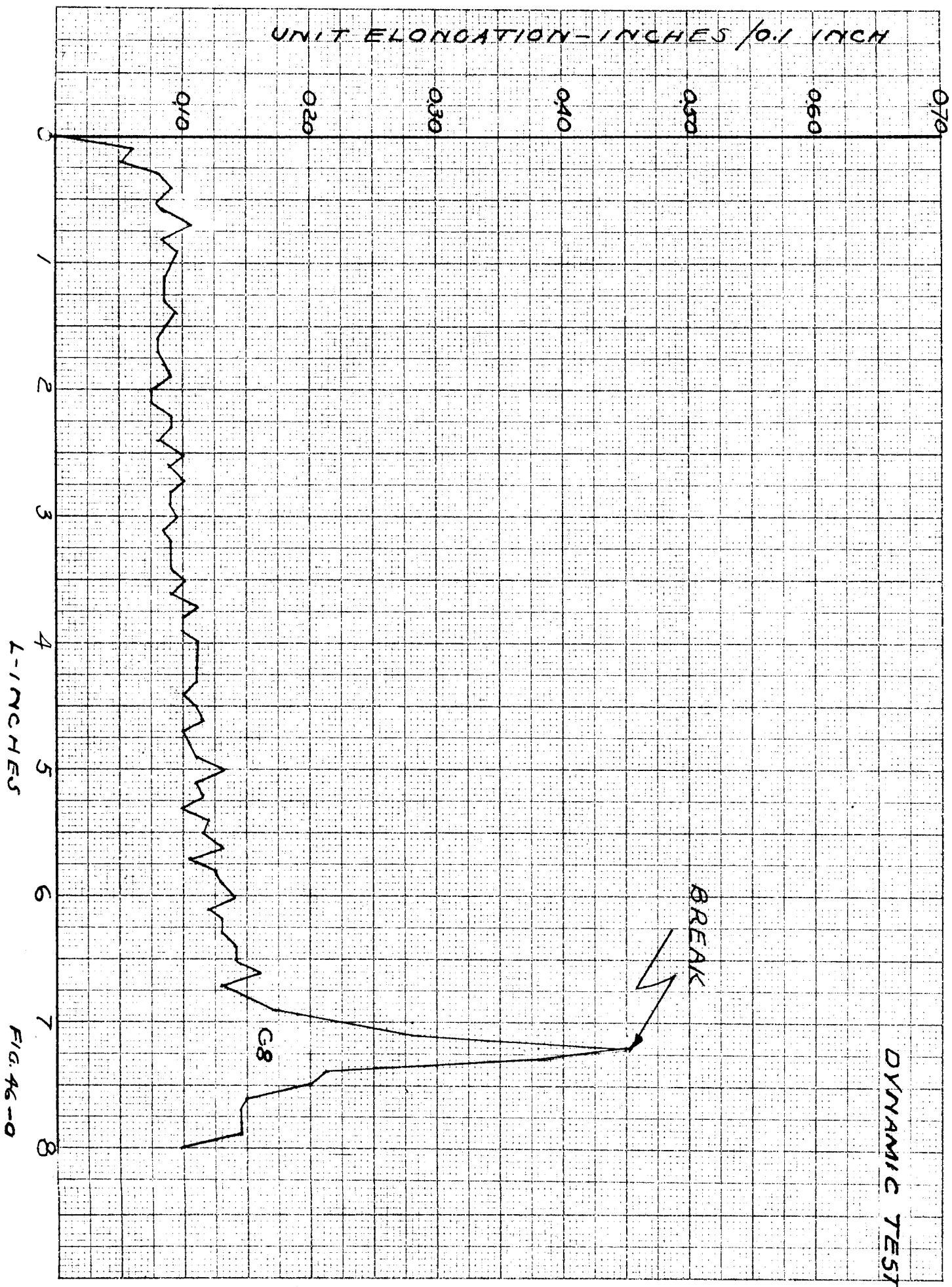


FIG. 46-0

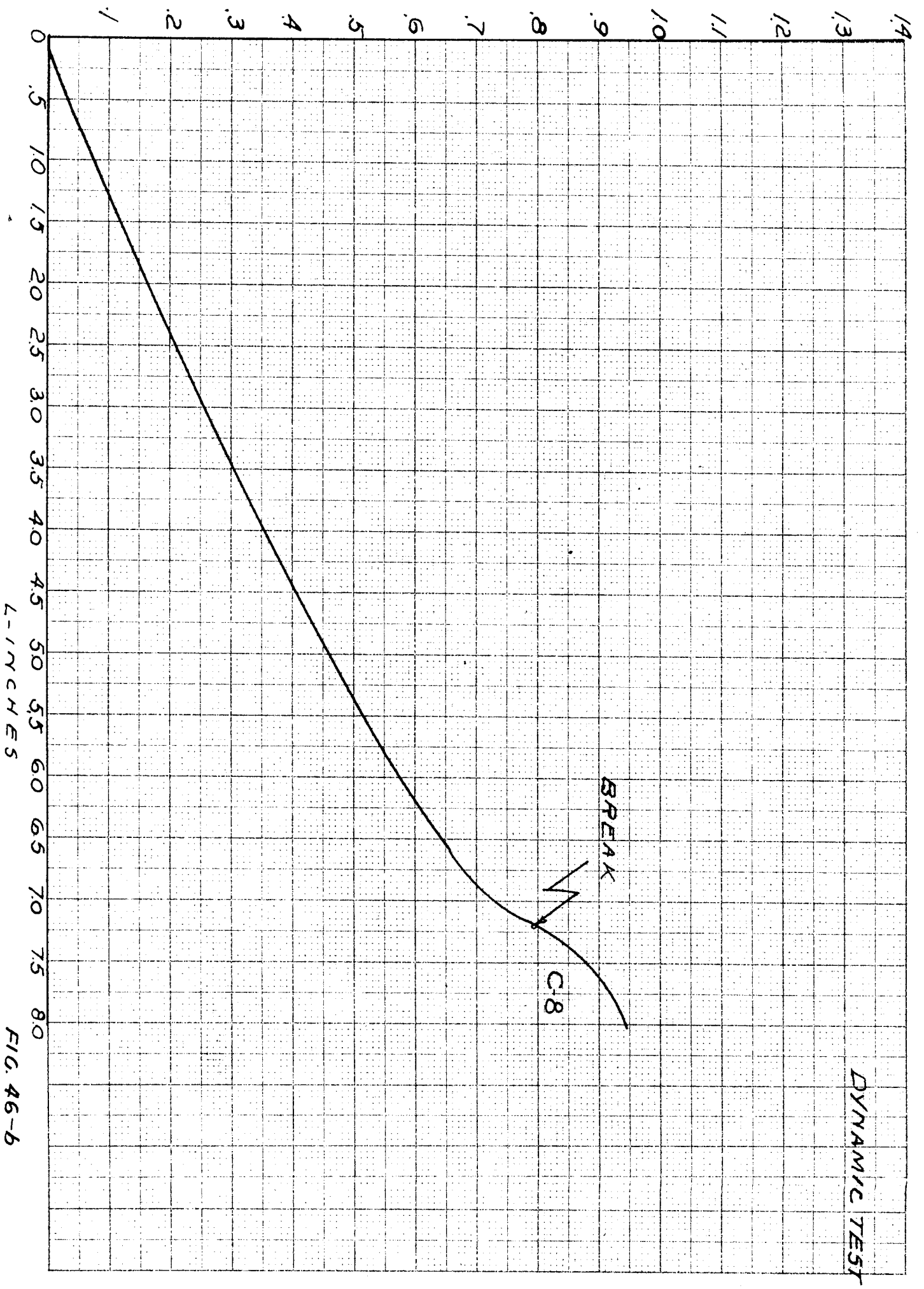
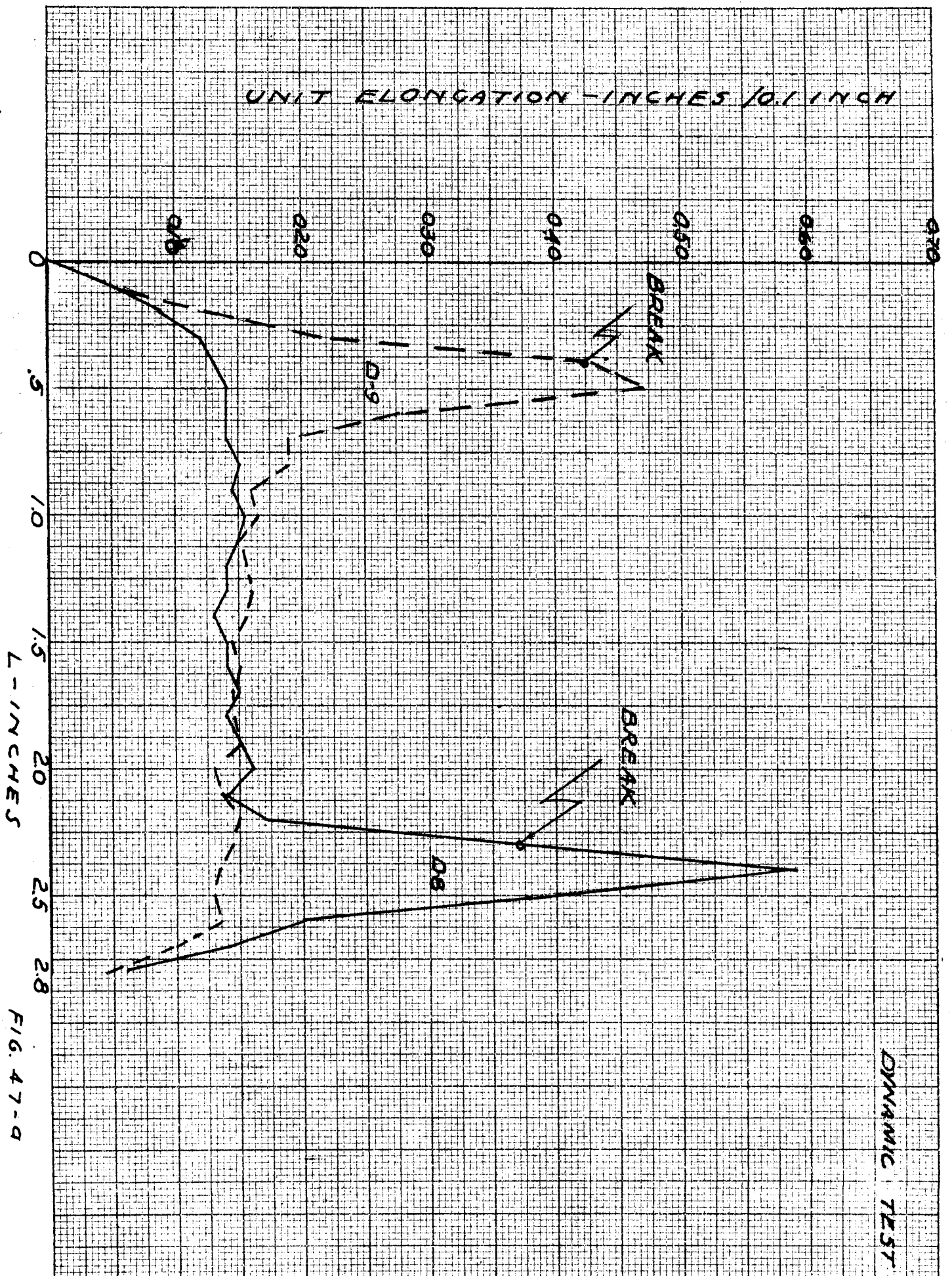


FIG. 46-b



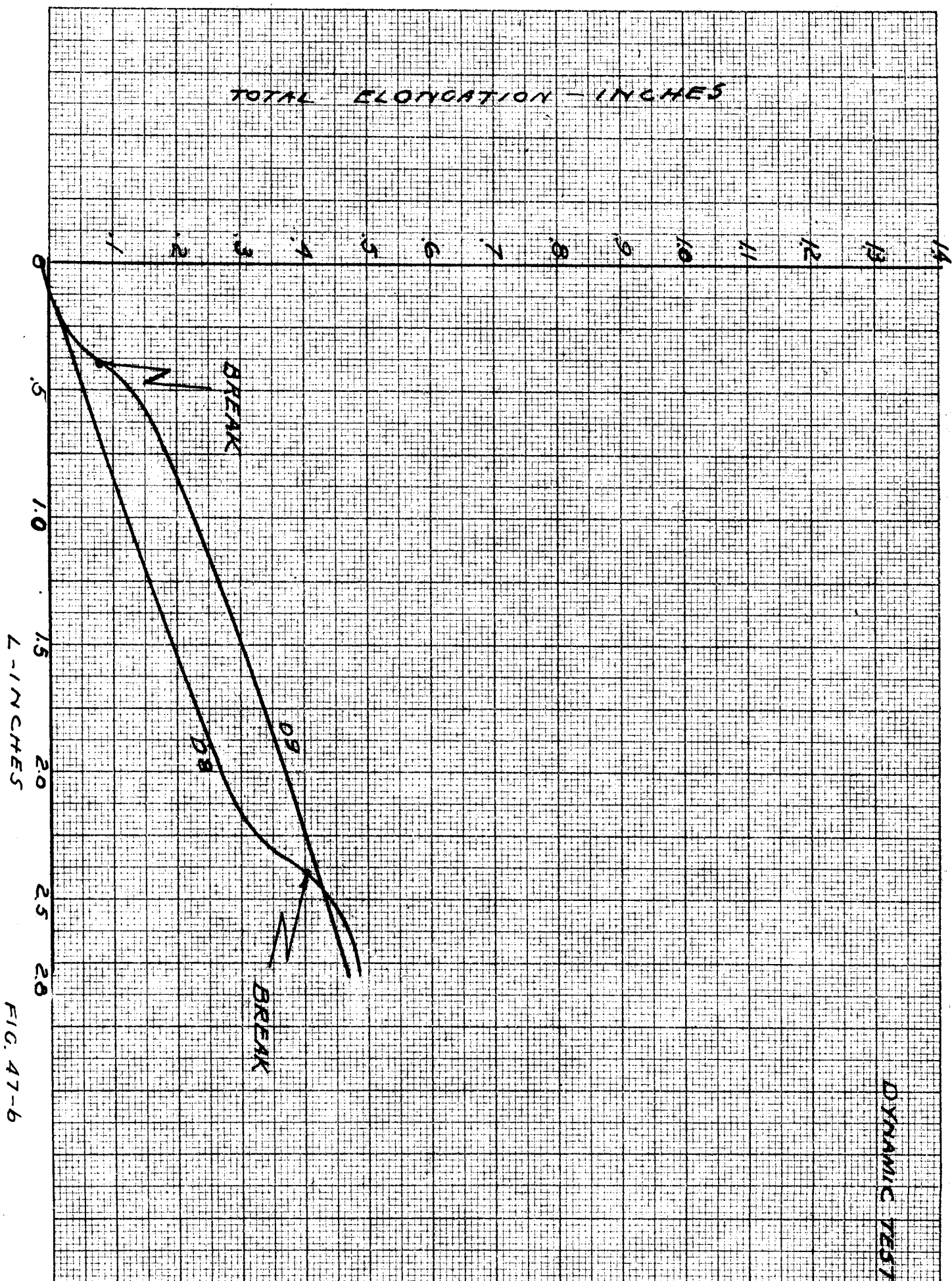
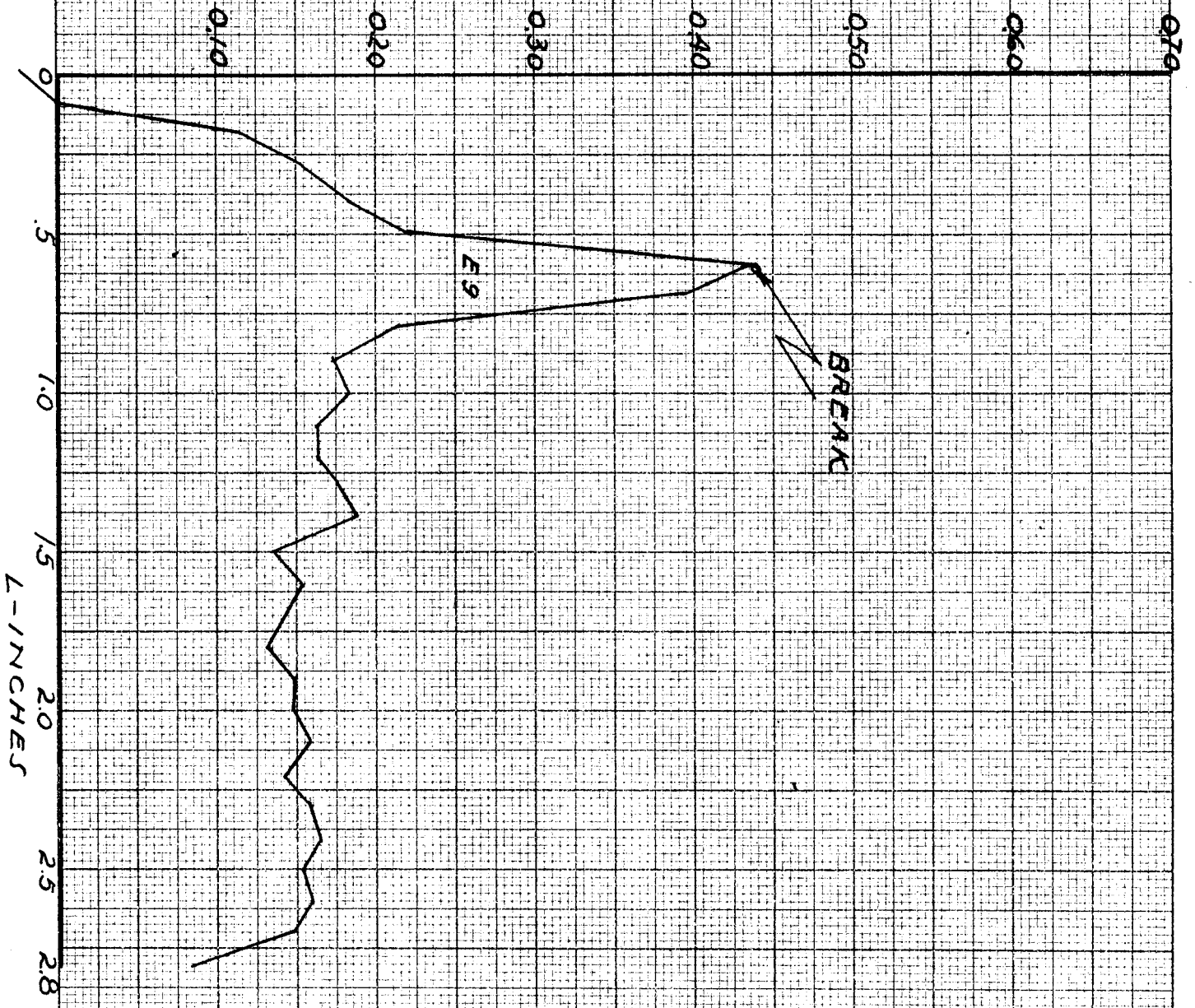


FIG. 47-6

UNIT ELONGATION - INCHES / 0.1 INCH

DYNAMIC TEST



L - INCHES

FIG. 48-a

TOTAL ELONGATION-INCHES

0 1 2 3 4 5 6 7 8 9 10

.5

1.0

1.5

2.0

2.5

2.8

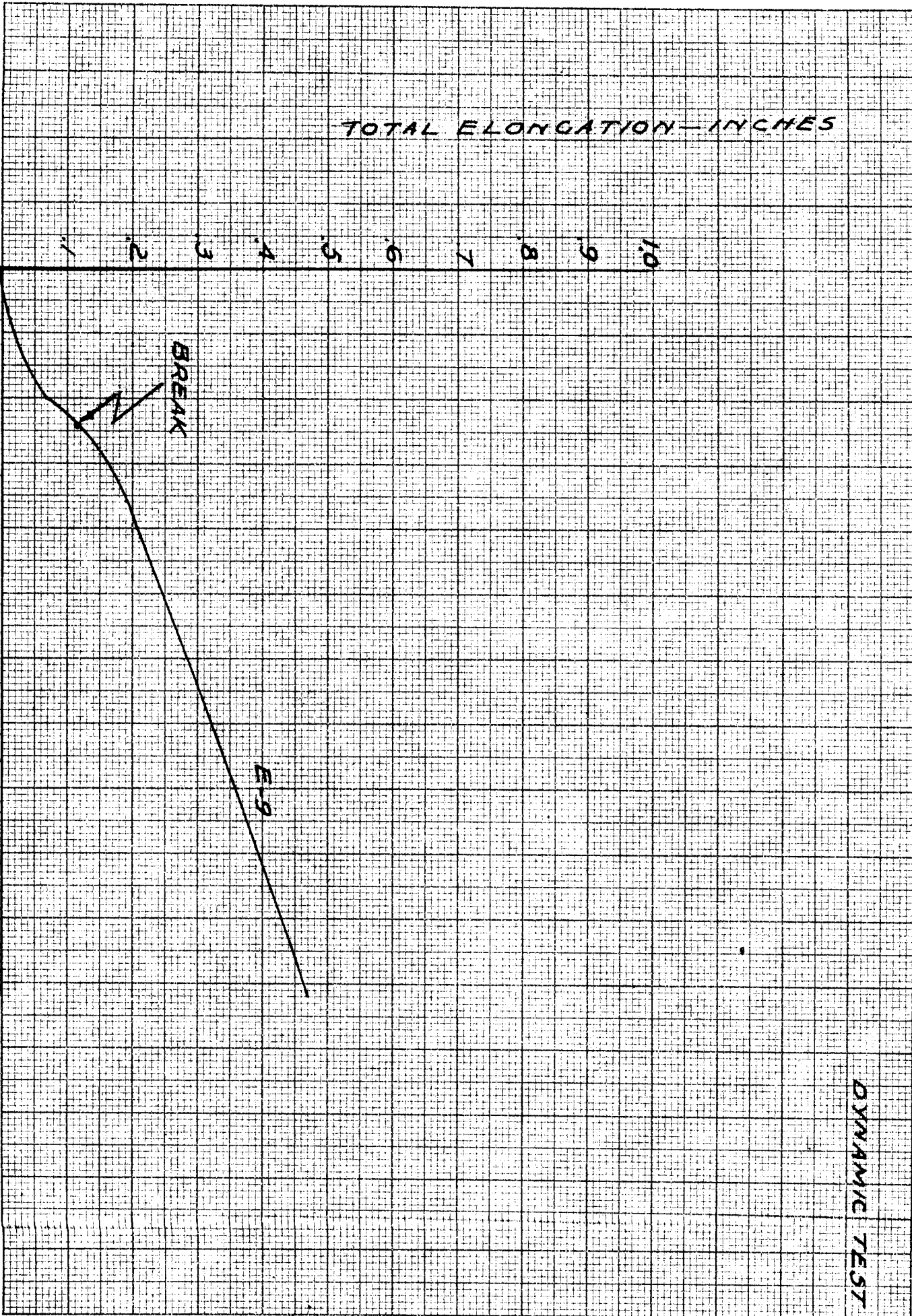
L-INCHES

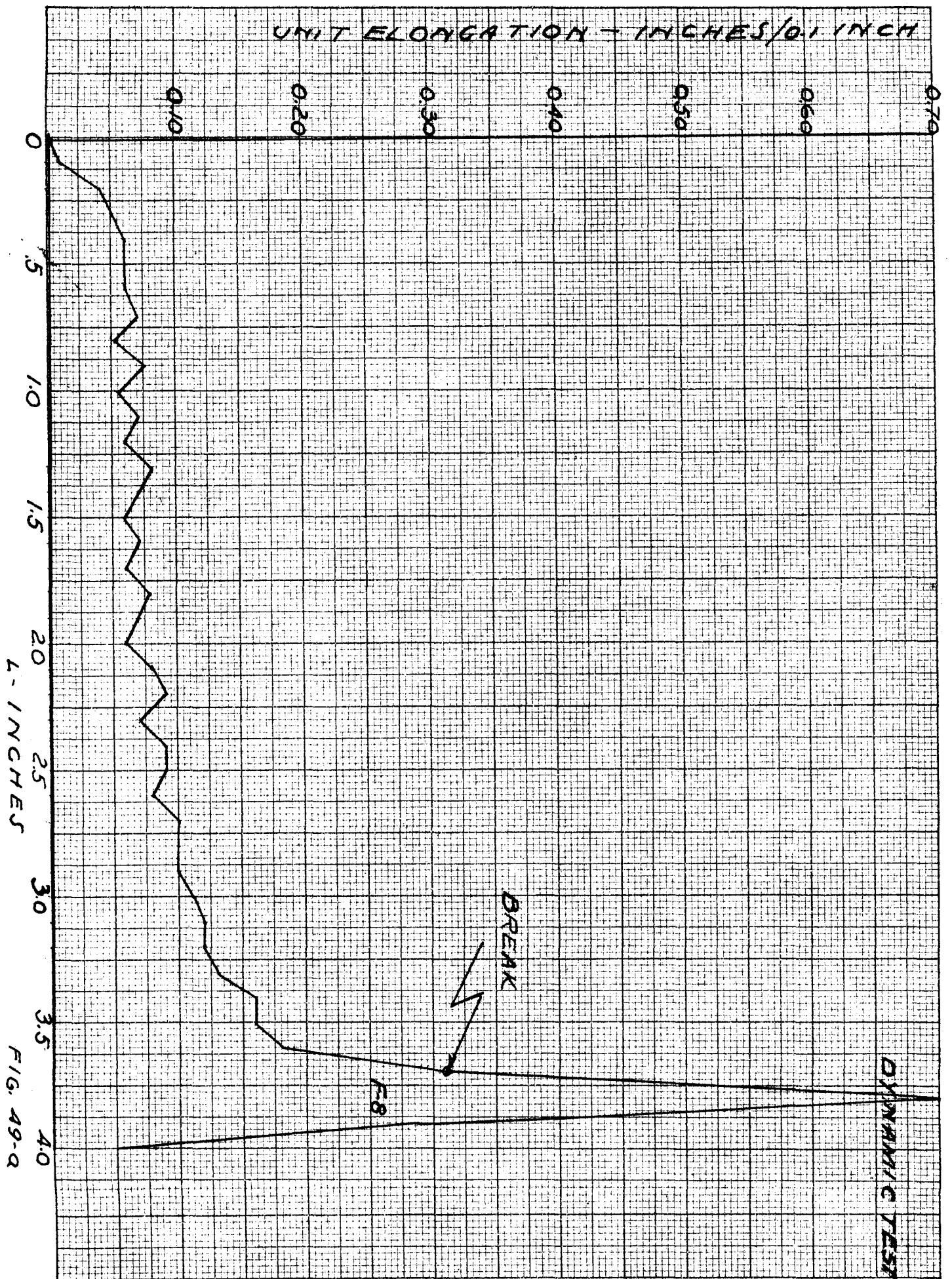
FIG. 48-6

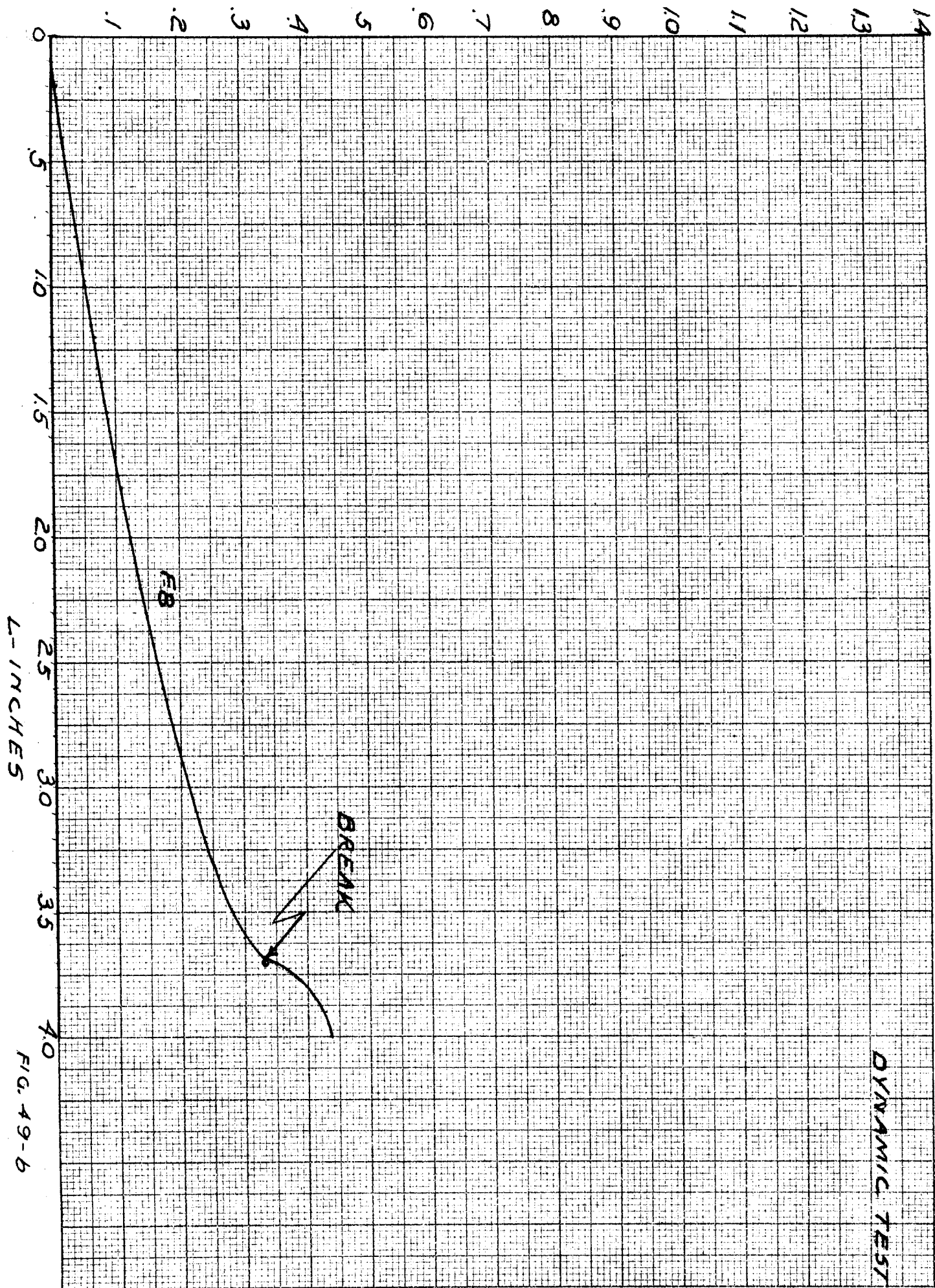
BREAK

E-9

DYNAMIC TEST







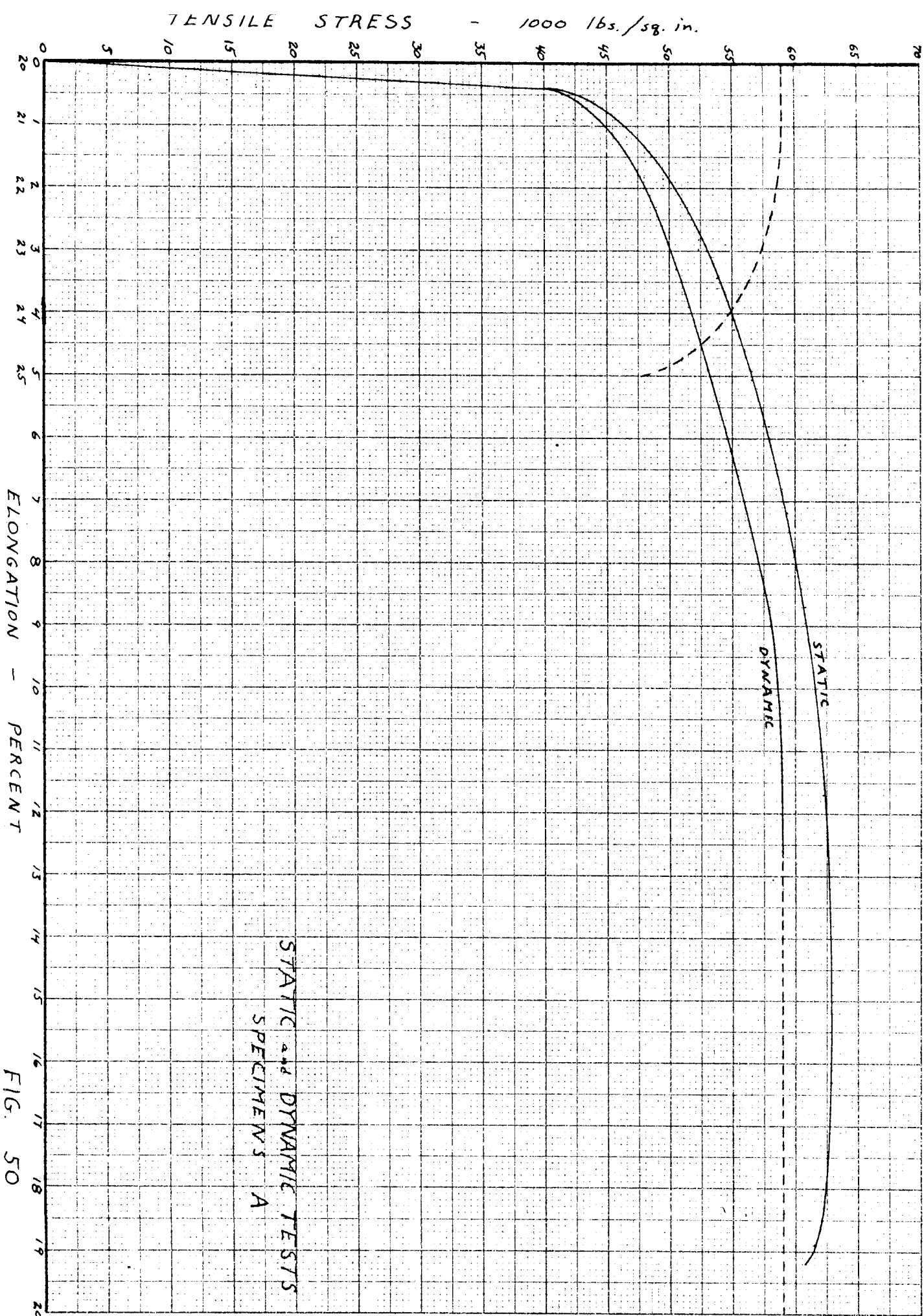


FIG. 50

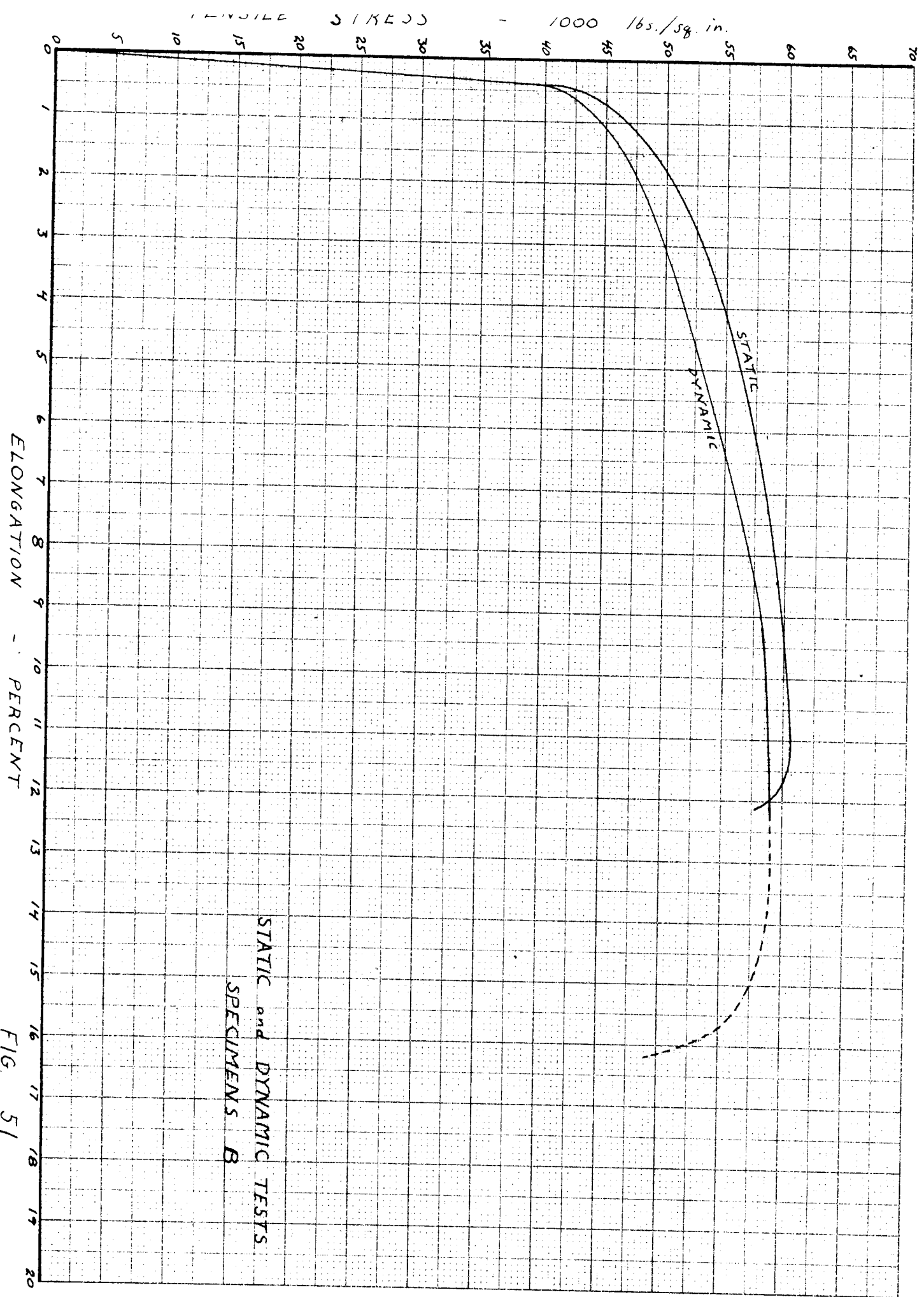


FIG. 51

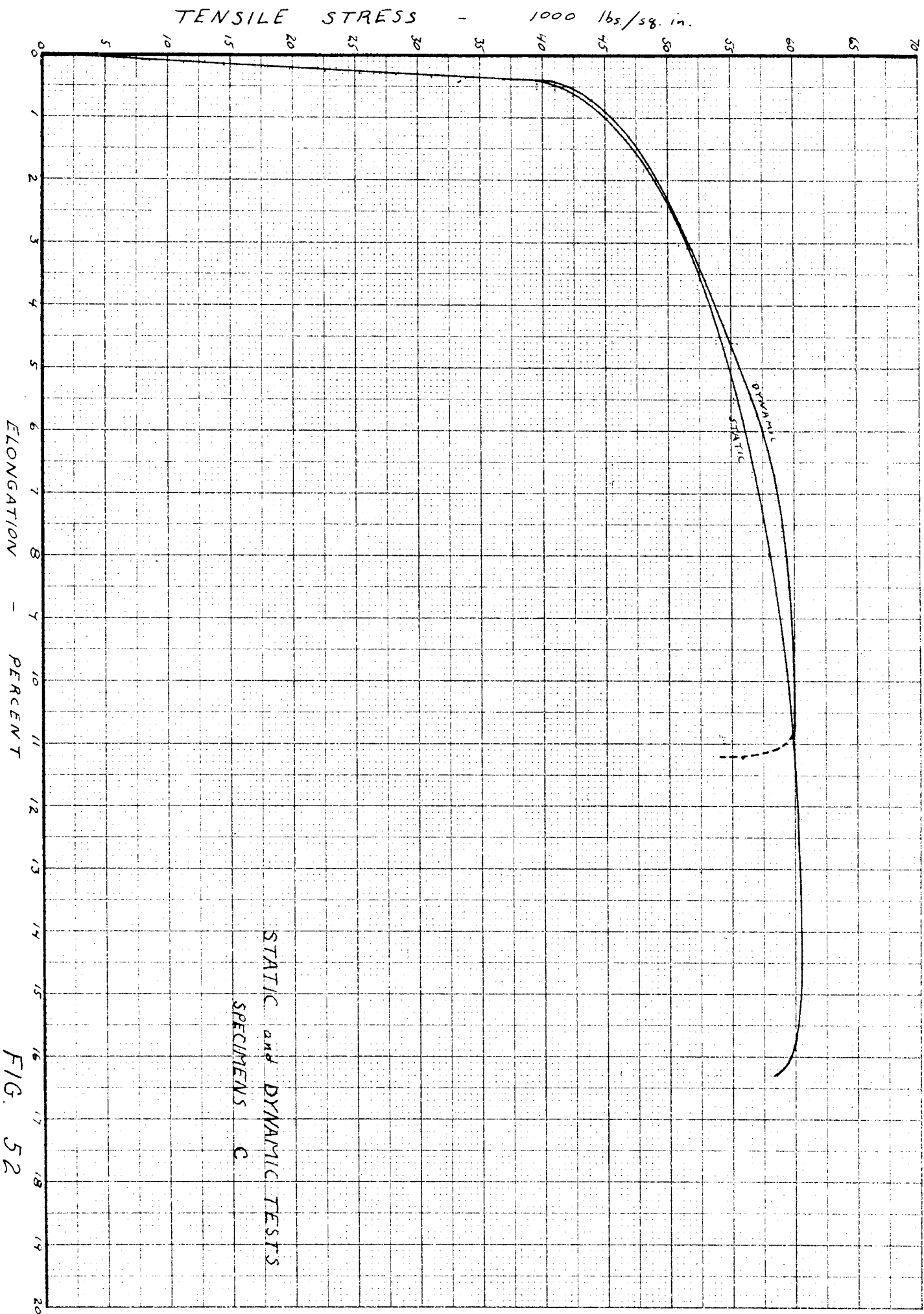


FIG. 52

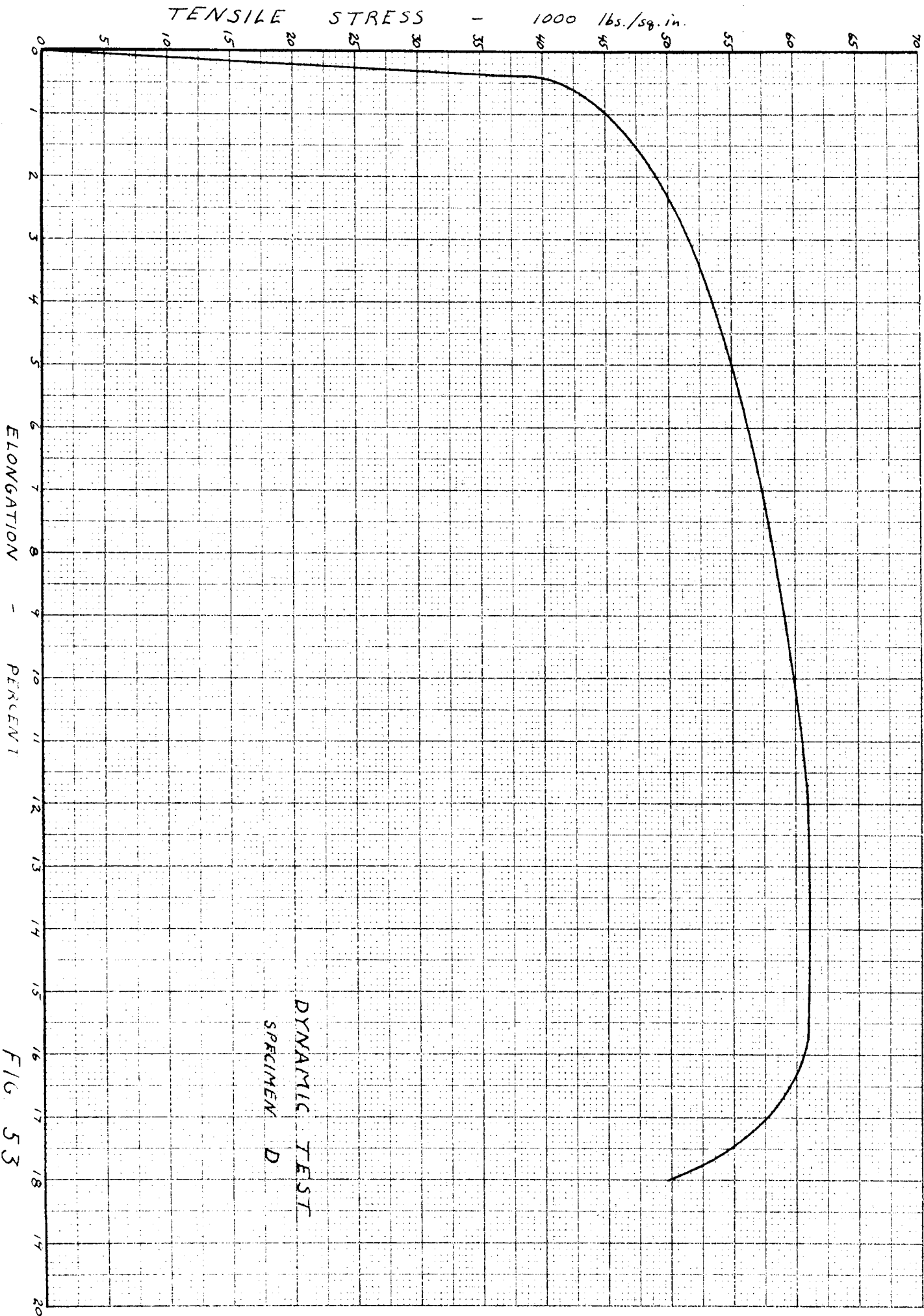
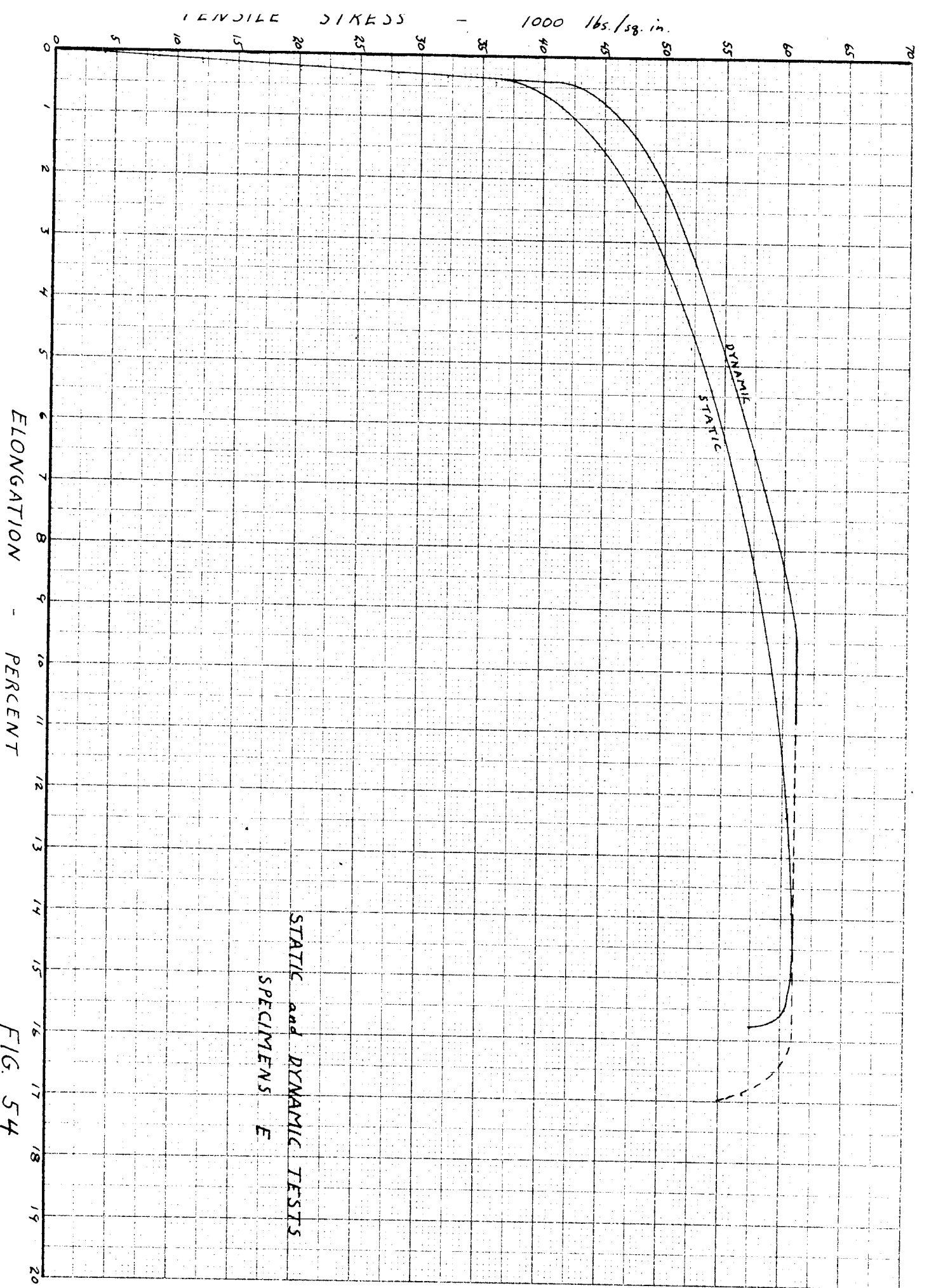
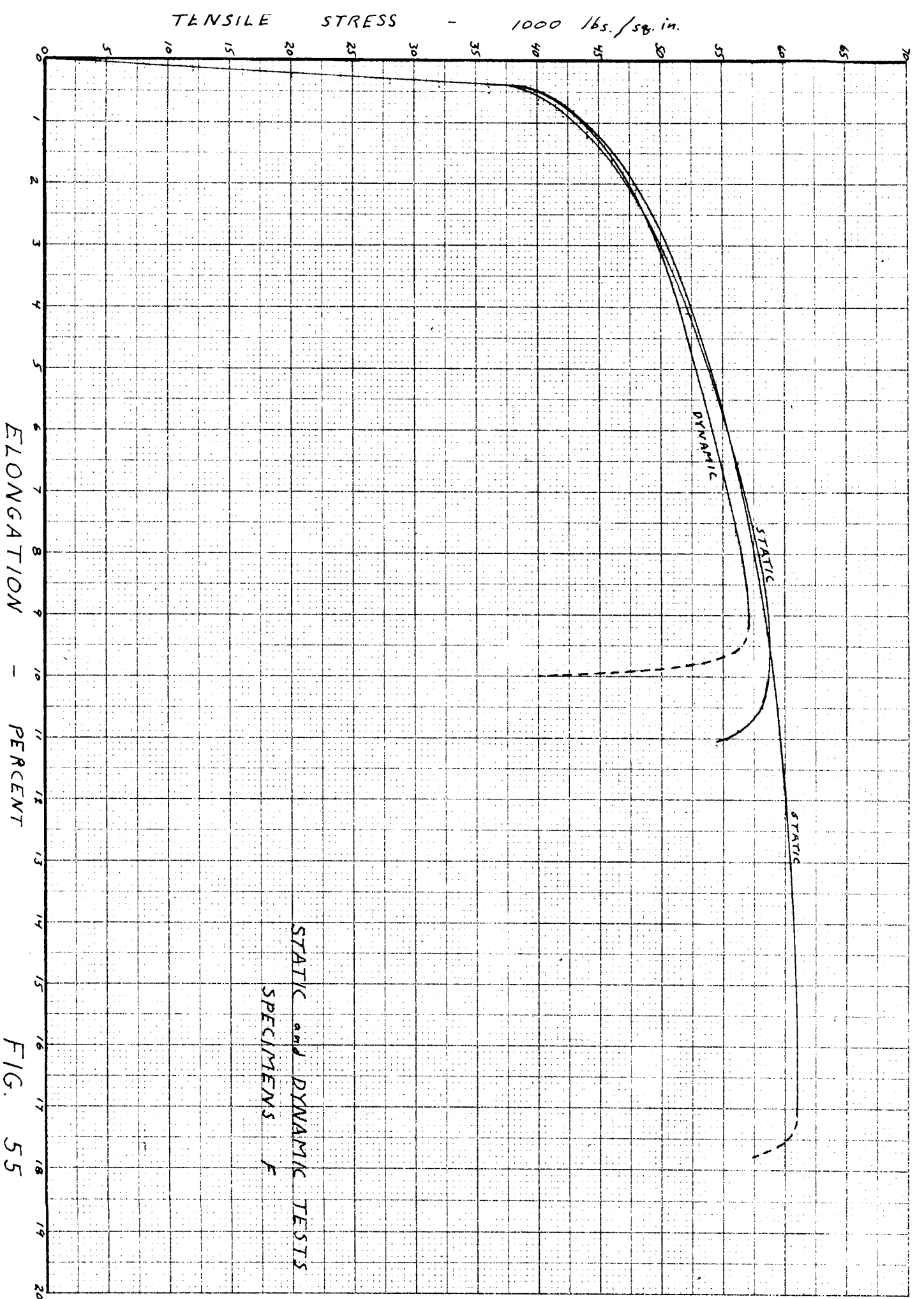


FIG 53





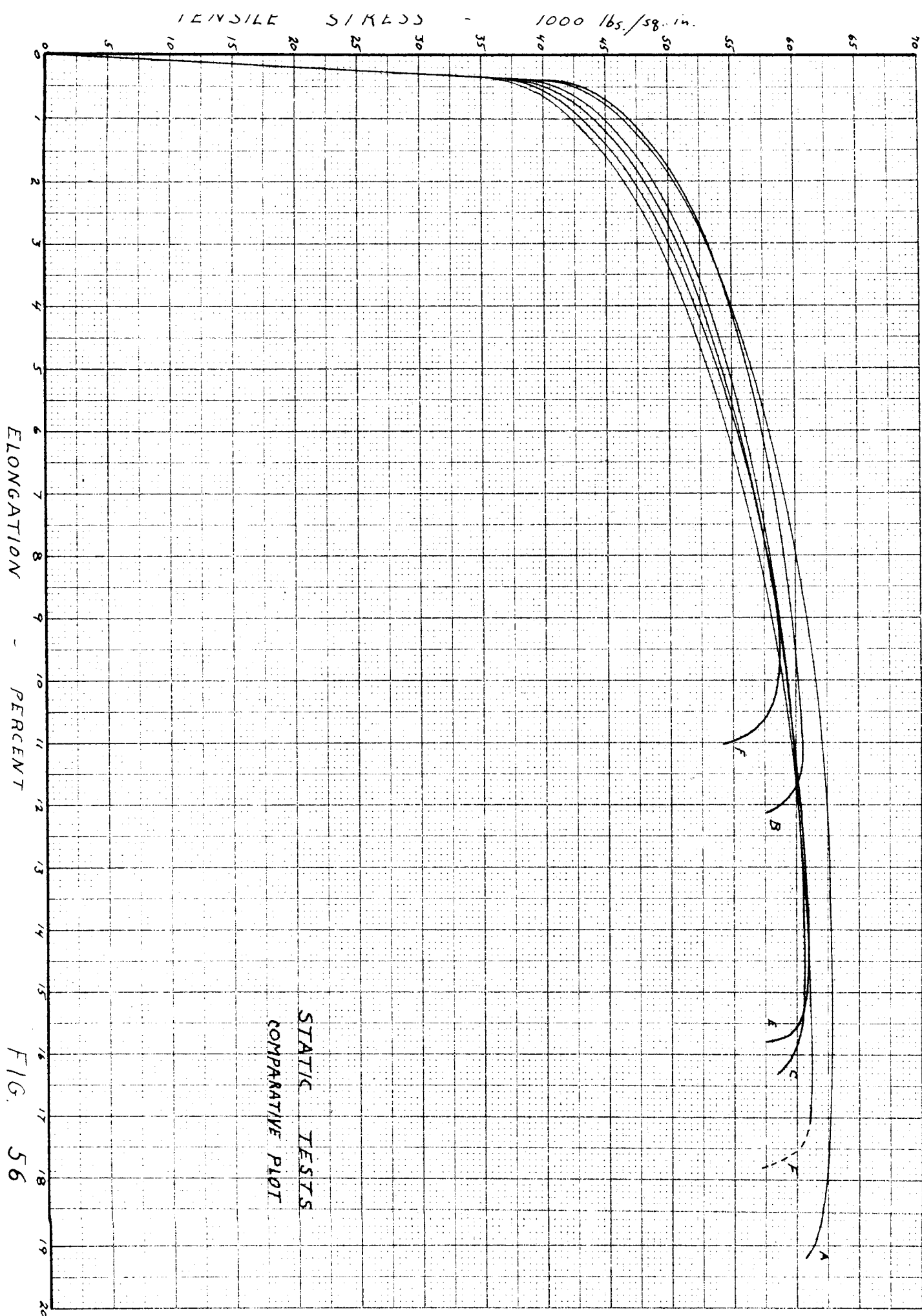


FIG. 56

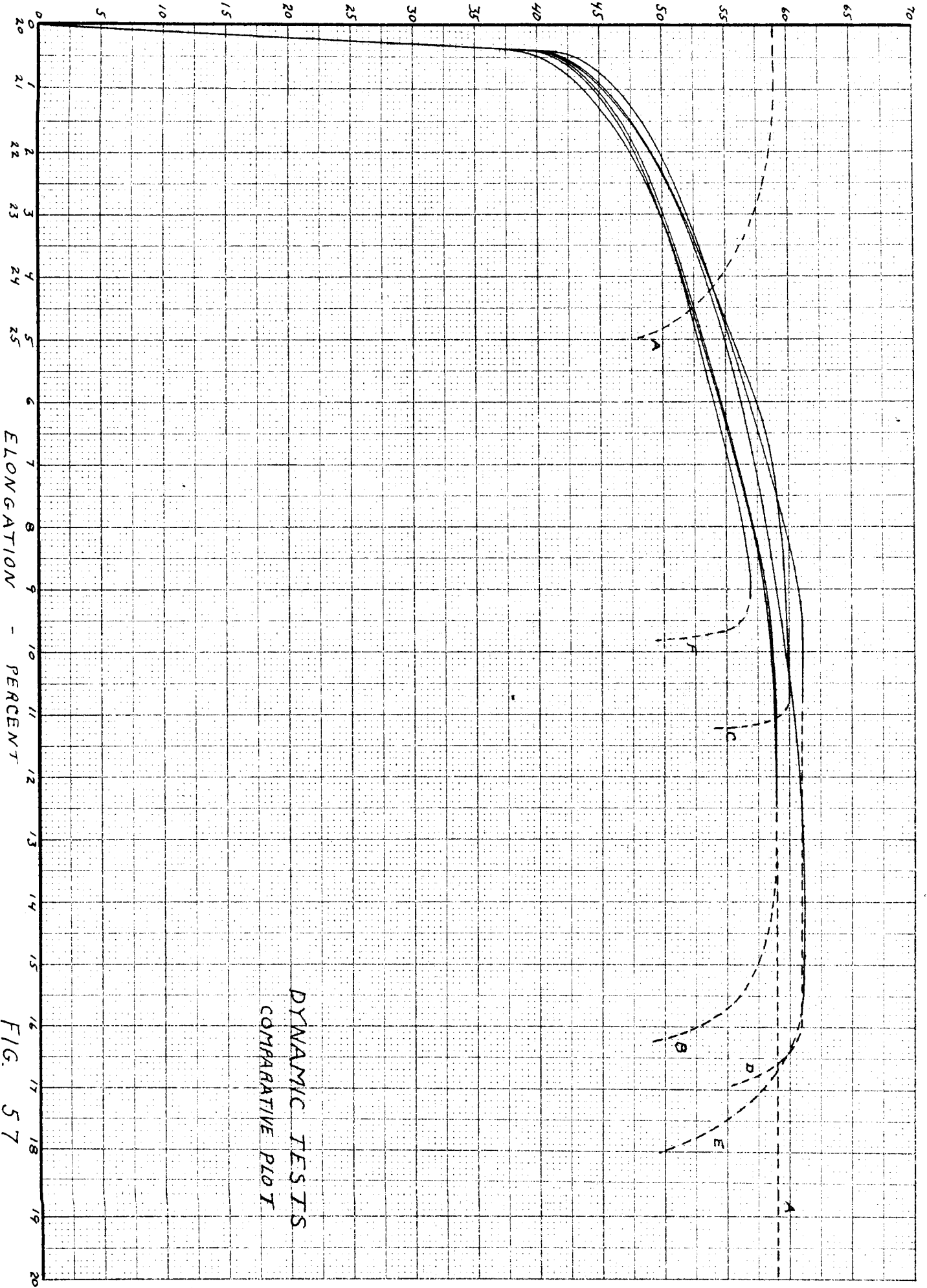


FIG. 57

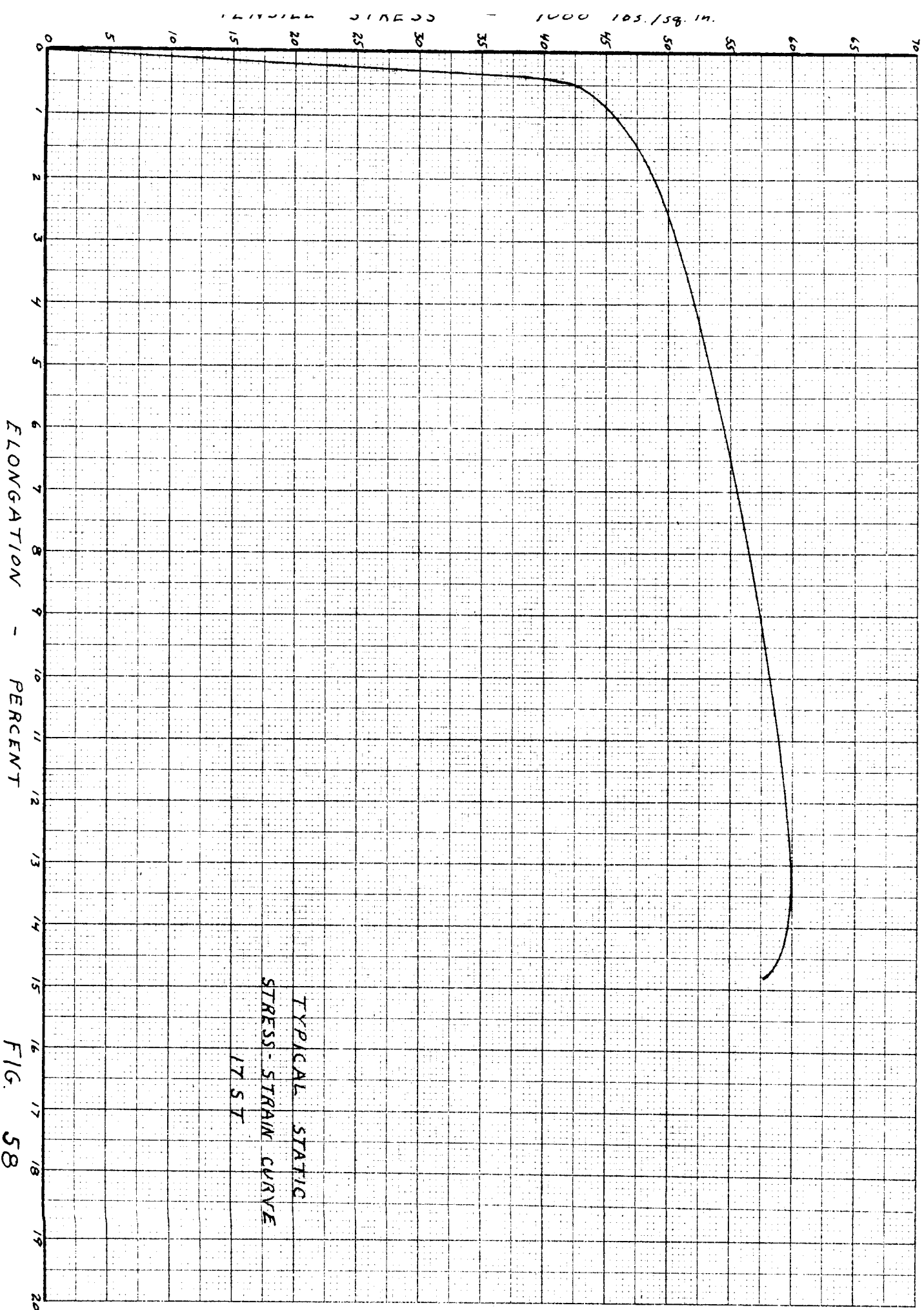
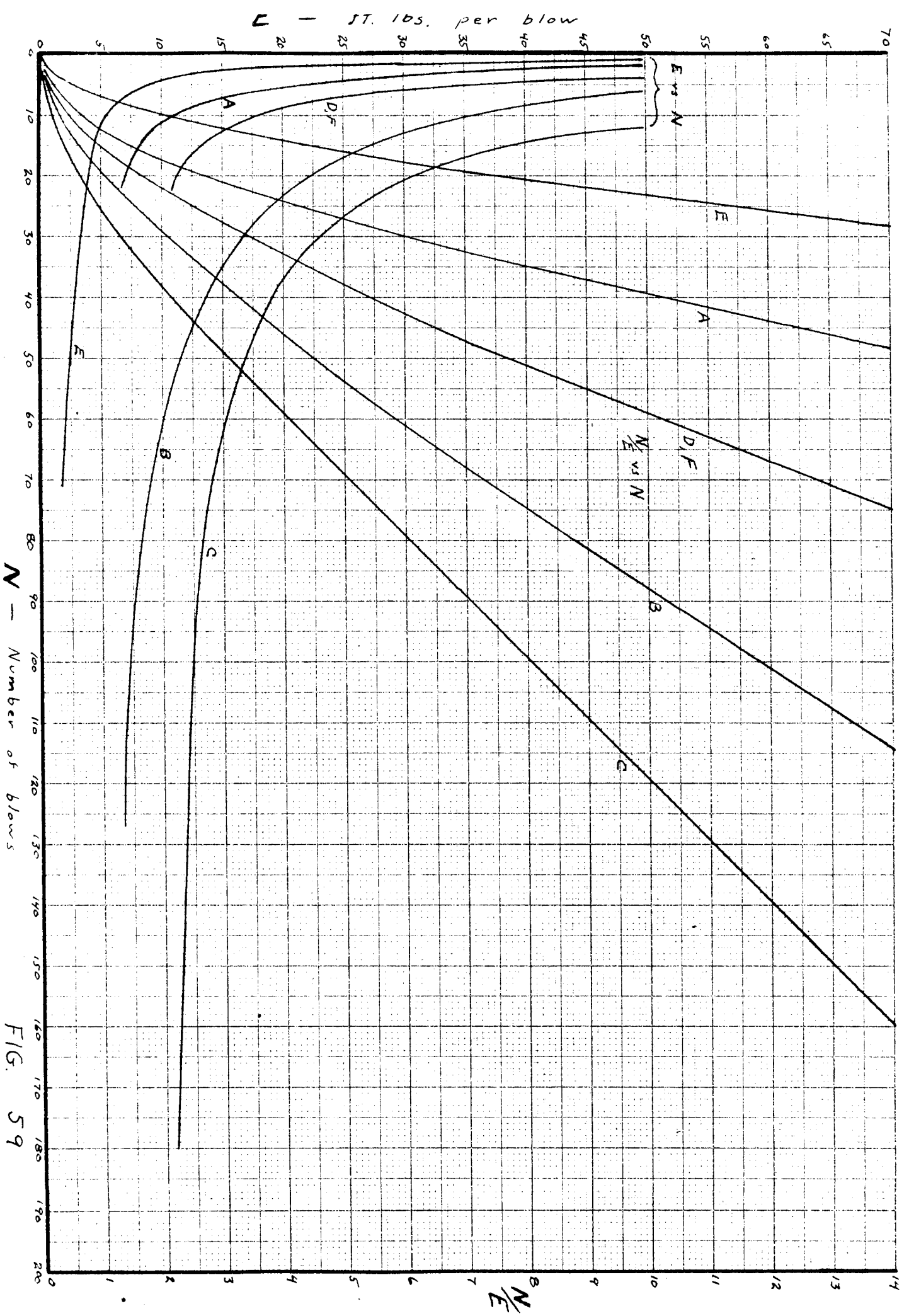
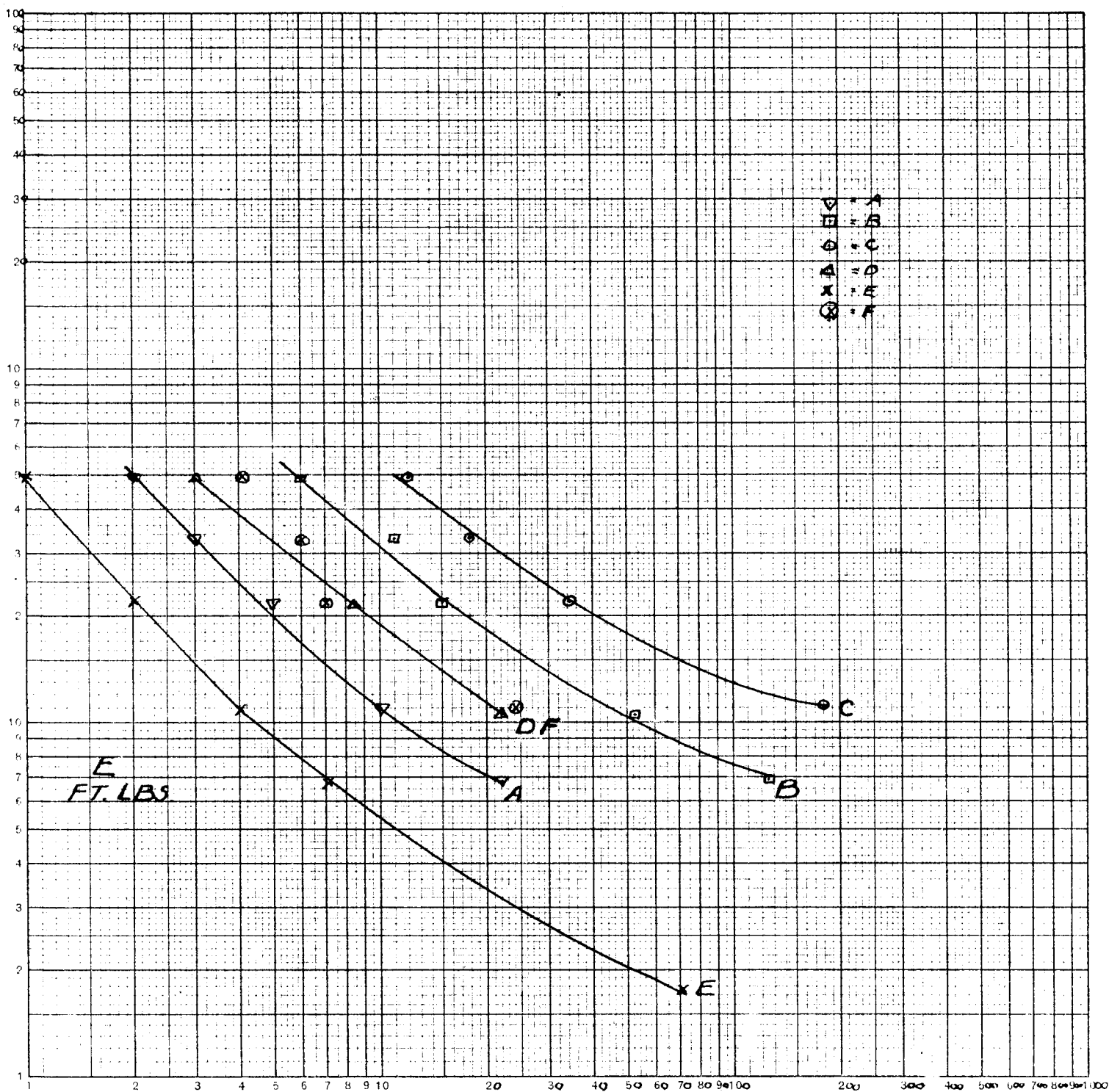


FIG. 58

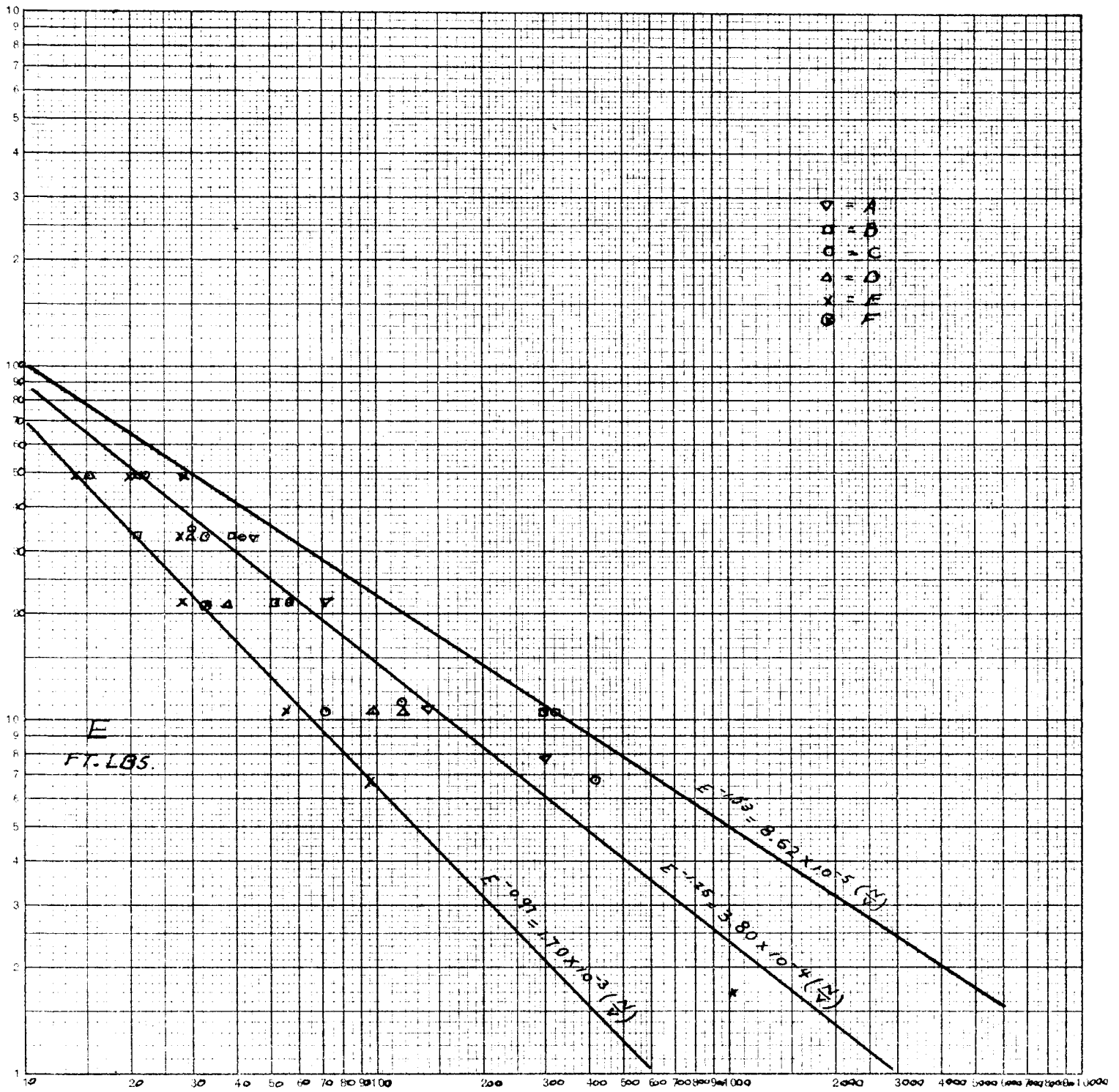


N - Number of blows



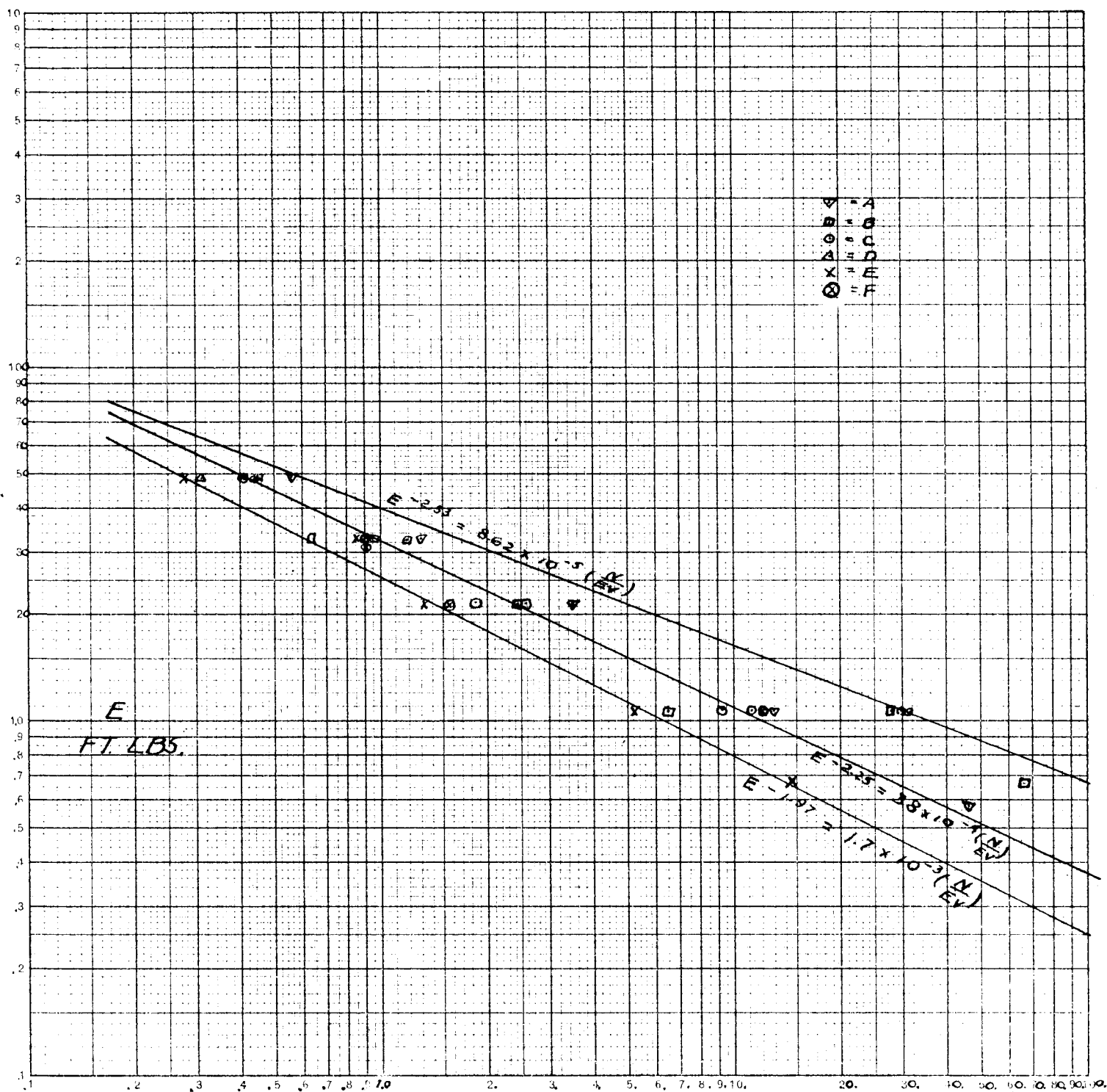
N

FIG. 60



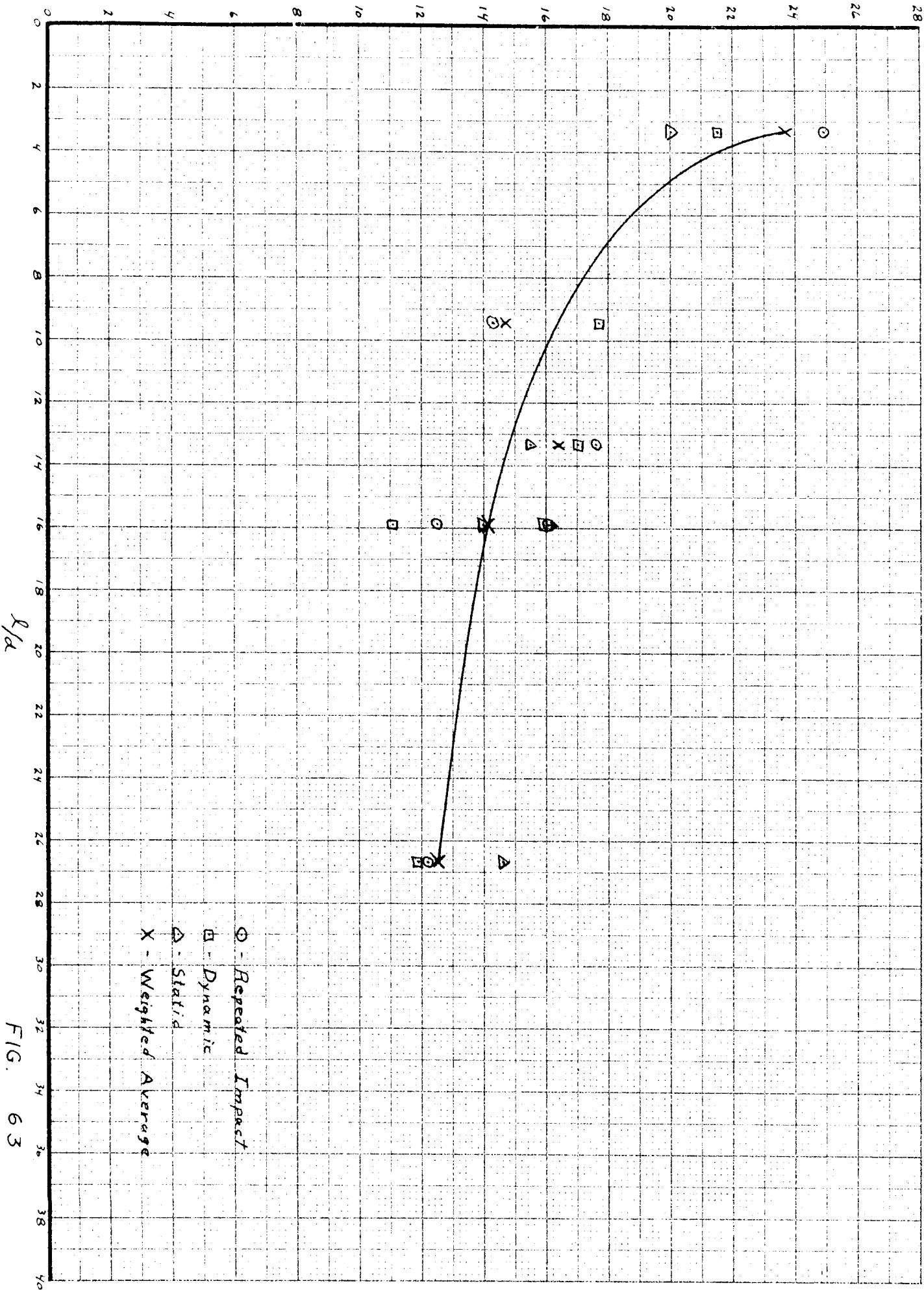
1/2

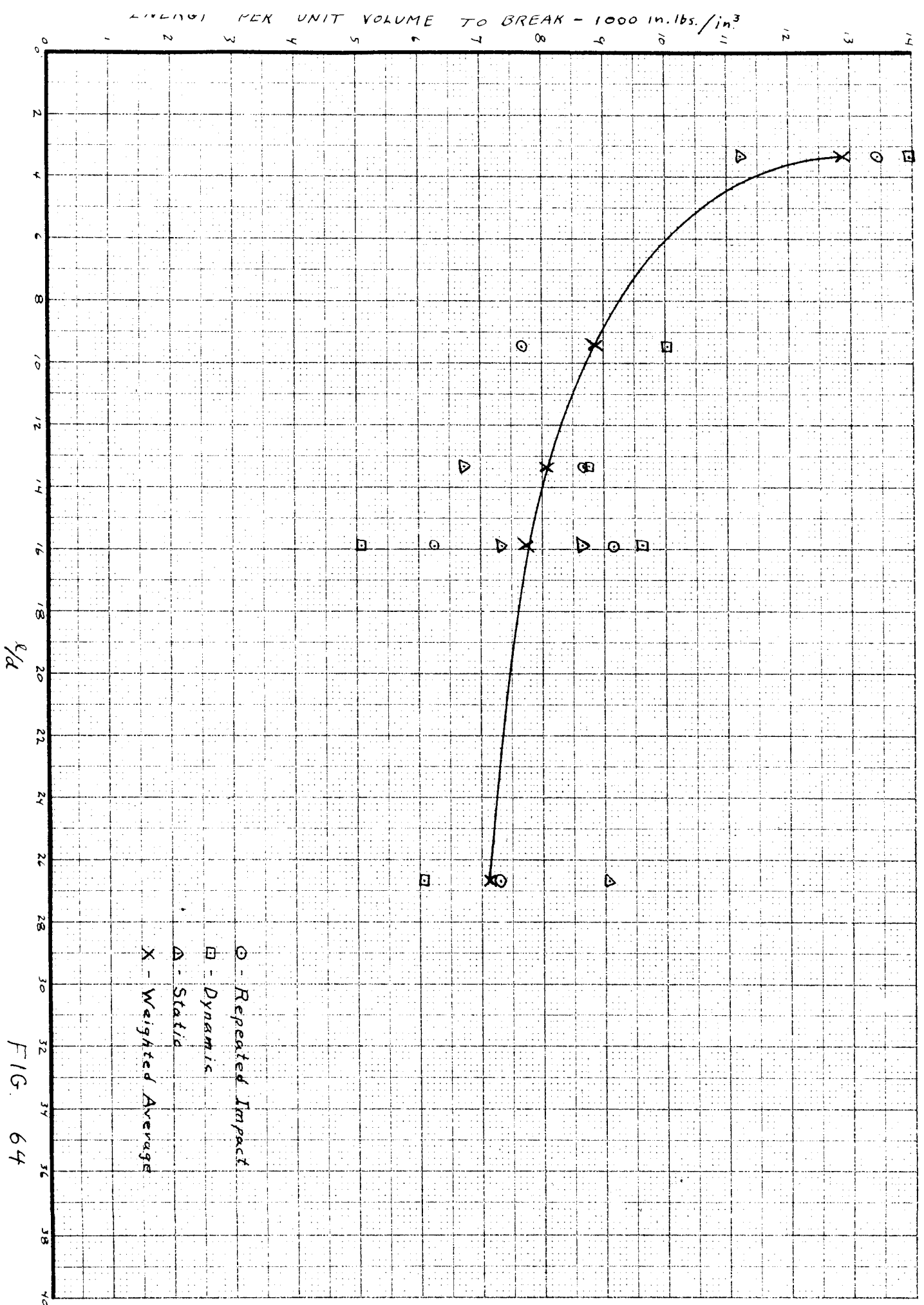
FIG. 61



$\frac{N}{EV}$

FIG. 62





F1G. 64